EXISTENCE OF HARMONIC FUNCTIONS VIA PERRON'S METHOD

Let $\Omega \subset \mathbb{R}^d$ be a bounded open set and let $\phi : \partial \Omega \to \mathbb{R}$ be a continuous function. In the next theorem we will use the Perron's method to prove the existence of a function $u : \overline{\Omega} \to \mathbb{R}$ solving the problem

$$\Delta u = 0 \quad \text{in} \quad \Omega , \qquad u = \phi \quad \text{on} \quad \partial \Omega$$

The argument is self-contained and only makes use of the Poisson's formula for balls in \mathbb{R}^d . An essential element of the proof are the boundary barriers from Lemma 2.

In what follows, given an open set Ω and a boundary datum ϕ as above, we define the following family of superharmonic functions

(1)
$$\mathcal{A} := \left\{ w : \overline{\Omega} \to \mathbb{R} : w \in C(\overline{\Omega}), \ w \ge \phi \text{ on } \partial\Omega, \ \Delta w \le 0 \text{ in } \Omega \right\},$$

where the inequality

$$\Delta w \leq 0$$
 in Ω

is intended in viscosity sense.

We recall that " $\Delta w \leq 0$ in Ω in viscosity sense" means that if a smooth function $P : \Omega \to \mathbb{R}$ touches w from below at some point $X \in \Omega$ (that is, $P \leq w$ in Ω and P(X) = w(X)), then $\Delta P(X) \leq 0$.

Teorema 1 (Existence of viscosity solutions via the Perron's method). Let Ω be a bounded open set admitting an exterior ball at every point on the boundary. Let $\phi : \partial \Omega \to \mathbb{R}$ be a continuous function and let \mathcal{A} be the class from (1). Then, the function

$$u:\overline{\Omega}\to\mathbb{R},$$

defined as

$$u(X) = \inf \left\{ w(X) : w \in \mathcal{A} \right\} \text{ for every } X \in \overline{\Omega},$$

has the following properties:

(a) $\Delta u = 0$ in Ω in viscosity sense;

(b) $u = \phi$ on $\partial \Omega$;

(c) u is continuous on $\overline{\Omega}$.

Proof. We proceed in two steps.

Step 1. Harmonicity of *u*: proof of (a).

We first notice that the functions w are bounded from below. Indeed, let $\underline{u}:\overline{\Omega}\to\mathbb{R}$ be a continuous function, which is smooth in Ω and such that

$$\underline{u} < \phi \quad \text{on} \quad \partial \Omega \quad \text{and} \quad \Delta \underline{u} > 0 \quad \text{in} \quad \Omega.$$

Then, for every $w \in \mathcal{A}$, we have that:

- w is superharmonic in viscosity sense;
- \underline{u} is subharmonic and smooth;
- $w > \underline{u}$ on $\partial \Omega$.

This implies that

$$\underline{u} \leq w$$
 in Ω .

We fix a ball

$$B_r \subset \Omega$$

We will show that u is harmonic in B_r . We fix a dense countable set

$$Q \subset \overline{\Omega}.$$

and we select a sequence of functions $w_n \in \mathcal{A}$ such that:

$$u(q) = \lim_{n \to +\infty} w_n(q)$$
 for every $q \in Q$.

Moreover, by replacing w_n with $w_1 \wedge w_2 \wedge \cdots \wedge w_n \in \mathcal{A}$, we can also suppose that:

the sequence of functions $w_n : \overline{\Omega} \to \mathbb{R}$ is decreasing.

For every n we consider the function

$$h_n:\overline{B}_r\to\mathbb{R}$$

which is continuous on \overline{B}_r , harmonic in B_r and is such that

 $h_n = w_n$ on ∂B_r .

We notice that by the maximum principle

$$\underline{u} \leq h_n \leq w_n$$
 in \overline{B}_r .

We next claim that the function

$$v_n:\overline{\Omega} \to \mathbb{R}$$
, $v_n(x) = \begin{cases} h_n(x) & \text{if } x \in \overline{B}_r, \\ w_n(x) & \text{if } x \in \overline{\Omega} \setminus B_r \end{cases}$

is in \mathcal{A} . Indeed, let P be a polynomial touching v_n from below at some point $X_0 \in \Omega$. We consider two cases.

- If $X_0 \in B_r$, then P touches from below the harmonic function h_n at X_0 and thus $\Delta P(X_0) \leq 0$.
- If $X_0 \in \Omega \setminus B_r$, then P touches from below also the function w_n at X_0 , and so we get again $\Delta P(X_0) \leq 0$.

This proves that $v_n \in \mathcal{A}$. We now notice that v_n is a monotone decreasing sequence of superharmonic functions such that

 $\underline{u} \leq v_n \leq w_1$ for every $n \geq 1$.

In particular, the pointwise limit

$$v(x) := \lim_{n \to +\infty} v_n(x),$$

exists and is finite for every $x \in \overline{\Omega}$. Now, by the monotone convergence theorem, we have that

$$0 = \lim_{n \to +\infty} \int_{B_r} h_n(x) \Delta \psi(x) \, dx = \int_{B_r} v(x) \Delta \psi(x) \, dx \quad \text{for every} \quad \psi \in C_c^{\infty}(B_r),$$

$$0 \ge \lim_{n \to +\infty} \int_{B_r} v_n(x) \Delta \psi(x) \, dx = \int_{B_r} v(x) \Delta \psi(x) \, dx \quad \text{for every} \quad \psi \in C_c^{\infty}(\Omega), \ \psi \ge 0$$

This implies that v is harmonic in B_r and superharmonic in Ω .

Notice that, since $v_n \in \mathcal{A}$ we have that

$$u \le v_n$$
 in $\overline{\Omega}$

for every $n \ge 1$, so that

$$u \leq v$$
 in $\overline{\Omega}$

On the other hand, by the choice of the dense set Q, we have

$$u(q) = v(q)$$
 for all $q \in Q$.

Suppose that in some point $X \in B_r$ we have

$$u(X) < v(X),$$

and take a ball $B_{\rho}(X) \subset B_r$. Since the functions v_n are harmonic and bounded in $B_{\rho}(X)$ we have that (up to a subsequence) v_n converges uniformly to v in $B_{\rho/2}(X)$. But then one can find $q \in Q \cap B_{\rho/2}(X)$ such that

u(q) < v(q),

which is a contradiction.

Step 2. u agrees with ϕ at the boundary: proof of (b).

Let $X_0 \in \partial \Omega$ be fixed. By the definition of the class \mathcal{A} we have that

$$\phi(X_0) \le w(X_0) \quad \text{for all} \quad w \in \mathcal{A},$$

By taking the infimum over all $w \in \mathcal{A}$, we get

$$\phi(X_0) = \inf_{w \in \mathcal{A}} w(X_0) \le u(X_0).$$

In order to show that

(2)
$$\phi(X_0) = u(X_0)$$

we argue by contradiction and we suppose that $u(X_{\infty}) - \phi(X_{\infty}) = \varepsilon > 0$. By Lemma 2 there is a competitor $\overline{w} \in \mathcal{A}$ such that

$$u(X_{\infty}) - \phi(X_{\infty}) \le \overline{w}(X_{\infty}) - \phi(X_{\infty}) < \varepsilon.$$

This is a contradiction and proves (2).

Step 3. Continuity of u up to the boundary: proof of (c).

Let $X_{\infty} \in \partial \Omega$ be fixed. It is sufficient to show that given a sequence $X_n \in \Omega$ converging to X_{∞} , we have

$$\lim_{n \to +\infty} u(X_n) = u(X_\infty).$$

We notice that, since all the functions $w \in \mathcal{A}$ are continuous on $\overline{\Omega}$ and $u = \inf_{\mathcal{A}} w$, it holds

$$\lim_{n \to +\infty} u(X_n) \le u(X_\infty)$$

Suppose by contradiction that

$$\lim_{n \to +\infty} u(X_n) < u(X_\infty).$$

By the previous point

$$\phi(X_{\infty}) = u(X_{\infty})$$

so we have

$$\lim_{n \to +\infty} u(X_n) < \phi(X_\infty).$$

Without loss of generality we can assume that there is a positive constant $\varepsilon > 0$ such that

$$\phi(X_{\infty}) = 0$$
 while $u(X_n) < -\varepsilon$ for every $n \ge 1$.

Let \underline{w} be a competitor constructed in Lemma 2. Then, for every $w \in \mathcal{A}$ we have

 $\underline{w}(X) \le w(X)$ for all $X \in \overline{\Omega}$.

As a consequence,

$$\underline{w}(X) \le u(X)$$
 for all $X \in \Omega$.

So, in particular,

$$-\varepsilon < \underline{w}(X_{\infty}) - \phi(X_{\infty}) = \underline{w}(X_{\infty}) = \lim_{n \to +\infty} \underline{w}(X_n) \le \lim_{n \to +\infty} u(X_n),$$

which is a contradiction. Thus, we have proved that

$$\lim_{n \to +\infty} u(X_n) = \phi(X_\infty) = u(X_\infty)$$

which concludes the proof of (c) and of the theorem.

Lemma 2 (Upper and lower barriers at boundary points admitting an exterior ball). Let Ω be a bounded open set in \mathbb{R}^d and let $\phi : \partial\Omega \to \mathbb{R}$ be a continuous function. Suppose that $X_0 \in \overline{\Omega}$ admits an exterior ball B at X_0 , that is, an open ball in \mathbb{R}^d such that $\overline{\Omega} \cap \overline{B} = \{X_0\}$. Then, for every $\varepsilon > 0$ there are continuous functions

$$\underline{u}:\overline{\Omega}\to\mathbb{R}\qquad and\qquad \overline{u}:\overline{\Omega}\to\mathbb{R}$$

such that:

(3)
$$\begin{cases} \Delta \underline{u} > 0 \quad in \quad \Omega; \\ \underline{u} \le \phi \quad on \quad \partial \Omega; \\ 0 \le \phi(X_0) - \underline{u}(X_0) \le \varepsilon; \end{cases} \quad and \quad \begin{cases} \Delta \overline{u} < 0 \quad in \quad \Omega; \\ \phi \le \overline{u} \quad on \quad \partial \Omega; \\ 0 \le \overline{u}(X_0) - \phi(X_0) \le \varepsilon. \end{cases}$$

Proof. Without loss of generality we can suppose that $\phi(X_0) = 0$. We proceed in several steps.

Step 1. Choice of an exterior tangent ball. Suppose that $B = B_R(Y_0)$ is the exterior ball at $X_0 \in \overline{\Omega}$, $\overline{\Omega} \cap \overline{B}_R(Y_0) = \{X_0\}.$

Let r > 0 be such that

$$|\phi(X)| \leq \varepsilon$$
 for every $X \in \partial \Omega \cap B_r(X_0)$.

We now set

$$\rho := \frac{1}{4} \min\{R, r\}$$

and we consider the ball $B_{\rho}(Z_0)$, where

$$Z_0 = X_0 + \rho \frac{Y_0 - X_0}{|Y_0 - X_0|}$$

which is an exterior ball at X_0 and is such that:

$$X_0 \in \partial B_\rho(Z_0)$$
, $B_\rho(Z_0) \subset \mathbb{R}^d \setminus \Omega$, $B_{2\rho}(Z_0) \subset B_r(X_0)$.

Step 2. A radially increasing superharmonic function in every dimension. Consider the function $g:(0,+\infty) \to (0,+\infty)$, $g(r) = 1 - r^{-d}$,

and let

$$G: \mathbb{R}^d \setminus \{0\} \to \mathbb{R}$$

be defined as follows:

$$G(X) = 1 - |X|^{-d} = g(|X|).$$

We notice that by construction

$$G = 0$$
 on ∂B_1

while we can compute the Laplacian of G in polar coordinates r = |X| and $\theta = X/|X|$ as

$$\Delta G(X) = \frac{1}{r^{d-1}} \partial_r \left[r^{d-1} \partial_r g(r) \right]$$
$$= -\frac{1}{r^{d-1}} \partial_r \left[r^{d-1} \partial_r \left[r^{-d} \right] \right]$$
$$= \frac{d}{r^{d-1}} \partial_r \left[r^{d-1} r^{-d-1} \right]$$
$$= \frac{d}{r^{d-1}} \partial_r \left[r^{-2} \right]$$
$$= \frac{-2d}{r^{d-4}},$$

so in any dimension $d \ge 2$ we have

$$\Delta G(X) < 0 \quad \text{for} \quad X \in \mathbb{R}^d \setminus \{0\}$$

Step 3. Construction of \underline{u} and \overline{u} . Let now C > 0 be a constant such that $C > \|\phi\|_{L^{\infty}(\partial\Omega)}$

and let

be defined as

$$\eta(X) := \begin{cases} \frac{C}{g(2)}g\left(\frac{|X-Z_0|}{\rho}\right) & \text{if } |X-Z_0| \ge \rho, \\ 0 & \text{if } |X-Z_0| \le \rho. \end{cases}$$

 $\eta: \mathbb{R}^d \to \mathbb{R}$

Then η has the following properties

$$\begin{cases} \Delta \eta < 0 & \text{in } \mathbb{R}^d \setminus \overline{B}_{\rho}(Z_0), \\ \eta \equiv 0 & \text{in } \overline{B}_{\rho}(Z_0), \\ \eta \ge C & \text{in } \mathbb{R}^d \setminus B_{2\rho}(Z_0) \end{cases}$$

By construction, we have that

$$-\varepsilon - \eta(X) \le \phi(X) \le \varepsilon + \eta(X)$$
 for every $X \in \partial \Omega$.

Thus, the functions

$$\overline{u}(X) := \varepsilon + \eta(X) \quad \text{and} \quad \underline{u}(X) := -\varepsilon - \eta(X)$$
 satisfy the conditions in (3).