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# OPTIMAL REGULARITY OF SOLUTIONS TO NO-SIGN OBSTACLE-TYPE PROBLEMS FOR THE SUB-LAPLACIAN 

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We establish the optimal $C_{H}^{1,1}$ interior regularity of solutions to

$$
\Delta_{H} u=f \chi_{\{u \neq 0\}},
$$

where $\Delta_{H}$ denotes the sub-Laplacian operator in a stratified group. We assume the weakest regularity condition on $f$, namely the group convolution $f * \Gamma$ is $C_{H}^{1,1}$, where $\Gamma$ is the fundamental solution of $\Delta_{H}$. The $C_{H}^{1,1}$ regularity is understood in the sense of Folland and Stein. In the classical Euclidean setting, the first seeds of the above problem were already present in the 1991 paper of Sakai and are also related to quadrature domains. As a special instance of our results, when $u$ is nonnegative and satisfies the above equation, we recover the $C_{H}^{1,1}$ regularity of solutions to the obstacle problem in stratified groups, which was previously established by Danielli, Garofalo and Salsa. Our regularity result is sharp: it can be seen as the subelliptic counterpart of the $C^{1,1}$ regularity result due to Andersson, Lindgren and Shahgholian.

## 1. Introduction

The main question we consider in this paper is the optimal interior regularity of distributional solutions to the no-sign obstacle-type problem

$$
\begin{equation*}
\Delta_{H} u=f \chi_{\{u \neq 0\}} \tag{1-1}
\end{equation*}
$$

on some domain of a stratified group $\mathbb{G}$; see Section 2 for notation and terminology. In the Euclidean setting, the obstacle problem is among the most-studied topics in the field of free boundary problems; see for instance [Rodrigues 1987; Friedman 1982; Petrosyan et al. 2012]. It asks which properties can be deduced about a function with given boundary values that minimizes the Dirichlet energy, under the constraint of lying above a given function. This is the classical obstacle problem, which can be studied through the theory of variational inequalities, using the Dirichlet energy; see for instance [Kinderlehrer and Stampacchia 1980; Frehse 1972]. The variational approach, after subtracting the obstacle from the solution, leads to the PDE formulation of the problem

$$
\left\{\begin{array}{cl}
\Delta u=f \chi_{\{u>0\}} & \text { in } B_{1},  \tag{1-2}\\
u \geq 0 & \text { in } B_{1}, \\
u=g & \text { on } \partial B_{1},
\end{array}\right.
$$

[^0]where $B_{1}$ denotes the metric unit ball with respect to the Carnot-Carathéodory distance (Definition 2.1). Our problem is a nonvariational counterpart of (1-2), that is,
\[

\left\{$$
\begin{array}{cl}
\Delta u=f \chi_{\{u \neq 0\}} & \text { in } B_{1},  \tag{1-3}\\
u=g & \text { on } \partial B_{1} .
\end{array}
$$\right.
\]

We point out that (1-3) - which is called a no-sign obstacle-type problem - naturally appears also when considering the so-called quadrature domains [Sakai 1991; Gustafsson and Shapiro 2005].

Two important questions about this problem concern the regularity of solutions to (1-3) and the regularity of the free boundary. In Euclidean space, the analysis of both questions is essentially complete [Sakai 1991; Caffarelli et al. 2000; Petrosyan and Shahgholian 2007; Andersson et al. 2013]. In particular, in relation to the regularity of solutions, [Andersson et al. 2013] shows that $u$ has the optimal $C^{1,1}$ regularity if the linear problem $\Delta v=f$ has a $C^{1,1}$ solution. This is the minimal regularity assumption on $f$ in order to establish the $C^{1,1}$ regularity of solutions.

The main result of this paper is the sharp regularity of solutions to (1-1) also in the subelliptic setting of stratified groups.

Theorem $1.1\left(C_{H}^{1,1}\right.$ regularity). Let $u \in L^{\infty}\left(B_{1}\right)$ be a distributional solution to (1-1) in the unit ball $B_{1}$. Let $f: B_{1} \rightarrow \mathbb{R}$ be locally summable such that $f * \Gamma \in C_{H}^{1,1}\left(B_{1}\right)$. Then there exists a universal constant $C>0$ such that, after a modification on a negligible set, we have $u \in C_{H}^{1,1}\left(B_{1 / 4}\right)$ and

$$
\begin{equation*}
\left\|D_{h}^{2} u\right\|_{L^{\infty}\left(B_{1 / 4}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) . \tag{1-4}
\end{equation*}
$$

In our setting, the natural counterpart of the Euclidean $C^{1,1}$ regularity is the $C_{H}^{1,1}$ regularity, where the horizontal derivatives are required to be Lipschitz continuous (Definition 2.2). The function $\Gamma$ denotes the fundamental solution of $\Delta_{H}$ (Definition 2.3). For further notation and terminology, we direct the reader to Section 2.

We wish to emphasize that $u$ satisfies (1-1) also in the strong sense. Indeed, the distributional equality $\Delta_{H}(f * \Gamma)=-f$, joined with the assumed $C_{H}^{1,1}$ regularity of $f * \Gamma$, shows that $f \in L^{\infty}\left(B_{1}\right)$. Therefore $f \chi_{\{u \neq 0\}} \in L^{\infty}\left(B_{1}\right)$ and by the regularity result [Folland 1975, Theorem 6.1] we get $u \in W_{H, \operatorname{loc}}^{2, p}\left(B_{1}\right)$ for every $1 \leq p<\infty$. The $C_{H}^{1,1}$ regularity of solutions to the obstacle problem in stratified groups was obtained in [Danielli et al. 2003], using the variational formulation of the problem. The regularity of the free boundary was subsequently established in step-two groups [Danielli et al. 2007]. Further results in this area have been obtained for Kolmogorov operators and parabolic nondivergence form operators of Hörmander type [Di Francesco et al. 2008; Frentz et al. 2010; 2012; Frentz 2013]. The no-sign obstacle-type problem in terms of (1-1) does not seem to have been considered before in the subelliptic setting.

Our arguments are remarkably different from the ones used for the obstacle problem. For instance, in this problem without a forcing term the solution is automatically superharmonic with respect to $\Delta_{H}$, while in our setting we have no such sign condition that would yield a superharmonic solution. We initiate our analysis observing that second-order horizontal derivatives of solutions to (1-1) satisfy certain BMO estimates, which were established in [Bramanti and Brandolini 2005; Bramanti and Fanciullo 2013]. The subsequent step is to construct suitable approximating polynomials, starting from the second-order
horizontal derivatives of the solution. Indeed these polynomials yield a subquadratic growth estimate (4-10) at small scales. We point out that this estimate is valid for any bounded and $W^{2, p}$ regular function, with bounded sub-Laplacian, so it might be of independent interest. As a consequence, we perform a suitable rescaling of the equation and then infer the crucial decay estimate of the measure of the coincidence set (Proposition 4.6), when the horizontal Hessian of the approximating polynomial is sufficiently large. More details on this procedure can be found at the beginning of Section 4.

Although our ideas mainly follow the path set up by [Andersson et al. 2013; Figalli and Shahgholian 2014], there are several difficulties related to the subelliptic setting. The basic one is concerned with the fact that the sub-Laplacian $\Delta_{H}$ is degenerate elliptic. In addition, since the operator $\Delta_{H}$ is written in terms of Hörmander vector fields, we can only consider the horizontal Hessian (2-5) of the solution, which is a nonsymmetric matrix. Then the construction of the approximating polynomials starting from the average of the second-order noncommuting derivatives $X_{i} X_{j} u$ becomes more delicate and requires some preliminary algebraic work; see Section 3. Notwithstanding the technical complications, the proof has become more streamlined: we can stay clear of the projection operator used in [Andersson et al. 2013], and this simplifies several technical points. A suitable quantitative decay estimate of the zero-level set (4-14) can be obtained also in our setting. Finally, we adapt the polynomial iteration technique of [Caffarelli 1989] to find explicit estimates of the second-order horizontal derivatives; see (1-4).

We finish the introduction by giving an overview of the paper. In Section 2 we introduce some basic notions on stratified groups and the related function spaces. In Section 3 we construct suitable second-order homogeneous polynomials (Definition 3.2), which have an assigned horizontal Hessian (Corollary 3.3). Then some important $W^{2, p}$ and BMO estimates are presented. Finally, we provide the crucial scaling estimates of Lemma 3.8. In Section 4 we prove a subquadratic growth estimate of the difference between a solution and its approximating polynomial. Then we apply the subquadratic growth estimate to get a suitable decay of the measure of the zero-level set. Finally, we establish the $C_{H}^{1,1}$ regularity in quantitative terms, according to (1-4).

## 2. Basic facts and notation

A stratified group is a simply connected, real nilpotent Lie group $\mathbb{G}$ whose Lie algebra $\mathcal{G}$ has a special stratification. We denote by $V_{i}$ the subspaces of $\mathcal{G}$ having the properties

$$
\mathcal{G}=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\iota} \quad \text { and } \quad\left[V_{1}, V_{j}\right]=V_{j+1}
$$

for $j=1, \ldots, \iota$ and $V_{\iota+1}=0$. Let us denote by $n$ the topological dimension of $\mathbb{G}$ and by $m$ the dimension of $V_{1}$. We choose a graded basis $X_{1}, X_{2}, \ldots, X_{n}$ of $\mathcal{G}$ that is characterized by the property that

$$
X_{m_{j-1}+1}, \ldots, X_{m_{j}}
$$

is a basis of $V_{j}$ for all $j=1, \ldots, \iota$, where we have set $m_{0}=0, m_{1}=m$ and $m_{j}=\sum_{i=1}^{j} \operatorname{dim} V_{i}$. We notice that $m_{\iota}=n$ and with these definitions, if $m_{k-1}<j \leq m_{k}$, then $k \in \mathbb{N}$ is uniquely determined and we define the positive integer

$$
\begin{equation*}
d_{j}:=k \tag{2-1}
\end{equation*}
$$

Through the exponential mapping of $\mathbb{G}$, one can construct a diffeomorphism from $\mathbb{R}^{n}$ to $\mathbb{G}$. Hence we have defined a graded basis $e_{1}, e_{2}, \ldots, e_{n}$ of $\mathbb{R}^{n}$ and graded coordinates $x_{1}, x_{2}, \ldots, x_{n}$ that define the point $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ of $\mathbb{G}$. This allows us to identify $\mathbb{G}$ with $\mathbb{R}^{n}$, as will be understood in the sequel.

In addition, one may also verify that the Lebesgue measure of $\mathbb{R}^{n}$ through the graded coordinates yields the Haar measure of the group $\mathbb{G}$. The notation $|A|$ denotes the Lebesgue measure of a measurable set $A \subset \mathbb{R}^{n}$.

The diffeomorphism associated to graded coordinates has also the property that the group operation on $\mathbb{G}$, when read in $\mathbb{R}^{n}$, is given by a special polynomial group operation

$$
\begin{equation*}
x y=x+y+\operatorname{BCH}(x, y) \tag{2-2}
\end{equation*}
$$

where the precise form of the vector polynomial $\mathrm{BCH}: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ is given by the important Baker-Campbell-Hausdorff formula, abbreviated as the BCH formula; see for instance [Varadarajan 1974]. The degree of $x_{j}$ is the integer $d_{j}$ defined in (2-1) and we define intrinsic dilations as

$$
\delta_{r} x=\left(r x_{1}, \ldots, r x_{m}, r^{2} x_{m+1}, \ldots, r^{2} x_{m_{2}}, \ldots, r^{\iota} x_{m_{\iota-1}+1}, \ldots, r^{\iota} x_{n}\right)=\sum_{j=1}^{n} r^{d_{j}} x_{j} e_{j}
$$

for any $r>0$. The notion of degree fits the algebraic properties of dilations, since

$$
\begin{equation*}
\delta_{r}(x y)=\left(\delta_{r} x\right)\left(\delta_{r} y\right) \tag{2-3}
\end{equation*}
$$

for all $x, y \in \mathbb{R}^{n}$. By the form of dilations, for every measurable set $A \subset \mathbb{R}^{n}$ we have

$$
\left|\delta_{r}(A)\right|=r^{Q}|A|
$$

for all $r>0$, where $Q=\sum_{j=1}^{n} d_{j}$ can be proved to be the Hausdorff dimension of $\mathbb{G}$.
The metric structure of $\mathbb{R}^{n}$ is given by a control distance. We say that $\gamma:[0, T] \rightarrow \mathbb{R}^{n}$, an absolutely continuous curve, is admissible if, for a.e. $t \in[0,1]$,

$$
\dot{\gamma}(t)=\sum_{i=1}^{m} b_{i}(t) X_{i}(\gamma(t))
$$

and $\sum_{i=1}^{m} b_{i}(t)^{2} \leq 1$. We denote by $\mathcal{H}(x, y)$ the family of all admissible curves whose image contains $x, y$. By Chow's theorem, $\mathcal{H}(x, y)$ is nonempty for every $x, y \in \mathbb{R}^{n}$; hence the "control distance"

$$
d(x, y)=\inf \left\{T>0 \mid \gamma:[0, T] \rightarrow \mathbb{R}^{n}, \gamma \in \mathcal{H}(x, y)\right\}
$$

is well-defined. It is also possible to check that $d$ is actually a distance, corresponding to the well-known Carnot-Carathéodory distance.

Since left translations preserve the "horizontal velocity", $d$ is also left-invariant, namely $d(x, y)=$ $d(z x, z y)$ for all $x, y, z \in \mathbb{R}^{n}$. Furthermore, dilations are Lie group homomorphisms; hence the CarnotCarathéodory distance is homogeneous in the sense that $d\left(\delta_{r} x, \delta_{r} y\right)=r d(x, y)$ for every $x, y \in \mathbb{R}^{n}$ and $r>0$.

Definition 2.1 (metric balls). For $x \in \mathbb{R}^{n}$ and $r>0$, we denote by $B_{r}(x)$ the open ball with center $x$ and radius $r>0$ with respect to $d$. Precisely, this is the set $\left\{y \in \mathbb{R}^{n}: d(x, y)<r\right\}$. When $x=0$, we use the notation $B_{r}:=B_{r}(0)$.

From the properties of $d$ and $\delta_{r}$, it is easy to observe that

$$
B_{r}(x)=x \delta_{r}\left(B_{1}\right)
$$

Dilations also allow us to introduce a natural notion of homogeneity, so we may say that a polynomial $p: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is $k$-homogeneous if

$$
p\left(\delta_{r} x\right)=r^{k} p(x) \quad \text { for all } x \in \mathbb{R}^{n} \text { and } r>0 .
$$

The number $k \in \mathbb{N}$ is the degree of $p$. Moreover, any vector field $X_{j}$ of the fixed graded basis can be identified with a first-order differential operator of the form

$$
\begin{equation*}
X_{j}=\partial_{x_{j}}+\sum_{i=m_{d_{j}}+1}^{n} a_{j i} \partial_{x_{i}} \tag{2-4}
\end{equation*}
$$

for every $j=1, \ldots, n$. The functions $a_{j i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ are homogeneous polynomials of degree $d_{i}-d_{j} \geq 1$ and in particular $X_{j}(0)=e_{j}$ for all $j=1, \ldots, n$. In the sequel $\Omega$ will be understood as an open bounded subset of $\mathbb{G}$ that can be also identified with an open subset of $\mathbb{R}^{n}$, if not otherwise stated.

Given a function $u: \Omega \rightarrow \mathbb{R}$ and considering the vector fields $X_{j}$ as differential operators, we may introduce the horizontal gradient and the horizontal Hessian

$$
\nabla_{h} u=\left(X_{1} u, \ldots, X_{m} u\right) \quad \text { and } \quad D_{h}^{2} u=\left(\begin{array}{cccc}
X_{1} X_{1} u & X_{1} X_{2} u & \cdots & X_{1} X_{m} u  \tag{2-5}\\
X_{2} X_{1} u & X_{2} X_{2} u & \cdots & X_{2} X_{m} u \\
\vdots & \vdots & \ddots & \vdots \\
X_{m} X_{1} u & \cdots & \cdots & X_{m} X_{m} u
\end{array}\right)
$$

respectively, whenever they are pointwise defined. More generally, we can define higher-order differential operators considering for $I=\left(i_{1}, \ldots, i_{n}\right) \in \mathbb{N}^{n}$ the function

$$
X^{I} u:=X_{1}^{i_{n}} \cdots X_{n}^{i_{1}} u
$$

Definition 2.2 (Folland-Stein spaces). Let $\Omega \subset \mathbb{R}^{n}$ be an open set. We denote by $C_{H}^{1}(\Omega)$ the space of all functions $u: \Omega \rightarrow \mathbb{R}$ such that the horizontal derivatives $X_{j} u$ exist on $\Omega$ for all $j=1, \ldots, m$ and are continuous. If $0<\alpha \leq 1$, then $C_{H}^{1, \alpha}(\Omega)$ is the space of functions $u$ in $C_{H}^{1}(\Omega)$ such that there exists $C>0$ with the property that

$$
\left|X_{j} f(x)-X_{j} f(y)\right| \leq C d(x, y)^{\alpha}
$$

for every $x, y \in \Omega$ and $j=1, \ldots, m$.
Notice that $D_{h}^{2} u$ is not symmetric, since the vector fields $X_{j}$ do not commute in general. We say that $X_{j} u$ are the horizontal derivatives and $X_{i} X_{j} u$ are the second-order horizontal derivatives. The symmetrized horizontal Hessian is defined as

$$
D_{h}^{2, s} u=\frac{1}{2}\left(D_{h}^{2} u+D_{h}^{2} u^{T}\right)
$$

The sub-Laplacian is defined as

$$
\Delta_{H} u=\sum_{j=1}^{m} X_{j}^{2} u
$$

Functions satisfying $\Delta_{H} u=0$ are called as usual harmonic functions.
Definition 2.3 (fundamental solution). We say that $\Gamma \in C^{\infty}(\mathbb{G} \backslash\{0\})$ is a fundamental solution for $\Delta_{H}$ if it is locally summable, it vanishes at infinity and satisfies $\Delta_{H} \Gamma=-\delta_{0}$, where $\delta_{0}$ denotes the Dirac distribution centered at the origin.

The fundamental solution $\Gamma$ defines a gauge $d_{G}=\Gamma^{1 /(2-Q)}$, which is 1-homogeneous with respect to dilations and continuous on $\mathbb{R}^{n}$. We can readily check that there exists a constant $c_{0}>1$ such that

$$
\begin{equation*}
c_{0}^{-1} d_{G}(x) \leq d(x, 0) \leq c_{0} d_{G}(x) \tag{2-6}
\end{equation*}
$$

for all $x \in \mathbb{R}^{n}$. Defining $d_{G}(x, y):=d_{G}\left(x^{-1} y\right)$ we also introduce the gauge ball

$$
\begin{equation*}
B_{r}^{G}(x)=\left\{y \in \mathbb{R}^{n}: d_{G}(x, y)<r\right\} . \tag{2-7}
\end{equation*}
$$

The previous estimates clearly imply that

$$
\begin{equation*}
B_{r}^{G}(x) \subset B_{c_{0} r}(x) \tag{2-8}
\end{equation*}
$$

for every $r>0$ and $x \in \mathbb{R}^{n}$.
Proposition 2.4. Let $\Omega \subset \mathbb{R}^{n}$ be an open set and let $\vartheta$ be harmonic in $\Omega$. We consider an open set $\Omega^{\prime} \subset \Omega$ and $h>0$ such that

$$
\operatorname{dist}_{G}\left(\Omega^{\prime}, \Omega^{c}\right):=\inf \left\{d_{G}(x, y): x \in \Omega^{\prime}, y \in \Omega^{c}\right\}>h
$$

Then $\vartheta \in C^{\infty}(\Omega)$ and for every multiindex I there exists a constant $C_{I, h}>0$ such that

$$
\begin{equation*}
\left|X^{I} \vartheta(x)\right| \leq C_{I, h}\|\vartheta\|_{L^{1}(\Omega)} . \tag{2-9}
\end{equation*}
$$

Proof. We consider the function $\phi$ defined in [Bonfiglioli et al. 2007, (5.50e)], where we choose $\varphi$ appearing in the definition of $\phi$ such that $\varphi \in C_{c}^{\infty}(] 3^{-1}, 1[), \varphi \geq 0$ and $\int_{\mathbb{R}} \varphi(t) d t=1$. It follows that $\phi$ is smooth and bounded on $\mathbb{R}^{n}$, along with all of its derivatives, and it is compactly supported in $B_{1}^{G}$; see the definition (2-7). We also consider $\phi_{r}(z):=r^{-Q} \phi\left(\delta_{1 / r} z\right)$, which is compactly supported on $B_{r}^{G}$. We finally set $\hat{\phi}_{r}(z):=\phi_{r}\left(z^{-1}\right)$ for all $z \in \mathbb{R}^{n}$ and $r>0$. Thus, using [Bonfiglioli et al. 2007, (5.50a), (5.50d)], for every $x \in B_{\lambda}$, we get

$$
\vartheta(x)=\int_{B_{h}^{G}(x)} \phi_{h}\left(x^{-1} y\right) \vartheta(y) d y=\int_{\Omega} \hat{\phi}_{h}\left(y^{-1} x\right) \vartheta(y) d y .
$$

We can differentiate the last integral an arbitrary number of times, due to the smoothness of $\hat{\phi}_{h}$, getting the smoothness of $\vartheta$ and the estimate

$$
\left|X^{I} \vartheta(x)\right|=\left|\int_{\Omega} X^{I} \hat{\phi}_{h}\left(y^{-1} x\right) \vartheta(y) d y\right| \leq\left\|X^{I} \hat{\phi}_{h}\right\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\|\vartheta\|_{L^{1}(\Omega)}
$$

for all $x \in \Omega^{\prime}$.

In our setting, we need the notion of Sobolev function adapted to the horizontal vector fields $X_{1}, \ldots, X_{m}$; see [Folland 1975]. The horizontal Sobolev space $W_{H}^{k, p}(\Omega)$ consists of those functions $u \in L^{p}(\Omega)$ for which, for all $j_{s} \in\{1, \ldots, m\}$ and $s \in\{1, \ldots, k\}$, there exists a function $v_{j_{1}, \ldots, j_{k}} \in L^{p}(\Omega)$ such that

$$
\int_{\Omega} u(y)\left(X_{j_{1}} \cdots X_{j_{k}} \phi\right)(y) d y=(-1)^{k} \int_{\Omega} v_{j_{1}, \ldots, j_{k}}(y) \phi(y) d y
$$

for any function $\phi \in C_{c}^{\infty}(\Omega)$. Also in the more general setting of Hörmander vector fields some Sobolev embedding theorems hold; see [Garofalo and Nhieu 1996, Theorem 1.11 and (3.19)] or [Lu 1996, Theorem 1.1]. The next theorem specializes these embedding results for stratified groups.

Theorem 2.5. Let $p>Q$, where $Q$ is the Hausdorff dimension of $\mathbb{G}$ and let $\Omega^{\prime} \Subset \Omega$ be any open and relatively compact subset. Then there exists $C>0$, depending on $\Omega^{\prime}$, such that for every $u \in W_{H}^{1, p}(\Omega)$, up to a modification of $u$ on a negligible set, we have

$$
|u(x)-u(y)| \leq C\|u\|_{W_{H}^{1, p}(\Omega)} d(x, y)^{1-Q / p}
$$

for every $x, y \in \Omega^{\prime}$.
The (1,1)-Poincaré inequality

$$
\begin{equation*}
\int_{B_{r}(x)}\left|u(y)-u_{B_{r}(x)}\right| d y \leq c r \int_{B_{r}(x)}\left|\nabla_{h} u(y)\right| d y \tag{2-10}
\end{equation*}
$$

holds for every $u \in C^{1}\left(\overline{B_{r}(x)}\right)$. This inequality follows from [Jerison 1986]; see also [Lanconelli and Morbidelli 2000].

For any measurable function $u$ that is summable on a measurable set $A \subset \Omega$, we use the notation

$$
u_{A}:=f_{A} u(y) d y=\frac{1}{|A|} \int_{A} u(y) d y
$$

Definition 2.6. For $u \in L^{1}(\Omega)$, we define the BMO seminorms

$$
\begin{aligned}
{[u]_{\mathrm{BMO}(\Omega)} } & :=\sup _{x_{0} \in \Omega, r>0} f_{B_{r}\left(x_{0}\right) \cap \Omega}\left|u(y)-u_{B_{r}\left(x_{0}\right)}\right| d y, \\
{[u]_{\mathrm{BMO}_{\mathrm{loc}}(\Omega)} } & :=\sup _{B_{r}\left(x_{0}\right) \subset \Omega} f_{B_{r}\left(x_{0}\right)}\left|u(y)-u_{B_{r}\left(x_{0}\right)}\right| d y
\end{aligned}
$$

and for $1 \leq p<\infty$ the corresponding $\mathrm{BMO}^{p}$ norms

$$
\begin{aligned}
\|u\|_{\mathrm{BMO}^{p}(\Omega)} & :=[u]_{\mathrm{BMO}(\Omega)}+\|u\|_{L^{p}(\Omega)}, \\
\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}(\Omega)} & :=[u]_{\mathrm{BMO}_{\mathrm{loc}}(\Omega)}+\|u\|_{L^{p}(\Omega)} .
\end{aligned}
$$

The spaces $\mathrm{BMO}^{p}(\Omega)$ and $\mathrm{BMO}_{\mathrm{loc}}^{p}(\Omega)$ consist of all $L^{p}$ functions on $\Omega$ with finite $\mathrm{BMO}^{p}$ and $\mathrm{BMO}_{\mathrm{loc}}^{p}$ norm, respectively. See [Bramanti and Fanciullo 2013] for more information on BMO functions in the subelliptic setting.

## 3. Preparatory results

We first study the relationship between the coefficients of a 2-homogeneous polynomial and its secondorder horizontal derivatives. Then, by some $W_{H}^{2, p}$ and BMO estimates, we show how to control the horizontal Hessian of a Sobolev function by the horizontal Hessian of a suitable 2-homogeneous harmonic polynomial (Corollary 3.7). Finally, in Lemma 3.8 we establish a quantitative control on the growth of these polynomials at small scales.

We need first to find 2-homogeneous polynomials with assigned second-order horizontal derivatives. To do this, we first observe that (2-2), combined with (2-3) and (2-1), setting

$$
\mathrm{BCH}(x, y)=\sum_{j=m+1}^{n} q_{j}(x, y) e_{j}
$$

implies that any $q_{j}$ is a homogeneous polynomial of degree $d_{j}$. Due to the BCH formula, one can also prove that $q_{l}$ is a 2 -homogeneous polynomial with respect to the variables $x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}$ for all $l=m+1, \ldots, m_{2}$ and

$$
q_{l}(x, y)=-q_{l}(y, x) .
$$

From the definition of left-invariant vector field, we get

$$
a_{j l}(x)=\frac{\partial q_{l}}{\partial y_{j}}(x, 0)
$$

for all $j=1, \ldots, m$ and $l=m+1, \ldots, m_{2}$. As a consequence, we get

$$
\begin{equation*}
\frac{\partial a_{j l}}{\partial x_{i}}=\frac{\partial^{2} q_{l}}{\partial x_{i} \partial y_{j}}=-\frac{\partial^{2} q_{l}}{\partial x_{j} \partial y_{i}}=-\frac{\partial a_{i l}}{\partial x_{j}} \tag{3-1}
\end{equation*}
$$

for all $i, j=1, \ldots, m$ and $l=m+1, \ldots, m_{2}$. Notice that the partial derivatives in the previous equalities are all constant functions. Equalities (3-1) will be important in the proof of Proposition 3.1.

Every polynomial on $\mathbb{R}^{n}$, thought of as equipped with dilations $\delta_{r}$, is the sum of homogeneous polynomials and the maximum among these degrees is the degree of the polynomial. Polynomials of degree 1 are just affine functions $\ell$ of the form

$$
\ell(x)=\alpha+\langle\beta, \pi(x)\rangle,
$$

with $\beta=\left(\beta_{1}, \beta_{2}, \ldots, \beta_{m}\right) \in \mathbb{R}^{n}, \alpha \in \mathbb{R}$ and we have used the projection

$$
\begin{equation*}
\pi: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}, \quad \pi(x)=\left(x_{1}, \ldots, x_{m}\right) \tag{3-2}
\end{equation*}
$$

A homogeneous polynomial of degree 2 must have the form

$$
\begin{equation*}
p(x)=\frac{1}{2} \sum_{i, j=1}^{m} c_{i j} x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} c_{l} x_{l} \tag{3-3}
\end{equation*}
$$

where $c_{i j}$ and $c_{l}$ are real numbers, with $c_{i j}=c_{j i}$ for all $i, j=1, \ldots, m$.

Proposition 3.1. Let $p: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a 2-homogeneous polynomial of the form (3-3) and let us consider the basis $X_{m+1}, \ldots, X_{m_{2}}$ of $V_{2}$. Then we have

$$
c_{i j}=\frac{1}{2}\left(X_{i} X_{j} p+X_{j} X_{i} p\right) \quad \text { and } \quad X_{i} X_{j} p=c_{i j}+\sum_{l=m+1}^{m_{2}} \gamma_{i j}^{l} c_{l}
$$

where $\gamma_{i j}^{l}$ are proportional to the structure constants of the Lie algebra, namely

$$
\begin{equation*}
\left[X_{i}, X_{j}\right]=\sum_{l=m+1}^{m_{2}} 2 \gamma_{i j}^{l} X_{l} \tag{3-4}
\end{equation*}
$$

and $i, j=1, \ldots, m$.
Proof. We first define the symmetrized second-order derivative

$$
\left(X_{i} X_{j}\right)^{s}:=\frac{1}{2}\left(X_{i} X_{j}+X_{j} X_{i}\right)
$$

so that we can write

$$
\begin{equation*}
X_{i} X_{j}=\left(X_{i} X_{j}\right)^{s}+\frac{1}{2}\left[X_{i}, X_{j}\right] \tag{3-5}
\end{equation*}
$$

for every $i, j=1, \ldots, m$. Since $X_{i} X_{j}$ and $X_{l}$ are homogeneous differential operators of order -2 and $p$ has degree 2, the horizontal derivatives $X_{i} X_{j} p$ and $X_{l} p$ are constants.

By (3-3) and (2-4), we get

$$
X_{j} p=\sum_{i=1}^{m} c_{j i} x_{i}+\sum_{i=m+1}^{n} a_{j i} \partial_{x_{i}}\left(\sum_{l=m+1}^{m_{2}} c_{l} x_{l}\right)=\sum_{i=1}^{m} c_{j i} x_{i}+\sum_{i=m+1}^{m_{2}} a_{j i} c_{i}
$$

for $j=1, \ldots, m$. As a consequence, taking into account the form of the vector fields (2-4) and of the polynomial (3-3), for any $i, j=1, \ldots, m$ and $l=m+1, \ldots, m_{2}$, we get

$$
\begin{equation*}
X_{i} X_{j} p=c_{i j}+\sum_{s=m+1}^{m_{2}} \partial_{x_{i}} a_{j s} c_{s} \tag{3-6}
\end{equation*}
$$

To establish the previous equality, we have also observed that the polynomials $a_{j i}$ are homogeneous of degree $d_{i}-d_{j}=1$; therefore they are only dependent on their first $m$ variables. In particular, all the partial derivatives $\partial_{x_{l}} a_{j i}$ are vanishing whenever the integers $l$ and $i$ take values from $m+1$ to $m_{2}$ and $j=1, \ldots, m$. Combining (3-6) and (3-1), we also obtain the first of the equalities

$$
X_{i} X_{j} p+X_{j} X_{i} p=2 c_{i j} \quad \text { and } \quad X_{l} p=c_{l}
$$

with $1 \leq i, j \leq m$ and $m+1 \leq l \leq m_{2}$. The latter directly follows from the form of (3-3). In conclusion, by virtue of (3-4), (3-5) and (3-6), we have obtained

$$
X_{i} X_{j} p=\left(X_{i} X_{j}\right)^{s} p+\sum_{l=m+1}^{m_{2}} \gamma_{i j}^{l} X_{l} p=c_{i j}+\sum_{l=m+1}^{m_{2}} \gamma_{i j}^{l} c_{l},
$$

concluding the proof.

Definition 3.2. For $B_{r}\left(x_{0}\right) \Subset \Omega$ and $u \in W_{H, \mathrm{loc}}^{2,1}(\Omega)$, we define the matrix

$$
P_{r}^{x_{0}}:=\left(D_{h}^{2} u\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)} I_{m} \in \mathbb{R}^{n \times n}
$$

where $I_{m}$ stands for the identity matrix and the $(i, j)$ entry of $\left(D_{h}^{2} u\right)_{B_{r}\left(x_{0}\right)}$ is the average $\left(X_{i} X_{j} u\right)_{B_{r}\left(x_{0}\right)}$. Associated to the ball $B_{r}\left(x_{0}\right)$, we also define the coefficients

$$
c_{i j}^{r, x_{0}}:=\left(\frac{X_{i} X_{j} u+X_{j} X_{i} u}{2}\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m} \delta_{i j}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)} \quad \text { and } \quad c_{l}^{r, x_{0}}=\left(X_{l} u\right)_{B_{r}\left(x_{0}\right)} .
$$

These numbers define the 2-homogeneous polynomial

$$
p_{r}^{x_{0}}(x)=\frac{1}{2} \sum_{i, j=1}^{m} c_{i j}^{r, x_{0}} x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} c_{l}^{r, x_{0}} x_{l}
$$

which we will show to be related to $P_{r}^{x_{0}}$.
Corollary 3.3. In the assumptions of Definition 3.2, the 2-homogeneous polynomial $p_{r}^{x_{0}}$ is harmonic and

$$
D_{h}^{2} p_{r}^{x_{0}}=P_{r}^{x_{0}}
$$

Proof. By Proposition 3.1, we have

$$
X_{i} X_{j} p_{r}^{x_{0}}=c_{i j}^{r, x_{0}}+\sum_{l=m+1}^{m_{2}} \gamma_{i j}^{l} c_{l}^{r, x_{0}}
$$

where $\gamma_{i i}^{l}=0$ and by the definition of $c_{i i}^{r, x_{0}}$ we get

$$
\Delta_{H} p_{r}^{x_{0}}=\sum_{i=1}^{m} c_{i i}^{r, x_{0}}=\sum_{i=1}^{m}\left[\left(X_{i} X_{i} u\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)}\right]=0 .
$$

Finally, we observe that

$$
\begin{aligned}
X_{i} X_{j} p_{r}^{x_{0}} & =\left(\frac{X_{i} X_{j} u+X_{j} X_{i} u}{2}\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m} \delta_{i j}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)}+\left(\sum_{l=m+1}^{m_{2}} \gamma_{i j}^{l} X_{l} u\right)_{B_{r}\left(x_{0}\right)} \\
& =\left(\frac{X_{i} X_{j} u+X_{j} X_{i} u}{2}\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m} \delta_{i j}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)}+\left(\frac{\left[X_{i}, X_{j}\right] u}{2}\right)_{B_{r}\left(x_{0}\right)} \\
& =\left(X_{i} X_{j} u\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m} \delta_{i j}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)}
\end{aligned}
$$

having taken into account that $\left[X_{i}, X_{j}\right]=\sum_{l=m+1}^{m_{2}} 2 \gamma_{i j}^{l} X_{l}$ from Proposition 3.1.
The following $W_{H}^{2, p}$ estimates go back to [Folland 1975]; see also [Bramanti and Brandolini 2000] for more general hypoelliptic operators.
Theorem 3.4 [Bramanti and Brandolini 2000]. Let $1<p<\infty$ and consider two bounded open sets $\Omega$ and $\Omega^{\prime}$ with $\Omega^{\prime} \Subset \Omega$. Then there exists a constant $C>0$ such that, for every $u \in W_{H}^{2, p}(\Omega)$,

$$
\begin{equation*}
\left\|X_{i} X_{j} u\right\|_{L^{p}\left(\Omega^{\prime}\right)} \leq C\left(\left\|\Delta_{H} u\right\|_{L^{p}(\Omega)}+\|u\|_{L^{p}(\Omega)}\right) \tag{3-7}
\end{equation*}
$$

It is well known that even for the classical Laplacian operator $\Delta$, it is not true that $L^{\infty}$ bounds on $\Delta u$ imply the boundedness of second-order horizontal derivatives. Indeed our starting point is that bounds on the BMO norm of the sub-Laplacian $\Delta_{H} u$ show that the BMO norm of the horizontal Hessian of $u$ is bounded, according to the results of [Bramanti and Brandolini 2005; Bramanti and Fanciullo 2013].
Theorem 3.5 [Bramanti and Fanciullo 2013, Theorem 2.10]. Let $1<p<\infty, 0<\sigma<1, u \in \mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)$ and $\Delta_{H} u \in \mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)$. Then $X_{i} X_{j} u \in \mathrm{BMO}^{p}\left(B_{\sigma}\right)$ for $i, j=1, \ldots, m$ and there exists a universal constant $C(\sigma, p)>0$ such that

$$
\begin{equation*}
\left\|X_{i} X_{j} u\right\|_{\mathrm{BMO}^{p}\left(B_{\sigma}\right)} \leq C(\sigma, p)\left(\left\|\Delta_{H} u\right\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right) \tag{3-8}
\end{equation*}
$$

Remark 3.6. Note that the nonvariational form of the operator in [Bramanti and Fanciullo 2013, Theorem 2.10] needs a priori that the solution $u$ and its horizontal derivatives are BMO. For our purposes, it is very important that the BMO regularity of $u$ is established with no a priori assumptions. This can be obtained for the sub-Laplacian operator, since its distributional form allows us to apply a mollification argument.

In the sequel, we will also use the Frobenius norm $|M|$ for a matrix $M$ of coefficients $m_{i j}$, setting

$$
|M|=\sqrt{\sum_{i j}\left|m_{i j}\right|^{2}}
$$

With this definition we easily notice that $\left|\Delta_{H} u\right| \leq\left|D_{h}^{2} u\right|$.
Corollary 3.7. Let $1<p<\infty$ and $0<\sigma<1$ be fixed. There exists $C(\sigma, p)>0$ such that for all $u \in$ $\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)$ that satisfy the condition $\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$, we have $X_{i} X_{j} u \in \mathrm{BMO}^{p}\left(B_{\sigma}\right)$ for $i, j=1, \ldots, m$ and whenever $x_{0} \in B_{\sigma}, 0<r<1-\sigma$,

$$
\begin{equation*}
f_{B_{r}\left(x_{0}\right) \cap B_{\sigma}}\left|D_{h}^{2} u(y)-P_{r}^{x_{0}}\right| d y \leq C(\sigma, p)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right), \tag{3-9}
\end{equation*}
$$

where the matrix $P_{r}^{x_{0}}$ is introduced in Definition 3.2.
Proof. Theorem 3.5 immediately implies that $X_{i} X_{j} u \in \mathrm{BMO}^{p}\left(B_{\sigma}\right)$ and (3-8) holds. Thus, we obtain the estimates

$$
\begin{aligned}
f_{B_{r}\left(x_{0}\right) \cap B_{\sigma}}\left|D_{h}^{2} u(y)-P_{r}^{x_{0}}\right| d y & \leq f_{B_{r}\left(x_{0}\right) \cap B_{\sigma}}\left|D_{h}^{2} u(y)-\left(D_{h}^{2} u\right)_{B_{r}\left(x_{0}\right)}\right| d y+\frac{1}{m}\left|\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)} I_{m}\right| \\
& \leq\left[D_{h}^{2} u\right]_{\mathrm{BMO}\left(B_{\sigma}\right)}+\frac{1}{\sqrt{m}}\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)} \\
& \leq \widetilde{C}(\sigma, p)\left(\left\|\Delta_{H} u\right\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right)+\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)} \\
& \leq C(\sigma, p)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}\left(B_{1}\right)}\right)
\end{aligned}
$$

Heuristically, if $D_{h}^{2} u$ is not bounded around $x_{0}$, since the difference of $D_{h}^{2} u$ and $P_{r}^{x_{0}}$ is controlled, the BMO estimate tells us that also $P_{r}^{x_{0}}$ becomes unbounded as $r \rightarrow 0^{+}$. Hence we will turn our attention to $P_{r}^{x_{0}}$. In the following lemma, we will derive a general "scaling estimate" for the difference $\left|P_{r_{1}}^{x_{0}}-P_{r_{2}}^{x_{0}}\right|$. In particular, when $r_{2}=2 r_{1}$ we get a uniform bound on the growth of $\left|P_{r}^{x_{0}}\right|$ on dyadic scales.

Lemma 3.8 (scaling estimates). Let $1<p<\infty$ and $0<\lambda_{1}<1$ be fixed. Then there exists a universal constant $C\left(\lambda_{1}, p\right)>0$ such that for all $u \in \mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)$ that satisfy the condition $\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$ the following holds. We have $X_{i} X_{j} u \in L_{\mathrm{loc}}^{1}\left(B_{1}\right)$, where $i, j=1, \ldots, m$ and for $x_{0} \in B_{\lambda_{1} / 3}$ the matrices of the form

$$
P_{r}^{x_{0}}:=\left(D_{h}^{2} u\right)_{B_{r}\left(x_{0}\right)}-\frac{1}{m}\left(\Delta_{H} u\right)_{B_{r}\left(x_{0}\right)} I_{m}
$$

with $0<r_{1}<\min \left\{\frac{2}{3} \lambda_{1}, 1-\lambda_{1}\right\}$ and $r_{1}<r_{2}<1-\lambda_{1}$, satisfy the inequality

$$
\left|P_{r_{1}}^{x_{0}}-P_{r_{2}}^{x_{0}}\right| \leq\left(\frac{r_{2}}{r_{1}}\right)^{Q} C\left(\lambda_{1}, p\right)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right)
$$

Proof. Due to the BMO estimate (3-9) with $\sigma=\lambda_{1}$, we can estimate $\left|P_{r_{1}}^{x_{0}}-P_{r_{2}}^{x_{0}}\right|$ as

$$
\begin{aligned}
f_{B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}}\left|P_{r_{1}}^{x_{0}}-P_{r_{2}}^{x_{0}}\right| d x & \leq f_{B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}}\left|D_{h}^{2} u(y)-P_{r_{1}}^{x_{0}}\right| d y+f_{B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}}\left|D_{h}^{2} u(y)-P_{r_{2}}^{x_{0}}\right| d y \\
& \leq f_{B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}}\left|D_{h}^{2} u(y)-P_{r_{1}}^{x_{0}}\right| d y+\frac{\left|B_{r_{2}}\left(x_{0}\right) \cap B_{\lambda_{1}}\right|}{\left|B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}\right|} f_{B_{r_{2}}\left(x_{0}\right) \cap B_{\lambda_{1}}}\left|D_{h}^{2} u(y)-P_{r_{2}}^{x_{0}}\right| d y \\
& \leq C\left(\lambda_{1}, p\right)\left(1+\left(\frac{r_{2}}{r_{1}}\right)^{Q}\right)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}\left(B_{1}\right)}\right)
\end{aligned}
$$

The last inequality follows by taking into account our conditions on the radii $r_{1}$ and $r_{2}$. Indeed, we have

$$
\frac{\left|B_{r_{2}}\left(x_{0}\right) \cap B_{\lambda_{1}}\right|}{\left|B_{r_{1}}\left(x_{0}\right) \cap B_{\lambda_{1}}\right|} \leq \frac{\left|B_{r_{2}}\left(x_{0}\right)\right|}{\left|B_{r_{1}}\left(x_{0}\right)\right|}=\left(\frac{r_{2}}{r_{1}}\right)^{Q} .
$$

Finally, with a slight abuse of notation, we denote the constant $2 C\left(\lambda_{1}, p\right)$ again by $C\left(\lambda_{1}, p\right)$ in the inequality of the lemma, concluding the proof.

## 4. Proof of $\boldsymbol{C}_{\boldsymbol{H}}^{1,1}$ regularity

This section represents the core of the paper. We establish the subquadratic growth of the difference

$$
u(y)-u\left(x_{0}\right)-\left\langle\nabla_{h} u\left(x_{0}\right), \pi\left(x_{0}^{-1} y\right)\right\rangle-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)
$$

on the ball $B_{r}\left(x_{0}\right)$, where $p_{r}^{x_{0}}$ is the harmonic polynomial introduced in Definition 3.2. We show that when the norm of $D_{h}^{2} p_{r}^{x_{0}}$ is sufficiently large, the measure of the coincidence set $\{u=0\}$ decays in a quantitative way. This is one of the central facts that leads us to the dichotomy argument of [Andersson et al. 2013] to reach the $C_{H}^{1,1}$ regularity. There are indeed two cases:
(i) When $\left|D_{h}^{2} p_{r}^{x_{0}}\right|$ is uniformly bounded as $r \rightarrow 0^{+}$, we immediately infer the regularity from the subquadratic growth.
(ii) If otherwise $\left|D_{h}^{2} p_{r}^{x_{0}}\right|$ grows without bound as $r \rightarrow 0^{+}$, then the coincidence set is "small" and we show that a suitable adaptation of Caffarelli's polynomial iteration technique can lead us to the $C_{H}^{1,1}$ regularity.

In the sequel, whenever we consider a function $u$ with essentially bounded sub-Laplacian $\Delta_{H} u$, it is understood that $u$ is chosen to be of class $C_{H}^{1}$. The following remark rigorously justifies this convention.

Remark 4.1. Let $\Omega \subset \mathbb{R}^{n}$ be an open set and let $u: \Omega \rightarrow \mathbb{R}$ be a locally summable function such that $\Delta_{H} u \in L^{\infty}(\Omega)$. From [Folland 1975, Theorem 6.1], we have $u \in W_{H, l o c}^{2, p^{\prime}}(\Omega)$ for every $p^{\prime}>1$. In view of Theorem 2.5, by standard arguments, we can modify $u$ on a negligible set such that $u \in C_{H}^{1, \alpha}\left(\Omega^{\prime}\right)$ for any relatively compact open set $\Omega^{\prime} \Subset \Omega$, where we have fixed some $p^{\prime}>Q$ and $\alpha=1-Q / p^{\prime}$. In particular, we have shown that, after the modification, $u \in C_{H}^{1}(\Omega)$.
Lemma 4.2 (subquadratic growth). Assume $u \in \mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)$ such that $\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$. Let $\lambda, \sigma \in(0,1)$ and fix $p>1$. Then there exist $r_{0}>0$ and a universal constant $C(\lambda, \sigma, p)>0$ such that for any $x_{0} \in B_{\lambda}$ and $0<r \leq r_{0}$, assuming that

$$
u\left(x_{0}\right)=X_{i} u\left(x_{0}\right)=0, \quad 1 \leq i \leq m
$$

and considering $p_{r}^{x_{0}}$, as given in Definition 3.2, the following estimate holds:

$$
\sup _{y \in B_{\sigma r}\left(x_{0}\right)}\left|u(y)-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| \leq C(\lambda, \sigma, p)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right) r^{2} .
$$

Proof. We fix $x_{0} \in B_{\lambda}$ and $\lambda^{\prime}=(1+\lambda) / 2$, so that for $0<r \leq \lambda^{\prime}-\lambda$ we have the inclusion

$$
\begin{equation*}
B_{r}\left(x_{0}\right) \subset B_{\lambda^{\prime}} . \tag{4-1}
\end{equation*}
$$

Let us introduce the translated and rescaled function

$$
u_{r, x_{0}}(x):=\frac{u\left(x_{0} \delta_{r} x\right)-p_{r}^{x_{0}}\left(\delta_{r} x\right)}{r^{2}}
$$

observing that it is well-defined in $B_{1}$. Taking into account that $u \in W_{H, \text { loc }}^{2, p}\left(B_{1}\right)$ and $\overline{B_{r}\left(x_{0}\right)} \subset \bar{B}_{\lambda^{\prime}} \subset B_{1}$, we have $u_{r, x_{0}} \in W_{H}^{2, p}\left(B_{1}\right)$. We are in the position to apply Corollary 3.7 to $u$ with $\sigma=\lambda^{\prime}$. As a consequence of both Corollary 3.3 and (3-9), taking into account (4-1), it follows that

$$
\begin{align*}
\left\|D_{h}^{2} u_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} & =\left|B_{1}\right| f_{B_{1}}\left|D_{h}^{2} u_{r, x_{0}}(x)\right| d x=\left|B_{1}\right| f_{B_{r}\left(x_{0}\right)}\left|D_{h}^{2} u(y)-P_{r}^{x_{0}}\right| d y \\
& \leq C(\lambda, p)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right) \tag{4-2}
\end{align*}
$$

Now we wish to apply the Poincaré inequality (2-10) to $u_{r, x_{0}}-\ell_{r, x_{0}}$, where $\ell_{r, x_{0}}$ is an affine function to be properly defined. If we let

$$
\ell_{r, x_{0}}(x):=\left(u_{r, x_{0}}\right)_{B_{1}}+\left\langle\left(\nabla_{h} u_{r, x_{0}}\right)_{B_{1}}, \pi(x)\right\rangle,
$$

where $\pi(x)=\left(x_{1}, \ldots, x_{m}\right)$, it follows that

$$
\left\|u_{r, x_{0}}-\ell_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} \leq c f_{B_{1}}\left|\nabla_{h} u_{r, x_{0}}-\left(\nabla_{h} u_{r, x_{0}}\right)_{B_{1}}\right| d x
$$

since the average over $B_{1}$ of the linear part of $\ell_{r, x_{0}}$ is zero. Again, from the Poincaré inequality, using (4-2), we get

$$
\begin{align*}
\left\|u_{r, x_{0}}-\ell_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} & \leq C\left\|D_{h}^{2} u_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} \\
& \leq C(\lambda, p)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right) . \tag{4-3}
\end{align*}
$$

For the sequel, we set $\hat{u}_{r, x_{0}}:=u_{r, x_{0}}-\ell_{r, x_{0}}$. Since both $p_{r}^{x_{0}}$ and $\ell_{r, x_{0}}$ are harmonic, we observe that

$$
\Delta_{H} \hat{u}_{r, x_{0}}(x)=\left(\Delta_{H} u\right)\left(x_{0} \delta_{r} x\right)=f\left(x_{0} \delta_{r} x\right)
$$

for a.e. $x \in B_{1}$, where we have set $f:=\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$. We set $g_{r, x_{0}}(x)=f\left(x_{0} \delta_{r} x\right) \chi_{B_{1}}$ and we consider the decomposition $\hat{u}_{r, x_{0}}=\hat{v}_{r, x_{0}}+\hat{w}_{r, x_{0}}$, where

$$
\hat{v}_{r, x_{0}}=-g_{r, x_{0}} * \Gamma \quad \text { and } \quad \hat{w}_{r, x_{0}}=\hat{u}_{r, x_{0}}+g_{r, x_{0}} * \Gamma
$$

and $\Gamma$ is the fundamental solution for $\Delta_{H}$, introduced in Definition 2.3. The explicit form of $\hat{v}_{r, x_{0}}$ allows us to get the estimate

$$
\left|\hat{v}_{r, x_{0}}(x)\right|=\left|\int_{\mathbb{R}^{n}} \Gamma\left(z^{-1} x\right) g_{r, x_{0}}(z) d z\right|=\left|\int_{B_{1}} \Gamma\left(z^{-1} x\right) g_{r, x_{0}}(z) d z\right| \leq C\left\|g_{r, x_{0}}\right\|_{L^{Q_{0}\left(B_{1}\right)}}
$$

for every $x \in B_{1}$, where $Q_{0}=Q+1$ and $C>0$ can be seen as a universal constant. The previous estimate follows from the Hölder inequality, setting $q=Q_{0} / Q$ and taking into account the (2-Q)-homogeneity of $\Gamma$. Indeed,

$$
\begin{equation*}
\left|\int_{B_{1}} \Gamma\left(z^{-1} x\right) g_{r, x_{0}}(z) d z\right| \leq\left(\int_{B_{2}}|\Gamma|^{q}\right)^{1 / q}\left\|g_{r, x_{0}}\right\|_{L} Q_{0\left(B_{1}\right)} \tag{4-4}
\end{equation*}
$$

for every $x \in B_{1}$. As a consequence, we have proved that

$$
\begin{equation*}
\left\|\hat{v}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{1}\right)} \leq C\left\|\Delta_{H} \hat{u}_{r, x_{0}}\right\|_{L^{Q_{0}\left(B_{1}\right)}} \tag{4-5}
\end{equation*}
$$

Since $\hat{w}_{r, x_{0}}$ is harmonic, from [Bonfiglioli et al. 2007, (5.52)] we have the mean-value-type formula

$$
\hat{w}_{r, x_{0}}(x)=f_{B_{(1-\sigma) / c_{0}}^{G}(x)} \Psi\left(x^{-1} z\right) \hat{w}_{r, x_{0}}(z) d z
$$

for any $x \in B_{\sigma}$, whenever $0<\sigma<1$ and with $c_{0}>1$ defined in (2-6). We point out that the function $\Psi$ is 0 -homogeneous with respect to dilations and smooth on $\mathbb{R}^{n} \backslash\{0\}$; see [Bonfiglioli et al. 2007, Definition 5.5.1] for more information. Notice that with our assumptions we have the inclusion $B_{(1-\sigma) / c_{0}}^{G}(x) \subset B_{1}$. For every $x \in B_{\sigma}$,

$$
\begin{aligned}
\left|\hat{w}_{r, x_{0}}(x)\right| & =\left|f_{B_{(1-\sigma) / c_{0}}^{G}(x)} \Psi\left(x^{-1} z\right) \hat{w}_{r, x_{0}}(z) d z\right| \leq\|\Psi\|_{L^{\infty}\left(B_{1}\right)} f_{B_{(1-\sigma) / c_{0}}^{G}(x)}\left|\hat{w}_{r, x_{0}}(z)\right| d z \\
& \leq\|\Psi\|_{L^{\infty}\left(B_{1}\right)} \frac{\left\|\hat{w}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}^{G} \leq C(\sigma)\left\|\hat{w}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}}{} .
\end{aligned}
$$

The constant $C(\sigma)$ only depends on $\sigma$ and it blows up as $\sigma \rightarrow 1^{-}$. By the triangle inequality and (4-5) we obtain

$$
\begin{align*}
\left\|\hat{w}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)} & \leq C(\sigma)\left\|\hat{w}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} \\
& \leq C(\sigma)\left(\left\|\hat{u}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}+\left\|\hat{v}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}\right) \\
& \leq C_{1}(\sigma)\left(\left\|\hat{u}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}+\left\|\Delta_{H} \hat{u}_{r, x_{0}}\right\|_{L^{Q_{0}\left(B_{1}\right)}}\right) \tag{4-6}
\end{align*}
$$

We conclude from both (4-5) and (4-6) that

$$
\begin{align*}
\left\|\hat{u}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)} & \leq\left\|\hat{v}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)}+\left\|\hat{w}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)} \\
& \leq C_{2}(\sigma)\left(\left\|\hat{u}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}+\left\|\Delta_{H} \hat{u}_{r, x_{0}}\right\|_{L^{Q_{0}\left(B_{1}\right)}}\right) \tag{4-7}
\end{align*}
$$

Differentiating $\hat{v}_{r, x_{0}}$, seen as an integral, it turns out that $\hat{v}_{r, x_{0}} \in C_{H}^{1}\left(B_{1}\right)$. Again arguing as in the proof of (4-4), from the Hölder inequality and the (1-Q)-homogeneity of $X_{j} \Gamma$, we get the estimate

$$
\begin{equation*}
\left|X_{j} \hat{v}_{r, x_{0}}(x)\right|=\left|\int_{B_{1}} X_{j} \Gamma\left(y^{-1} x\right) g_{r, x_{0}}(y) d y\right| \leq \bar{C}\left\|g_{r, x_{0}}\right\|_{L} Q_{0}\left(B_{1}\right) \tag{4-8}
\end{equation*}
$$

for every $j=1, \ldots, m, x \in B_{1}$ and a fixed geometric constant $\bar{C}>0$. By Proposition 2.4 , we get a constant $C_{3}(\sigma)>0$ such that

$$
\begin{equation*}
\left\|\nabla_{h} \hat{w}_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)} \leq C_{3}(\sigma)\left\|\hat{w}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)} \tag{4-9}
\end{equation*}
$$

Combining (4-7), (4-8) and (4-9), along with the third inequality of (4-6), we establish the first of the inequalities

$$
\begin{aligned}
\left\|\hat{u}_{r, x_{0}}\right\|_{C_{H}^{1}\left(B_{\sigma}\right)} & \leq C_{4}(\sigma)\left(\left\|\hat{u}_{r, x_{0}}\right\|_{L^{1}\left(B_{1}\right)}+\left\|\Delta_{H} \hat{u}_{r, x_{0}}\right\|_{L^{Q_{0}\left(B_{1}\right)}}\right) \\
& \leq C_{5}(\sigma, p, \lambda)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right) .
\end{aligned}
$$

The second inequality is a consequence of (4-3). Since $u_{r, x_{0}}(0)=X_{j} u_{r, x_{0}}(0)=0$, by our assumptions on $u$, and taking into account that $p_{r}^{x_{0}}(0)=X_{j} p_{r}^{x_{0}}(0)=0$, we immediately infer from the $C_{H}^{1}$ estimate above that

$$
\begin{aligned}
\left|\ell_{r, x_{0}}(0)\right|+\sum_{i=1}^{m}\left|X_{i} \ell_{r, x_{0}}(0)\right| & =\left|\ell_{r, x_{0}}(0)-u_{r, x_{0}}(0)\right|+\sum_{i=1}^{m}\left|X_{i} \ell_{r, x_{0}}(0)-X_{i} u_{r, x_{0}}(0)\right| \\
& \leq\left\|\hat{u}_{r, x_{0}}\right\|_{C^{1}\left(B_{\sigma}\right)} \leq C_{5}(\sigma, p, \lambda)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right)
\end{aligned}
$$

It follows that

$$
\left\|\ell_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}\right)} \leq C_{6}(\sigma, p, \lambda)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right)
$$

As a consequence,

$$
\begin{aligned}
\frac{1}{r^{2}} \sup _{y \in B_{\sigma r}\left(x_{0}\right)}\left|u(y)-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| & =\sup _{x \in B_{\sigma}}\left|\frac{u\left(x_{0} \delta_{r} x\right)-p_{r}^{x_{0}}\left(\delta_{r} x\right)}{r^{2}}\right|=\sup _{x \in B_{\sigma}}\left|u_{r, x_{0}}(x)\right| \\
& \leq \sup _{x \in B_{\sigma}}\left|\hat{u}_{r, x_{0}}(x)\right|+\sup _{x \in B_{\sigma}}\left|\ell_{r, x_{0}}(x)\right| \\
& \leq C(\sigma, p, \lambda)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{\mathrm{BMO}_{\mathrm{loc}}^{p}\left(B_{1}\right)}\right)
\end{aligned}
$$

Corollary 4.3. Assume $u \in L^{\infty}\left(B_{1}\right)$ such that $\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$ and fix $0<\lambda, \sigma<1$. If we consider $\pi$ as in (3-2), then there exists $r_{0}>0$ such that the affine function

$$
\ell^{x_{0}}(z):=u\left(x_{0}\right)+\left\langle\nabla_{h} u\left(x_{0}\right), \pi(z)\right\rangle, \quad x_{0} \in B_{\lambda},
$$

satisfies the following property: there exists a universal constant $C(\lambda, \sigma)>0$ such that for every $r \in\left(0, r_{0}\right]$ the estimate

$$
\begin{equation*}
\sup _{y \in B_{\sigma r}\left(x_{0}\right)}\left|u(y)-\ell^{x_{0}}\left(x_{0}^{-1} y\right)-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| \leq C(\lambda, \sigma)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) r^{2} \tag{4-10}
\end{equation*}
$$

holds, where $p_{r}^{x_{0}}$ is as in Definition 3.2.
Proof. Our assumptions allow us to apply Lemma 4.2 to $y \rightarrow u(y)-\ell^{x_{0}}\left(x_{0}^{-1} y\right)$ with $p=2$. Then there exist $r_{0}, C(\lambda, \sigma)>0$ such that

$$
\sup _{y \in B_{\sigma r}\left(x_{0}\right)}\left|u(y)-\ell^{x_{0}}\left(x_{0}^{-1} y\right)-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| \leq C(\lambda, \sigma)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\left\|u-\ell^{x_{0}}\right\|_{\mathrm{BMO}_{\mathrm{loc}}^{2}\left(B_{1}\right)}\right) r^{2}
$$

for every $r \in\left(0, r_{0}\right]$. In addition, we have

$$
\left\|u-\ell^{x_{0}}\right\|_{\mathrm{BMO}_{\mathrm{loc}}^{2}\left(B_{1}\right)} \leq C\left\|u-\ell^{x_{0}}\right\|_{L^{\infty}\left(B_{1}\right)} \leq C^{\prime}\left(\|u\|_{L^{\infty}\left(B_{1}\right)}+\left|\nabla_{h} u\left(x_{0}\right)\right|\right)
$$

We set $f=\Delta_{H} u \in L^{\infty}\left(B_{1}\right)$ and write $v=f * \Gamma$, getting

$$
\left|\nabla_{h} u\left(x_{0}\right)\right| \leq\left|\nabla_{h}(u+v)\left(x_{0}\right)\right|+\left|\nabla_{h}(f * \Gamma)\left(x_{0}\right)\right| .
$$

Arguing as in [Gilbarg and Trudinger 2001, Lemma 4.1], we establish

$$
\left|\nabla_{h} v\left(x_{0}\right)\right|=\left|\nabla_{h}(f * \Gamma)\left(x_{0}\right)\right| \leq\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}\left\|\nabla_{h} \Gamma\right\|_{L^{1}\left(B_{2}\right)} ;
$$

therefore we have

$$
\left|\nabla_{h} u\left(x_{0}\right)\right| \leq\left|\nabla_{h}(u+v)\left(x_{0}\right)\right|+\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}\left\|\nabla_{h} \Gamma\right\|_{L^{1}\left(B_{2}\right)} .
$$

Since $u+v$ is harmonic in $B_{1}$, by (2-9), it follows that

$$
\begin{aligned}
\left|\nabla_{h}(u+v)\left(x_{0}\right)\right| & \leq C_{0}\left(\|u\|_{L^{\infty}\left(B_{1}\right)}+\|v\|_{L^{\infty}\left(B_{1}\right)}\right) \\
& \leq C_{0}\left(\|u\|_{L^{\infty}\left(B_{1}\right)}+\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}\|\Gamma\|_{L^{1}\left(B_{2}\right)}\right) .
\end{aligned}
$$

This immediately leads us to our claim.
Remark 4.4. Notice that under the assumptions of Corollary 4.3, we can assume that, for every $\lambda, \sigma \in$ $(0,1)$ and any $x_{0} \in B_{\lambda}$, there exist $\tilde{r}_{0}>0$ and $C>0$, only depending on $\lambda$ and $\sigma$, such that for all $r \in\left(0, \tilde{r}_{0}\right]$ the estimate

$$
\sup _{y \in B_{\sigma_{0} r}^{G}\left(x_{0}\right)}\left|u(y)-\ell^{x_{0}}\left(x_{0}^{-1} y\right)-p_{r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| \leq C(\lambda, \sigma)\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) r^{2}
$$

holds for $\sigma_{0}=\sigma / c_{0} \in\left(0,1 / c_{0}\right)$ and additionally we have the inclusion $\overline{B_{r_{0}}^{G}\left(x_{0}\right)} \subset B_{1}$. This is a consequence of the definition of $c_{0}$ in (2-8). If we set $r_{0}:=\tilde{r}_{0} / c_{0}$, replacing $r$ by $c_{0} r$, we may rephrase the previous estimate as

$$
\begin{equation*}
\sup _{y \in B_{G r}^{G}\left(x_{0}\right)}\left|u(y)-\ell^{x_{0}}\left(x_{0}^{-1} y\right)-p_{c_{0} r}^{x_{0}}\left(x_{0}^{-1} y\right)\right| \leq C(\lambda, \sigma) c_{0}^{2}\left(\left\|\Delta_{H} u\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) r^{2} \tag{4-11}
\end{equation*}
$$

for every $0<r \leq r_{0}$.

We introduce now the important definition of coincidence set:

$$
\Lambda:=\left\{x \in B_{1}: u(x)=0\right\} .
$$

We will perform a blow-up of $\Lambda$ around a fixed point $x_{0} \in B_{1 / 2}$, considering the rescaled and translated coincidence sets

$$
\Lambda_{r}\left(x_{0}\right):=\left\{x \in B_{1}^{G}: u\left(x_{0} \delta_{r} x\right)=0\right\}
$$

for $0<r \leq r_{0}$ and some $r_{0}>0$ such that $B_{r}^{G}\left(x_{0}\right) \subset B_{1}$. Notice that in the previous definition the gauge distance is used for technical reasons, related to the existence of solutions to the Dirichlet problem with respect to the sub-Laplacian.

The next result is a technical lemma, which will be used both to get the decay estimates in Proposition 4.6 and to establish the regularity in Theorem 4.8.

Lemma 4.5. Let $f$ be such that $f * \Gamma \in C_{H}^{1,1}\left(B_{1}\right)$ and let $u$ solve (1-1) in $B_{1}$. Then for every $0<\lambda, \sigma<1$, there exists $r_{0}>0$ such that for every $x_{0} \in B_{\lambda}$ we have $\overline{B_{r_{0}}^{G}\left(x_{0}\right)} \subset B_{1}$ and the following holds. Let us consider the translated and rescaled function

$$
\begin{equation*}
u_{r, x_{0}}(x):=\frac{u\left(x_{0} \delta_{r} x\right)-\ell^{x_{0}}\left(\delta_{r} x\right)-p_{c_{0} r}^{x_{0}}\left(\delta_{r} x\right)}{r^{2}} \tag{4-12}
\end{equation*}
$$

where $p_{c_{0} r}^{x_{0}}$ is introduced in Definition 3.2 and $\ell^{x_{0}}(z)=u\left(x_{0}\right)+\left\langle\nabla_{h} u\left(x_{0}\right)\right.$, $\left.\pi(z)\right\rangle$. For each $r \in\left(0, r_{0}\right]$ we also define $v_{r, x_{0}}$ as the solution to

$$
\begin{cases}\Delta_{H} v_{r, x_{0}}=f_{r, x_{0}} & \text { in } B_{\sigma}^{G}  \tag{4-13}\\ v_{r, x_{0}}=u_{r, x_{0}} & \text { on } \partial B_{\sigma}^{G}\end{cases}
$$

where $f_{r, x_{0}}(x)=f\left(x_{0} \delta_{r} x\right) \chi_{B_{\sigma}^{G}}$. Then there exists a universal constant $C(\lambda, \sigma)>0$, depending on $\lambda$ and $\sigma$, such that

$$
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq C(\lambda, \sigma)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

Proof. Due to Remark 4.4, there exists $r_{0}>0$ such that for every $x_{0} \in B_{\lambda}$ we have $\overline{B_{r_{0}}^{G}\left(x_{0}\right)} \subset B_{1}$ and (4-11) holds for every $r \in\left(0, r_{0}\right]$. We write the solution to the Dirichlet problem (4-13) in the form

$$
v_{r, x_{0}}=\eta_{r, x_{0}}+\zeta_{r, x_{0}}
$$

where $\zeta_{r, x_{0}}$ solves

$$
\begin{cases}\Delta_{H} \zeta_{r, x_{0}}=0 & \text { in } B_{\sigma}^{G} \\ \zeta_{r, x_{0}}=u_{r, x_{0}}-\eta_{r, x_{0}} & \text { on } \partial B_{\sigma}^{G}\end{cases}
$$

and we have defined

$$
\eta_{r, x_{0}}=-f_{r, x_{0}} * \Gamma
$$

Indeed, the open set $B_{\sigma}^{G}$ is regular with respect to $\Delta_{H}$; see [Bonfiglioli et al. 2007, Proposition 7.2.8]. From the identity

$$
D_{h}^{2} v_{r, x_{0}}=-D_{h}^{2}\left(f_{r, x_{0}} * \Gamma\right)+D_{h}^{2} \zeta_{r, x_{0}},
$$

taking into account the equality $D_{h}^{2}(f * \Gamma)\left(x_{0} \delta_{r} x\right)=D_{h}^{2}\left(f_{r, x_{0}} * \Gamma\right)(x)$ for a.e. $x \in B_{\sigma^{2}}^{G}$ and the estimate (2-9) we obtain

$$
\begin{aligned}
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} & \leq\left\|D_{h}^{2}\left(f_{r, x_{0}} * \Gamma\right)\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)}+\left\|D_{h}^{2} \zeta_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \\
& \leq\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{\sigma^{2} r}^{G}\left(x_{0}\right)\right)}+C(\sigma)\left\|\zeta_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}^{G}\right)}
\end{aligned}
$$

Now we combine the maximum principle and the Dirichlet problem (4-13) to get

$$
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+C(\sigma)\left\|u_{r, x_{0}}+f_{r, x_{0}} * \Gamma\right\|_{L^{\infty}\left(\partial B_{\sigma}^{G}\right)}
$$

Due to the version of the subquadratic growth in (4-11), taking into account the definition (4-12) and the immediate estimate

$$
\left\|f_{r, x_{0}} * \Gamma\right\|_{L^{\infty}\left(B_{\sigma}^{G}\right)} \leq C\|f\|_{L^{\infty}\left(B_{1}\right)}
$$

where $C>0$ only depends on $\Gamma$, it follows that

$$
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+C(\lambda, \sigma)\left(\|u\|_{L^{\infty}\left(B_{1}\right)}+\|f\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

In conclusion, we have established the estimate

$$
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq C(\lambda, \sigma)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

concluding the proof.
Proposition 4.6 (decay of the coincidence set). Let $f$ be such that $f * \Gamma \in C_{H}^{1,1}\left(B_{1}\right)$ and let $u$ solve (1-1). Then for every $\beta>0$, there exist $C_{\beta}>0$ and $r_{0}>0$ so that if $0<r \leq r_{0}, x_{0} \in B_{1 / 2}$, and the estimate

$$
\left|P_{r}^{x_{0}}\right| \geq C_{\beta}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

holds, we have

$$
\begin{equation*}
\left|\Lambda_{r / 2}\left(x_{0}\right)\right| \leq \frac{\left|\Lambda_{r}\left(x_{0}\right)\right|}{2^{\beta Q}} \tag{4-14}
\end{equation*}
$$

Proof. Our assumptions allow us to apply Lemma 4.5 with $\lambda=\frac{1}{2}$, where we choose $\sigma \in[1 / \sqrt{2}, 1)$. Let $r_{0}>0, v_{r, x_{0}}$ and $u_{r, x_{0}}$ be as in the same lemma and define

$$
w_{r, x_{0}}:=v_{r, x_{0}}-u_{r, x_{0}}
$$

Lemma 4.5 yields a constant $C(\sigma)>0$ such that

$$
\left\|D_{h}^{2} v_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq C(\sigma)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

for every $r \in\left(0, r_{0}\right]$. In addition, from the definition of $w_{r, x_{0}}$ we observe that

$$
\begin{cases}\Delta_{H} w_{r, x_{0}}=f_{r, x_{0}} \chi_{\Lambda_{r}\left(x_{0}\right)} & \text { in } B_{\sigma}^{G} \\ w_{r, x_{0}}=0 & \text { on } \partial B_{\sigma}^{G}\end{cases}
$$

By uniqueness, it follows that

$$
w_{r, x_{0}}=-\left(f_{r, x_{0}} \chi_{\Lambda_{r}\left(x_{0}\right)}\right) * G_{B_{\sigma}^{G}}
$$

where $G_{B_{\sigma}^{G}}$ is the Green's function of $B_{\sigma}^{G}$, according to [Bonfiglioli et al. 2007, Definition 9.2.1]. From the definition of the Green's function, we have $G_{B_{\sigma}^{G}} \geq 0$. In addition, taking into account [Bonfiglioli et al. 2007, Proposition 9.2.12(iv)], we also notice that the maximum principle gives

$$
G_{B_{\sigma}^{G}}(x, y) \leq \Gamma\left(x^{-1} y\right)
$$

for every $x, y \in B_{\sigma}^{G}$ with $x \neq y$. Then a standard convolution estimate yields

$$
\begin{equation*}
\left\|w_{r, x_{0}}\right\|_{L^{\infty}\left(B_{\sigma}^{G}\right)} \leq C\|f\|_{L^{\infty}\left(B_{r \sigma}^{G}\left(x_{0}\right)\right)}\left\|\chi_{\Lambda_{r}\left(x_{0}\right)}\right\|_{L^{Q}\left(B_{1}\right)} \leq C\|f\|_{L^{\infty}\left(B_{1}\right)}\left|\Lambda_{r}\left(x_{0}\right)\right|^{1 / Q} \tag{4-15}
\end{equation*}
$$

for some geometric constant $C>0$. The $W_{H}^{2, p}$ estimates (3-7) give a universal constant $C_{1}$, depending on $\sigma$, such that

$$
\begin{aligned}
\int_{B_{\sigma^{2}}^{G}}\left|D_{h}^{2} w_{r, x_{0}}(x)\right|^{2 Q} d x & \leq C_{1}\left(\left\|f_{r, x_{0}} \chi_{\Lambda_{r}\left(x_{0}\right)}\right\|_{L^{2 Q}\left(B_{\sigma}^{G}\right)}+\left\|w_{r, x_{0}}\right\|_{\left.L^{2} Q_{\left(B_{\sigma}^{G}\right)}\right)^{2 Q}}\right. \\
& \leq C_{2}\|f\|_{L^{\infty}\left(B_{1}\right)}^{2 Q}\left(\left|\Lambda_{r}\left(x_{0}\right)\right|+\left|\Lambda_{r}\left(x_{0}\right)\right|^{2}\right) \\
& \leq C_{3}\|f\|_{L^{\infty}\left(B_{1}\right)}^{2 Q}\left|\Lambda_{r}\left(x_{0}\right)\right| .
\end{aligned}
$$

The second inequality is again a consequence of a convolution estimate, joined with (4-15). Since $\left|\Lambda_{r}\left(x_{0}\right)\right| \leq\left|B_{1}^{G}\right|$, the third inequality is also established. Furthermore, taking the second-order horizontal derivatives in the definition (4-12), we get the equality

$$
P_{c_{0} r}^{x_{0}}=\left(D_{h}^{2} u\right)\left(x_{0} \delta_{r} x\right)+D_{h}^{2} w_{r, x_{0}}(x)-D_{h}^{2} v_{r, x_{0}}(x)
$$

and also $\Lambda_{r \sigma^{2}}\left(x_{0}\right)=\delta_{\sigma^{-2}}\left(\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}\right)$. In addition, arguing as in [Gilbarg and Trudinger 2001, Lemma 7.7], we can establish that $\left(D_{h}^{2} u\right)\left(x_{0} \delta_{r} x\right)=0$ a.e. on the coincidence set $\Lambda_{r}\left(x_{0}\right)$. Taking into account all previous facts, we get

$$
\begin{aligned}
\sigma^{2 Q}\left|\Lambda_{r \sigma^{2}}\left(x_{0}\right)\right|\left|P_{c_{0} r}^{x_{0}}\right|^{2 Q} & =\left|\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}\right|\left|P_{c_{0} r}^{x_{0}}\right|^{2 Q}=\int_{\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}}\left|P_{c_{0} r}^{x_{0}}\right|^{2 Q} d x \\
& =\int_{\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}}\left|\left(D_{h}^{2} u\right)\left(x_{0} \delta_{r} x\right)+D_{h}^{2} w_{r, x_{0}}(x)-D_{h}^{2} v_{r, x_{0}}(x)\right|^{2 Q} d x \\
& =\int_{\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}}\left|D_{h}^{2} w_{r, x_{0}}(x)-D_{h}^{2} v_{r, x_{0}}(x)\right|^{2 Q} d x \\
& \leq 4^{Q} \int_{\Lambda_{r}\left(x_{0}\right) \cap B_{\sigma^{2}}^{G}}\left|D_{h}^{2} w_{r, x_{0}}(x)\right|^{2 Q}+\left|D_{h}^{2} v_{r, x_{0}}(x)\right|^{2 Q} d x \\
& \leq C_{2}(\sigma)\left(\|f\|_{L^{\infty}\left(B_{1}\right)}^{2 Q}\left|\Lambda_{r}\left(x_{0}\right)\right|+\left|\Lambda_{r \sigma^{2}}\left(x_{0}\right)\right|\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)^{2 Q}\right)
\end{aligned}
$$

Consequently,

$$
\frac{\sigma^{2 Q}\left|P_{c_{0} r}^{x_{0}}\right|^{2 Q}-C_{2}(\sigma)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)^{2 Q}}{C_{2}(\sigma)\|f\|_{L^{\infty}\left(B_{1}\right)}^{2 Q}}\left|\Lambda_{r \sigma^{2}}\left(x_{0}\right)\right| \leq\left|\Lambda_{r}\left(x_{0}\right)\right| .
$$

We see that the coefficient in front of $\left|\Lambda_{r \sigma^{2}}\left(x_{0}\right)\right|$ is bigger than $2^{\beta Q}$ if

$$
\begin{equation*}
\sigma^{2 Q}\left|P_{c_{0} r}^{x_{0}}\right|^{2 Q} \geq C_{2}(\sigma) 2^{\beta Q}\|f\|_{L^{\infty}\left(B_{1}\right)}^{2 Q}+C_{2}(\sigma)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)^{2 Q} . \tag{4-16}
\end{equation*}
$$

By the simple inequality $\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)} \geq\|f\|_{L^{\infty}\left(B_{1}\right)}$, a few more computations lead us to the sufficient condition

$$
\left|P_{c_{0} r}^{x_{0}}\right| \geq \sqrt[2 Q]{C_{2}(\sigma) \sigma^{-2 Q}\left(2^{\beta Q}+2^{2 Q-1}\right)}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

to get (4-16) to hold. Finally, we choose $\sigma=1 / \sqrt{2}$, then the proof follows by choosing the constant $C_{\beta}$ in our statement equal to $\sqrt[2 Q]{C_{2}(1 / \sqrt{2}) 2^{Q}\left(2^{\beta Q}+2^{2 Q-1}\right)}$ and replacing $c_{0} r$ by $r$.

To carry out the proof of the $C_{H}^{1,1}$ regularity, we need a Calderón-type second-order differentiability, according to the next definition.
Definition 4.7. We say that $u \in L_{\mathrm{loc}}^{1}(\Omega)$ is twice $L^{1}$ differentiable at $x_{0}$ if there exists a polynomial $t$ of degree less than or equal to 2 such that

$$
\frac{1}{r^{2}} f_{B_{r}\left(x_{0}\right)}|u(z)-t(z)| d z \rightarrow 0 \quad \text { as } r \rightarrow 0^{+}
$$

The polynomial $t$ has the form

$$
t(x)=c_{0}+\sum_{l=1}^{m} v_{l}\left(x_{l}-x_{0 l}\right)+\frac{1}{2} \sum_{i, j=1}^{m} c_{i j}\left(x_{i}-x_{0 i}\right)\left(x_{j}-x_{0 j}\right)+\sum_{l=m+1}^{m_{2}} c_{l}\left(x_{l}-x_{0 l}\right)
$$

$x=\left(x_{1}, \ldots, x_{n}\right), x_{0}=\left(x_{01}, \ldots, x_{0 n}\right)$ and $c_{0}, c_{i j}, c_{l} \in \mathbb{R}$.
It is possible to show that any $u \in W_{H, \text { loc }}^{2,1}(\Omega)$ is twice $L^{1}$ differentiable a.e. in $\Omega$. Furthermore, if the function is twice $L^{1}$ differentiable at a Lebesgue point $x_{0} \in \Omega$ of all functions $X_{i} X_{j} u, X_{j} u$ and $u$, then the corresponding polynomial is unique and it has the form

$$
u\left(x_{0}\right)+\sum_{j=1}^{m} X_{j} u\left(x_{0}\right)\left(x_{j}-x_{0 j}\right)+\frac{1}{2} \sum_{i, j=1}^{m}\left(\left(X_{i} X_{j}+X_{j} X_{i}\right) u\right)\left(x_{0}\right)\left(x_{i}-x_{0 i}\right)\left(x_{j}-x_{0 j}\right)+\sum_{l=m+1}^{m_{2}} X_{l} u\left(x_{0}\right)\left(x_{l}-x_{0 l}\right)
$$

see [Magnani 2005] for more information. We are now in the position to prove the optimal interior regularity of solutions to the no-sign obstacle-type problem (1-1).

Theorem 4.8 ( $C^{1,1}$ regularity). Let $u \in L^{\infty}\left(B_{1}\right)$ be a distributional solution to (1-1) in the unit ball $B_{1}$. Let $f: B_{1} \rightarrow \mathbb{R}$ be locally summable such that $f * \Gamma \in C_{H}^{1,1}\left(B_{1}\right)$. Then there exists a universal constant $C>0$ such that, after a modification on a negligible set, we have $u \in C_{H}^{1,1}\left(B_{1 / 4}\right)$ and

$$
\left\|D_{h}^{2} u\right\|_{L^{\infty}\left(B_{1 / 4}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) .
$$

Proof. We consider $C_{\beta}$ as in Proposition 4.6 and fix $\beta=4$. We consider a priori the constant

$$
K=C_{4}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

Combining the Hölder inequality and Theorem 3.4, and taking into account that the constant $C_{\beta}$ in Proposition 4.6 is bounded from below by a universal positive constant independent of $\beta$, we can find a universal constant $C_{1}^{\prime}>0$ such that

$$
\begin{equation*}
\left\|D_{h}^{2} u\right\|_{L^{1}\left(B_{1 / 2}\right)} \leq C_{1}^{\prime} K \tag{4-17}
\end{equation*}
$$

Let $r_{0}>0$ be the minimum among the $r_{0}$ 's of Remark 4.4, Lemma 4.5 with $\lambda=\frac{1}{4}$ and Proposition 4.6 with $\beta=4$. We fix an integer $i_{0}$ such that

$$
\begin{equation*}
i_{0} \geq 3+\log _{2} c_{0} \tag{4-18}
\end{equation*}
$$

such that $2^{-i_{0}} \leq r_{0}$, where $c_{0}$ is the geometric constant appearing in (2-6). Then (4-17) provides us with a universal constant $\bar{C}_{1} \geq 1$ such that

$$
\begin{equation*}
\left|P_{2^{-i_{0}}}^{y}\right| \leq \bar{C}_{1} K \tag{4-19}
\end{equation*}
$$

for all $y \in B_{1 / 4}$. Notice that $\bar{C}_{1}$ actually depends on $i_{0}$. However, this integer is fixed throughout the proof. We have chosen $i_{0}$ to satisfy also (4-18) in view of the subsequent application of Lemma 3.8 with $\lambda_{1}=\frac{3}{4}$. We can fix $x_{0} \in B_{1 / 4}$ such that $u$ is twice $L^{1}$ differentiable at $x_{0}$. Using [Magnani 2005, Theorem 3.8] for $p=1$ and $k=2$, the set of these differentiability points has full measure in $B_{1}$. We can further write $u=v-w$ such that

$$
\Delta_{H} v=f \quad \text { and } \quad \Delta_{H} w=f \chi_{\Lambda}
$$

on $B_{1}$, where $v=-f * \Gamma$. By assumption $v \in C_{H}^{1,1}\left(B_{1}\right)$; hence it is also a.e. twice $L^{1}$ differentiable. Therefore we can further assume $v$ is twice $L^{1}$ differentiable at $x_{0}$, since the set of these points has full measure in $B_{1}$. Now, only two cases may occur.
Case 1: $\liminf _{k \rightarrow \infty}\left|P_{2^{-k}}^{x_{0}}\right| \leq \bar{C}_{1} K$. At our point $x_{0}$, we have

$$
\begin{aligned}
\left|D_{h}^{2} u\left(x_{0}\right)\right| & =\left|\lim _{k \rightarrow \infty} f_{B_{2-k}\left(x_{0}\right)} D_{h}^{2} u(y) d y\right|=\lim _{k \rightarrow \infty}\left|\left(P_{2^{-k}}^{x_{0}}+\frac{\left(\Delta_{H} u\right)_{B_{2-k}\left(x_{0}\right)}}{m} I_{m}\right)\right| \\
& \leq \liminf _{k \rightarrow \infty}\left(\left|P_{2^{-k}}^{x_{0}}\right|+\frac{1}{\sqrt{m}}\left|\left(\Delta_{H} u\right)_{B_{2-k}\left(x_{0}\right)}\right|\right) \\
& =\frac{1}{\sqrt{m}}\left|\Delta_{H} u\left(x_{0}\right)\right|+\liminf _{k \rightarrow \infty}\left|P_{2^{-k}}^{x_{0}}\right| \leq \frac{1}{\sqrt{m}}\|f\|_{L^{\infty}\left(B_{1}\right)}+\bar{C}_{1} K \\
& \leq\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\bar{C}_{1} K .
\end{aligned}
$$

Therefore

$$
\left|D_{h}^{2} u\left(x_{0}\right)\right| \leq\left(\bar{C}_{1} C_{4}+1\right)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

Case 2: $\liminf _{k \rightarrow \infty}\left|P_{2^{-k}}^{x_{0}}\right|>\bar{C}_{1} K$. Then the following integer is well-defined:

$$
k_{0}:=\min \left\{k \in \mathbb{N}: k \geq i_{0},\left|P_{2^{-j}}^{x_{0}}\right|>\bar{C}_{1} K \text { for all } j \geq k\right\}
$$

The positive integer $k_{0}$ possibly depends on $x_{0}$. We notice that from the definition of $k_{0}$, we have $\left|P_{2^{-k_{0}+1}}^{x_{0}}\right| \leq \bar{C}_{1} K$. The strict inequality $k_{0}>i_{0}$ follows by (4-19). In view of our choice of $i_{0}$, which satisfies (4-18) and then $i_{0}>3$, we can apply Lemma 3.8 with $\lambda_{1}=\frac{3}{4}$. Indeed, we have $B_{1 / 4}=B_{\lambda_{1} / 3}$ and

$$
2^{-k_{0}+1}<\min \left\{\frac{2}{3} \lambda_{1}, 1-\lambda_{1}\right\}=2^{-2}
$$

so Lemma 3.8 with $r_{1}=2^{-k_{0}}$ and $r_{2}=2^{-k_{0}+1}$ yields

$$
\begin{align*}
\left|P_{2^{-k_{0}}}^{x_{0}}\right| & \leq\left|P_{2^{-k_{0}+1}}^{x_{0}}\right|+C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \\
& \leq\left(\bar{C}_{1} C_{4}+C\right)\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) . \tag{4-20}
\end{align*}
$$

We consider the "rescaled function" defined in Lemma 4.5:

$$
\begin{equation*}
u_{0}(x):=\frac{u\left(x_{0} \delta_{2-k_{0}} x\right)-\ell^{x_{0}}\left(\delta_{2-k_{0}} x\right)-p_{c_{0} 2^{-k_{0}}}^{x_{0}}\left(\delta_{2-k_{0}} x\right)}{4^{-k_{0}}} \tag{4-21}
\end{equation*}
$$

This function coincides with $u_{2-k_{0}, x_{0}}$ of the same lemma. Now we set $f_{0}(x):=f\left(x_{0} \delta_{2-k_{0}} x\right)$, which is also defined on $B_{1}^{G}$. We can find a harmonic function $h_{0}$ such that

$$
v_{0}=2^{2 k_{0}} v\left(x_{0} \delta_{2-k_{0}} x\right)+h_{0}
$$

and $v_{0}$ satisfies the Dirichlet problem

$$
\left\{\begin{align*}
\Delta_{H} v_{0}=f_{0} & \text { in } B_{\sigma}^{G}  \tag{4-22}\\
v_{0}=u_{0} & \text { on } \partial B_{\sigma}^{G}
\end{align*}\right.
$$

with $0<\sigma<1$. Notice that $v_{0}$ is also twice $L^{1}$ differentiable at 0 , a consequence of the twice $L^{1}$ differentiability of $v$ at $x_{0}$. For the same reason, the twice $L^{1}$ differentiability of $u$ at $x_{0}$ gives the twice $L^{1}$ differentiability of $u_{0}$ at 0 . From Lemma 4.5 with $\lambda=\frac{1}{4}$, there exists $C_{\sigma}>0$ such that

$$
\begin{equation*}
\left\|D_{h}^{2} v_{0}\right\|_{L^{\infty}\left(B_{\sigma^{2}}^{G}\right)} \leq C_{\sigma}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tag{4-23}
\end{equation*}
$$

For the sequel, it is now important to remark that the difference

$$
\begin{equation*}
w_{0}:=v_{0}-u_{0} \tag{4-24}
\end{equation*}
$$

is twice $L^{1}$ differentiable at the origin. Then we know the existence of a polynomial

$$
R(x)=w_{0}(0)+\sum_{j=1}^{m} X_{j} w_{0}(0) x_{j}+\frac{1}{2} \sum_{i, j=1}^{m}\left(\left(X_{i} X_{j}+X_{j} X_{i}\right) w_{0}\right)(0) x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} X_{l} w_{0}(0) x_{l}
$$

such that we get

$$
\begin{equation*}
\frac{1}{r^{2}} f_{B_{\kappa r}}\left|w_{0}(z)-R(z)\right| d z \rightarrow 0 \tag{4-25}
\end{equation*}
$$

as $r \rightarrow 0^{+}$and for an arbitrary $\kappa>0$. The definition of $w_{0}$ immediately gives

$$
\left\{\begin{aligned}
\Delta_{H} w_{0} & =f_{0} \chi_{\Lambda_{2-k_{0}}\left(x_{0}\right)} & & \text { in } B_{\sigma}^{G} \\
w_{0} & =0 & & \text { on } \partial B_{\sigma}^{G}
\end{aligned}\right.
$$

Claim. For a fixed $0<\alpha<1$, there exist $l_{0} \geq 1$ and $C>0$, depending on $\alpha$ and on universal constants, such that for $\tau=2^{-l_{0}}$ and for every $k \in \mathbb{N} \backslash\{0\}$, there exist harmonic polynomials $q_{k}$ with the property

$$
\begin{equation*}
\left\|w_{0}-q_{k}\right\|_{L^{\infty}\left(B_{\tau^{k}}^{G}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{(2+\alpha)(k-1)} \tag{4-26}
\end{equation*}
$$

where the constants are independent of $x_{0}$.
To prove (4-26) by induction, we need first to establish the case $k=1$. Here we choose the null harmonic polynomial $q_{1}=0$. We consider the decomposition (4-24) and observe that standard $L^{\infty}$ estimates for $v_{0}$ are available, since it solves (4-22). Indeed, we may further decompose $v_{0}$ into the sum of $z_{0}=-f_{0} * \Gamma$ and of a harmonic function $h_{0}$ such that $\left.h_{0}\right|_{\partial B_{\sigma}^{G}}=u_{0}-z_{0}$. Then we apply the subquadratic growth estimate (4-11) of Remark 4.4 where we fix $\lambda=\frac{1}{4}$. This leads us to the estimate

$$
\left\|v_{0}\right\|_{L^{\infty}\left(B_{\sigma}\right)} \leq C_{1 \sigma}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

Then using again estimate (4-11), we obtain

$$
\begin{aligned}
\left\|w_{0}\right\|_{L^{\infty}\left(B_{\sigma}^{G}\right)} & \leq\left\|v_{0}\right\|_{L^{\infty}\left(B_{\left.B_{1}\right)}^{G}\right)}+\left\|u_{0}\right\|_{L^{\infty}\left(B_{r_{1}}^{G}\right)} \\
& \leq C_{2 \sigma}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) .
\end{aligned}
$$

Taking $\sigma=\tau=2^{-l_{0}}$, the estimate (4-26) is established for $k=1$. We may take $l_{0} \in \mathbb{N}$ possibly larger such that

$$
\begin{equation*}
\tau=2^{-l_{0}} \leq \frac{1}{2\left|B_{1}^{G}\right|^{1 / Q}} \tag{4-27}
\end{equation*}
$$

In view of Proposition 2.4, there exists a universal constant $c>0$ such that

$$
\begin{equation*}
\left\|D_{h}^{3} H\right\|_{L^{\infty}\left(B_{1 / 2}^{G}\right)} \leq c\|H\|_{L^{\infty}\left(B_{1}^{G}\right)} \tag{4-28}
\end{equation*}
$$

for any harmonic function $H$ on $B_{1}^{G}$. Now we assume the statement (4-26) is true for any fixed $k \geq 1$ and define

$$
w_{k}(x):=\frac{w_{0}\left(\delta_{\tau^{k}} x\right)-q_{k}\left(\delta_{\tau^{k}} x\right)}{\tau^{(2+\alpha)(k-1)}}
$$

on $\bar{B}_{1}^{G}$. We choose the harmonic function $h_{k}$ such that

$$
\left\{\begin{aligned}
\Delta_{H} h_{k}=0 & \text { in } B_{1}^{G} \\
h_{k}=w_{k} & \text { on } \partial B_{1}^{G} .
\end{aligned}\right.
$$

From the definition of $w_{k}$, we get

$$
\Delta_{H} w_{k}=\tau^{2-\alpha(k-1)} f\left(x_{0} \delta_{2-k_{0} \tau^{k}} \cdot\right) \chi_{\Lambda_{2^{-k}} \tau^{k}\left(x_{0}\right)}
$$

on $B_{1}^{G}$, and the induction assumption yields

$$
\begin{equation*}
\left\|w_{k}\right\|_{L^{\infty}\left(B_{1}^{G}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) . \tag{4-29}
\end{equation*}
$$

Clearly $w_{k}-h_{k}$ vanishes on $\partial B_{1}^{G}$. Taking into account our choice of $i_{0}$ such that $2^{-i_{0}} \leq r_{0}$, the decay estimate of the coincidence set (4-14) applies in particular for $\beta=4$ and for every $r \in\left(0,2^{-k_{0}}\right]$, that is,

$$
\begin{equation*}
\left|\Lambda_{r / 2}\left(x_{0}\right)\right| \leq \frac{\left|\Lambda_{r}\left(x_{0}\right)\right|}{2^{4 Q}} \tag{4-30}
\end{equation*}
$$

Arguing as before for $v_{0}$, we can decompose $w_{k}-h_{k}$ into the sum of a harmonic function and a convolution with the fundamental solution; therefore standard convolution estimates yield the first of the inequalities

$$
\begin{aligned}
\left\|w_{k}-h_{k}\right\|_{L^{\infty}\left(B_{1}^{G}\right)} & \leq C \| \tau^{2-\alpha(k-1)} f\left(x_{0} \delta_{\left.2^{-k_{0}-l_{0} k}\right)} \chi_{\Lambda_{2-k_{0}-l_{0} k}\left(x_{0}\right)} \|_{L^{Q}}{ }_{\left(B_{1}^{G}\right)}\right. \\
& \leq C \tau^{-\alpha(k-1)}\|f\|_{L^{\infty}\left(B_{1}\right)}\left|\Lambda_{2^{-k_{0}-l_{0} k}\left(x_{0}\right)}\right|^{1 / Q} \\
& \leq C 2^{\alpha l_{0}(k-1)}\|f\|_{L^{\infty}\left(B_{1}\right)} 2^{-4 l_{0} k}\left|\Lambda_{2^{-k_{0}}}\left(x_{0}\right)\right|^{1 / Q} \\
& \leq C\left|B_{1}^{G}\right|^{1 / Q}\|f\|_{L^{\infty}\left(B_{1}\right)} \tau^{k(4-\alpha)+\alpha} \\
& \leq \frac{1}{2} C\|f\|_{L^{\infty}\left(B_{1}\right)} \tau^{2+\alpha},
\end{aligned}
$$

where the third inequality is a consequence of (4-30) and the last inequality follows from (4-27). Combining the estimate (4-28) for harmonic functions, the maximum principle and our induction assumption as stated in (4-29), we get

$$
\begin{aligned}
\left\|D_{h}^{3} h_{k}\right\|_{L^{\infty}\left(B_{1 / 2}^{G}\right)} & \leq c\left\|h_{k}\right\|_{L^{\infty}\left(B_{1}^{G}\right)} \leq c\left\|w_{k}\right\|_{L^{\infty}\left(B_{1}^{G}\right)} \\
& \leq c C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
\end{aligned}
$$

Define $\bar{q}_{k}(x)$ as the second-order Taylor polynomial of $h_{k}$ at the origin. In particular, $\bar{q}_{k}$ is harmonic. The previous estimates joined with the application of the stratified Taylor inequality stated in [Folland and Stein 1982, Corollary 1.44 with $k=2$ and $x=0$ ] give

$$
\begin{aligned}
\left\|h_{k}-\bar{q}_{k}\right\|_{L^{\infty}\left(B_{\tau}^{G}\right)} & \leq C_{2}^{\prime} c C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{3} \\
& \leq \frac{1}{2} C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{2+\alpha}
\end{aligned}
$$

where we have chosen $l_{0}$ possibly larger, such that the conditions

$$
b^{3} \tau=b^{3} 2^{-l_{0}}<\frac{1}{2} \quad \text { and } \quad \tau=2^{-l_{0}} \leq\left(\frac{1}{2 c C_{2}^{\prime}}\right)^{1 /(1-\alpha)}
$$

also hold. The constants $b$ and $C_{2}^{\prime}$ are from [Folland and Stein 1982, Corollary 1.44 with $k=2$ and $x=0$ ] and this corollary is applied with the gauge distance $d_{G}$. We stress that $l_{0}$ does not depend on $k_{0}$ or $x_{0}$. This is very important for the final estimate of $D_{h}^{2} u\left(x_{0}\right)$. As a consequence, we obtain

$$
\begin{aligned}
\left\|w_{k}-\bar{q}_{k}\right\|_{L^{\infty}\left(B_{\tau}^{G}\right)} & \leq\left\|w_{k}-h_{k}\right\|_{L^{\infty}\left(B_{\tau}^{G}\right)}+\left\|h_{k}-\bar{q}_{k}\right\|_{L^{\infty}\left(B_{\tau}^{G}\right)} \\
& \leq \frac{1}{2} C\|f\|_{L^{\infty}\left(B_{1}\right)} \tau^{2+\alpha}+\frac{1}{2} C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{2+\alpha} \\
& \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{2+\alpha} .
\end{aligned}
$$

Taking into account the definition of $w_{k}$, we have proved that

$$
\left\|\frac{w_{0}\left(\delta_{\tau^{k}} \cdot\right)-q_{k}\left(\delta_{\tau^{k}} \cdot\right)}{\tau^{(2+\alpha)(k-1)}}-\bar{q}_{k}\right\|_{L^{\infty}\left(B_{\tau}^{G}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{2+\alpha}
$$

from which we infer

$$
\left\|w_{0}-q_{k}-\tau^{(2+\alpha)(k-1)} \bar{q}_{k}\left(\delta_{\tau^{-k}} \cdot\right)\right\|_{L^{\infty}\left(B_{\tau^{k+1}}^{G}\right)} \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{(2+\alpha) k}
$$

If we define the new polynomial

$$
q_{k+1}(x):=q_{k}(x)+\tau^{(2+\alpha)(k-1)} \bar{q}_{k}\left(\delta_{\tau^{-k}} x\right)
$$

then the induction step is proved and this concludes the proof of our claim. By the same previous argument, we have another universal constant $c^{\prime}>0$ such that

$$
\begin{align*}
\max \left\{\left\|h_{k}\right\|_{L^{\infty}\left(B_{1 / 2}^{G}\right)},\left\|\nabla_{h} h_{k}\right\|_{L^{\infty}\left(B_{1 / 2}^{G}\right)},\left\|D_{h}^{2} h_{k}\right\|_{L^{\infty}\left(B_{1 / 2}^{G}\right)}\right\} & \leq c^{\prime}\left\|w_{k}\right\|_{L^{\infty}\left(B_{1}^{G}\right)} \\
& \leq c^{\prime} C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tag{4-31}
\end{align*}
$$

We introduce the notation

$$
\begin{aligned}
& q_{k}(x)=a^{k}+\sum_{i=1}^{m} b_{i}^{k} x_{i}+\frac{1}{2} \sum_{i, j=1}^{m} c_{i j}^{k} x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} c_{l}^{k} x_{l}, \\
& \bar{q}_{k}(x)=\bar{a}^{k}+\sum_{i=1}^{m} \bar{b}_{i}^{k} x_{i}+\frac{1}{2} \sum_{i, j=1}^{m} \bar{c}_{i j}^{k} x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} \bar{c}_{l}^{k} x_{l}
\end{aligned}
$$

From the definition of $\bar{q}_{k}$ and taking into account the estimates (4-31), we get

$$
\begin{equation*}
\max _{i, j, l}\left\{\bar{a}^{k}, \bar{b}_{i}^{k}, \bar{c}_{i j}^{k}, \bar{c}_{l}^{k}\right\} \leq c^{\prime} C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tag{4-32}
\end{equation*}
$$

Consequently, differentiating the equality

$$
q_{k+1}(x)-q_{k}(x)=\tau^{(2+\alpha)(k-1)} \bar{q}_{k}\left(\delta_{\tau^{-k}} x\right)
$$

with the differential operators $X_{i}, X_{i} X_{j}$ for $i, j=1, \ldots, m$ and $X_{l}$ for $l=m+1, \ldots, m_{2}$, and evaluating all the equalities at the origin, we get

$$
\begin{aligned}
\left|a^{k+1}-a^{k}\right| & \leq c^{\prime} C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{(2+\alpha)(k-1)}, \\
\max _{1 \leq i \leq m}\left|b_{i}^{k+1}-b_{i}^{k}\right| & \leq c^{\prime} C \tau^{-1}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{(1+\alpha)(k-1)}, \\
\max _{1 \leq i, j \leq m}\left|c_{i j}^{k+1}-c_{i j}^{k}\right| & \leq c^{\prime} C \tau^{-2}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{\alpha(k-1)}, \\
\max _{m+1 \leq l \leq m_{2}}\left|c_{l}^{k+1}-c_{l}^{k}\right| & \leq c^{\prime} C \tau^{-2}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}{ }_{\left(B_{1}\right)}}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{\alpha(k-1)} .
\end{aligned}
$$

Representing any of these coefficients as $\gamma^{k}$, we notice that they are Cauchy sequences converging to some $\gamma$. In addition, for any of them we have

$$
\begin{equation*}
\left|\gamma^{k}-\gamma\right| \leq \frac{c^{\prime} C \tau^{-2}}{1-\tau^{\alpha}}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{(\alpha+l)(k-1)} \tag{4-33}
\end{equation*}
$$

In these estimates, we have set $l=0$ when $\gamma^{k}=c_{l}^{k}, c_{i j}^{k}, l=1$ for $\gamma^{k}=b_{i}^{k}$ and $l=2$ for $\gamma^{k}=a_{i}^{k}$. As a consequence, the polynomials $q_{k}$ uniformly converge on compact sets to a polynomial $\tilde{q}$ that has the form

$$
\tilde{q}(x)=\tilde{a}+\sum_{i=1}^{m} \tilde{b}_{i} x_{i}+\frac{1}{2} \sum_{i, j=1}^{m} \tilde{c}_{i j} x_{i} x_{j}+\sum_{l=m+1}^{m_{2}} \tilde{c}_{l} x_{l}
$$

Any coefficient $\gamma$ of $\tilde{q}$, can be written for instance as $\gamma^{2}+\gamma-\gamma^{2}$. By (4-33), we can find a universal estimate for $\gamma-\gamma^{2}$ that depends on $\alpha$. We also observe that the coefficients of $q_{2}$ are given by the formula $q_{2}=\bar{q}_{1} \circ \delta_{\tau^{-1}}$. The estimate (4-32) for $k=2$ and the fact that $\tau=2^{-l_{0}}$ can be universally fixed, independently of $x_{0}$, finally lead us to the estimate

$$
\begin{equation*}
\left|D_{h}^{2} \tilde{q}\right| \leq C_{\tau, \alpha}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tag{4-34}
\end{equation*}
$$

for a suitable geometric constant $C_{\tau, \alpha}>0$ depending on the constants of (4-33) and (4-32). From (4-33), defining

$$
\bar{C}_{\tau, \alpha, f, u}=\frac{c^{\prime} C \tau^{-2}\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)}{1-\tau^{\alpha}}
$$

we can establish the following quantitative estimate on small balls:

$$
\left.\begin{array}{rl}
\left\|q_{k}-\tilde{q}\right\|_{L^{\infty}\left(B_{\tau^{k+1}}^{G}\right)} \leq & \bar{C}_{\tau, \alpha, f, u}\left(\tau^{(\alpha+2)(k-1)}\right.
\end{array}+\tau^{(\alpha+1)(k-1)} \sum_{i=1}^{m}\left\|x_{i}\right\|_{L^{\infty}\left(B_{\tau^{k+1}}^{G}\right)}\right)
$$

where we have used the proper intrinsic homogeneity of all the monomials $x_{i}, x_{i} x_{j}$ and $x_{l}$, with $i, j=$ $1, \ldots, m$ and $l=m+1, \ldots, m_{2}$. We would like to prove that

$$
\lim _{r \rightarrow 0} \frac{1}{r^{2}} f_{B_{r r}^{G}}\left|w_{0}(z)-\tilde{q}(z)\right| d z=0
$$

Let us consider $r=\tau^{k}$ and then

$$
\begin{aligned}
\frac{1}{r^{2}} f_{B_{\tau r}^{G}}\left|w_{0}(z)-\tilde{q}(z)\right| d z & \leq \frac{1}{r^{2}} f_{B_{r r}^{G}}\left|w_{0}(z)-q_{k}(z)\right| d z+\frac{1}{r^{2}} f_{B_{\tau r}^{G}}\left|\tilde{q}(z)-q_{k}(z)\right| d z \\
& =\tau^{-2 k} f_{B_{\tau^{k+1}}^{G}}\left|w_{0}(z)-q_{k}(z)\right| d z+\tau^{-2 k} f_{B_{\tau^{k+1}}^{G}}\left|\tilde{q}(z)-q_{k}(z)\right| d z \\
& \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right) \tau^{\alpha k}+\tau^{-2 k}\left\|\tilde{q}-q_{k}\right\|_{L^{\infty}\left(B_{\tau^{k}}^{G}\right)}
\end{aligned}
$$

goes to zero as $k \rightarrow \infty$. If we choose $\kappa_{0}>0$ sufficiently small, then we have proved that

$$
\frac{1}{\tau^{2 k}} f_{B_{k_{0} \tau^{2 k}}}\left|w_{0}(z)-R(z)\right| d z \leq \frac{1}{\tau^{2 k}} f_{B_{\tau^{k}}^{G}}\left|w_{0}(z)-R(z)\right| d z \rightarrow 0
$$

By the uniqueness of the second-order polynomial $R$ satisfying (4-25) with $\kappa=\kappa_{0}$, we get $\tilde{q}=R$. Taking into account (4-23) with $\sigma=\tau$ and (4-34) with $\alpha=\frac{1}{2}$, we obtain a new constant $C>0$ such that

$$
\left|D_{h}^{2} u_{0}(0)\right| \leq\left|D_{h}^{2} v_{0}(0)\right|+\left|D_{h}^{2} w_{0}(0)\right| \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

As a consequence, since $k_{0}>i_{0}$ and $i_{0}$ satisfies (4-18) we can apply Lemma 3.8 with $r_{1}=2^{-k_{0}}$ and $r_{2}=c_{0} 2^{-k_{0}}$, so that taking into account the estimate (4-20) and the definition (4-21) of $u_{0}$, we finally obtain a possibly larger constant, which we still denote by $C>0$, such that

$$
\left|D_{h}^{2} u\left(x_{0}\right)\right| \leq\left|D_{h}^{2} u_{0}(0)\right|+\left|P_{c_{0} 2^{-k_{0}}}^{x_{0}}\right| \leq C\left(\left\|D_{h}^{2}(f * \Gamma)\right\|_{L^{\infty}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

concluding the proof.

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