

Deep Learning theory - Lecture 3

Q: How about higher dimensions? $d \gg 1$

Idea: We would like to approximate with sums.

$$\prod_e \mathbb{1}(x_e \in A_e) \quad A_e = \bigcup_{j=1}^d [b_{e,j}, b'_{e,j})$$

However, this cannot be done (at least directly) with shallow nets.

Consider $\sigma(z) = \cos(z)$. then Or can it?

$$\begin{aligned} \sigma(z) \cdot \sigma(y) &= \cos(z) \cos(y) \\ &= \cos(z+y) + \cos(z-y) \\ &= \sigma(z+y) + \sigma(z-y) \end{aligned}$$

So, at least in principle, using the above property of cosines and the Fourier approximation of step functions:

$$\begin{aligned} g(x) &\approx \sum_j \alpha_j \prod_e \mathbb{1}(x_e \in [b_{j,e}, b'_{j,e})) \approx \sum_j \alpha_j \prod_e \sum_k \beta_k \cos(\gamma_k x_e) \\ \text{algebra} &\rightarrow \approx \sum_j \alpha_j \sum_k \beta_k \prod_e \cos(\gamma_k x_e) \approx \sum_j \alpha_j \sum_k \beta \sum_m \delta_m \cos(\sum_e \gamma'_e x_e) \end{aligned}$$

$$\text{expressivity} \approx \sum_{\delta} \alpha_{\delta} \sum_{\alpha} \beta_{\alpha} \sum_{\omega} \delta_{\omega} \sum_{\eta} \eta_{\eta} \mathbb{1}[\eta'_{\omega} \cdot x \geq b_{\omega}]$$

In practice, this is painful, but the heavy lifting was done for us:

Thm 2.5 (Stone-Weierstrass): Let $\mathcal{F} \subseteq C(X)$ for compact $X \subseteq \mathbb{R}^d$ satisfy:

a) for every $x \in X$, there exists $f \in \mathcal{F}$ such that $f(x) \neq 0$

b) for every pair $x, x' \in X$ with $x \neq x'$ there exists $f \in \mathcal{F}$ with

$$f(x) \neq f(x') \quad (\mathcal{F} \text{ separates points})$$

c) \mathcal{F} is closed under pointwise multiplication (\mathcal{F} is an algebra)

then \mathcal{F} is a universal approximator.

Lemma 2.6 \mathcal{F}_{\cos} is universal

Pf: a) each $f \in \mathcal{F}_{\cos}$ is continuous (finite sum of cont. functions)

b) $\cos(0 \cdot x) = 1 \quad \forall x \in X$

c) $x \neq x' \Rightarrow f(z) = \cos\left(\frac{(z-x') \cdot (x-x')}{\|x-x'\|^2}\right)$ satisfies $\begin{cases} f(x') = 1 \\ f(x) = 0 \end{cases}$

d) already checked. \square

Thm 2.7 Suppose $\sigma \in C(\mathbb{R})$ is sigmoidal: $\begin{cases} \lim_{z \rightarrow -\infty} \sigma(z) = 0 \\ \lim_{z \rightarrow \infty} \sigma(z) = 1 \end{cases}$
then \mathcal{F}_{σ} is universal.

Also, $\mathcal{F}_{\text{ReLU}}$ is universal

Pf (sketch): By Lemma 2.7 we have there exists $n \in \mathbb{N}$,

$$h_n(x) = \sum_{j=1}^n \tilde{a}_j \cos(\tilde{\omega}_j \cdot x + \tilde{b}_j) \in \overline{\mathcal{F}}_{\cos}$$

$$\text{with } \|h - g\|_{\infty} \leq \frac{\varepsilon}{2}$$

Then, since $h_{n,j}(x) = \tilde{a}_j \cos(\tilde{\omega}_j \cdot x + \tilde{b}_j) \in C(X)$, by exercise we have $\exists f_{n,j} \in \mathcal{F}_{\text{sigmoid}} : \|f_{n,j} - h_{n,j}\| \leq \frac{\varepsilon}{2n}$

$$\implies \text{for } f(x) = \sum_j f_{n,j}(x) \in \mathcal{F}_{\text{sigmoid}}$$

$$\|f_n - g\|_{\infty} \leq \|f_n - h_n\| + \|h_n - g\| \leq \sum_{j=1}^n \frac{\varepsilon}{2n} + \frac{\varepsilon}{2} \leq \varepsilon. \quad \square$$

Note: the algebra condition does not hold for polynomials of bounded degree. In fact.

Thm (Leshno, 1993): $\overline{\mathcal{F}}_{\sigma}$ is universal iff $\sigma \in C(\mathbb{R})$ is not a polynomial

Multilayer neural networks

Def: Let $L \in \mathbb{N}$. A fully connected feedforward neural network of widths $(n_1, \dots, n_L) \in \mathbb{N}^L$ is a function of the form

$$f_\theta(x) = \sigma_{L+1}(z^{L+1}(x))$$

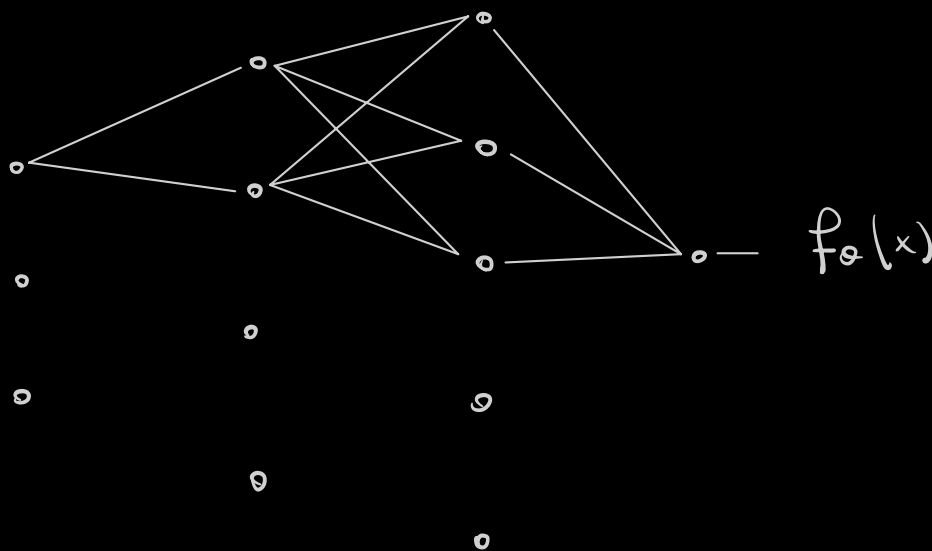
where the preactivations are given by.

$$z_d^e(x) = \alpha_{e-1} \sum_{k=1}^{n_{e-1}} w_{dk}^e \sigma_e(z_k^{e-1}(x)) + b_d^e \quad d \in \{1, \dots, n_e\} \\ e \in \{2, \dots, L+1\}$$

$$z_d^1(x) = \sum_{k=1}^d w_{dk}^1 x_k + b_d^1$$

for a choice of $\theta = \left((w_{dk}^e)_{d=1, k=1}^{n_e, n_{e-1}}, (b_d^e)_{d=1}^{n_e} \right)_{e=1}^{L+1} \in \mathbb{R}^{\sum_{e=1}^L (n_{e-1}+1)n_e}$

Note: This network can be represented as a graph:



- Letting σ_e act componentwise we can write

$$f_\sigma(x) = \sigma_{L+1}(w_{L+1} \sigma_L(\dots w_2 \sigma_1(w_1 x + b_1) + b_2 \dots + b_{L+1}))$$

$$\text{for } w^e \in \mathbb{R}^{n_e \times n_{e-1}}, b^e \in \mathbb{R}^{n_e}$$

- σ_i are the same as in the single layer setting.

Lemma: Deep neural networks with ReLU activation are universal approximators.

Proof: since for $z \in \mathbb{R}$ $\mathbb{1}(z) = -(-z)_+ + z_+ = -1 \cdot \sigma((-1)z) + 1 \cdot \sigma(1 \cdot z)$
we can construct a network of depth L combining $L-1$ layers of $\mathbb{1}$ with the network from Thm 2.7.

Q: Why using deep neural networks?

Thm (Telgarsky 2015): for any $L \geq 2$ there exists a depth $2L^2 + 4$ ReLU NN with $3L^2 + 6$ nodes f_L such that for any depth L NN with $\leq 2^L$ nodes we have $\|g - f_L\|_1 \geq \frac{1}{32}$.

Neural network training.

For a given dataset D_n , we aim to minimize the empirical risk

$$\hat{R}(\theta) = \hat{R}(f_\theta) = \frac{1}{n} \sum_{j=1}^n \ell(f_\theta(x_j), y_j) \quad (\text{training error})$$

For an algorithm A , we aim to characterize the optimization error

$$\hat{R}(A(D_n)) - \inf_{f \in \mathcal{F}} \hat{R}(f)$$

While in some cases this can be done explicitly (e.g. linear regression) in general the problem of finding the minimum of a function \hat{R} is hard.

One method to (hopefully) solve this problem: move sequentially in the direction (in Θ) of steepest descent of \mathcal{R} by updating

$$\theta \leftarrow \theta - \gamma D_\theta \mathcal{R}(\theta)$$



for a small timestep parameter γ . This method is called gradient descent:

the update reads:
$$\underline{\theta_{k+1} = \theta_k - \gamma_k D_\theta \mathcal{R}(\theta_k)}$$

Note: Why using this and not trying to solve $D_\theta \mathcal{R}(\theta) = 0$?

Computation of $D_\theta \mathcal{R}$ is cheap: consider

$$D_{w_{l+1}^1} f(\theta) = \sigma'_{l+1}(z_{l+1}(x)) W^l \sigma'_l(z_l(x)) \dots \sigma'_1(z_1(x)) \cdot x$$



In the above update, provided that we know σ'_e and z_e we are computing a complicated derivative by taking a product of known numbers (z_e were evaluated to find $f_\theta(x)$) so that

$$\theta_{k+1} = \theta_k - \gamma_k D_\theta \hat{R}(\theta_k)$$

$$= \theta_k - \gamma_k \frac{1}{n} \sum_{j=1}^n \underbrace{D_\theta f_{\theta_k}(x_j)}_{\text{"easy"}} \underbrace{D_f \ell(f_{\theta_k}(x_j), y_j)}_{\text{"easy": just evaluate } f_{\theta_k}}$$

To study the dynamics of θ_k we write formally

$$\theta_{k+1} = \theta_k - \gamma D_\theta R(\theta_k) \rightarrow \frac{\theta_{k+1} - \theta_k}{\gamma} = -D_\theta R(\theta_k)$$

Based on the above, one expects that $\theta_k \approx \bar{\theta}_{k\gamma}$ where $\bar{\theta}: \mathbb{R}_+ \rightarrow \Theta$ solves

$$\begin{cases} \frac{d}{dt} \bar{\theta}_t = -D_\theta R(\bar{\theta}_t) \\ \bar{\theta}_0 = \theta_0 \end{cases} \quad (\text{gradient flow})$$

Lemma: Let $D_\theta R$ be Lipschitz. For every $T > 0$ there exists $C > 0$ s.t

$$\|\bar{\theta}_{k\gamma} - \theta_k\| \leq C\gamma \quad \forall k \in \{0, \dots, \lfloor \frac{T}{\gamma} \rfloor\}$$

Proof: $\bar{\theta}_{t+\gamma} = \bar{\theta}_t - \gamma D_\theta R(\bar{\theta}_t) + C\gamma^2$

$$e_{k+1} = \|\bar{\theta}_{(k+1)\gamma} - \theta_{k+1}\| = \|\bar{\theta}_{k\gamma} - \gamma D_\theta R(\bar{\theta}_{k\gamma}) - \theta_k + \gamma D_\theta R(\theta_k)\| + C\gamma^2$$

$$\leq (1 + \gamma\lambda) e_k + C\gamma$$

$$\Rightarrow e_{R+1} = C\delta^2 \sum_{j=1}^R (1+\lambda\delta)^j = \frac{C\delta^2}{\lambda\delta} ((1+\lambda\delta)^{R+1} - 1) \leq \frac{C\delta}{\lambda} (e^{\lambda\delta(R+1)} - 1) \leq C'\delta \quad \square$$

This problem simplifies when \hat{R} is convex and has Lipschitz derivative.

Def: $\hat{R}(\theta)$ is λ strongly convex if

$$\hat{R}(\theta') \geq \hat{R}(\theta) + \langle D_{\theta} \hat{R}(\theta), \theta' - \theta \rangle + \frac{\lambda}{2} \|\theta' - \theta\|^2 \quad \text{for any } \theta, \theta' \in \Theta$$

$$\Rightarrow \hat{R}(\theta') \geq \hat{R}(\theta) + \langle D_{\theta} \hat{R}(\theta), \theta - \theta' \rangle + \frac{\lambda}{2} \|\theta - \theta'\|^2$$

adding the two inequalities we have

$$\langle D_{\theta} \hat{R}(\theta') - D_{\theta} \hat{R}(\theta), \theta' - \theta \rangle \geq \lambda \|\theta - \theta'\|^2$$

Thm: Let $R(\theta)$ be λ -convex, then there exists a unique θ^* and

$$\|\bar{\theta}_t - \theta_*\|^2 \leq \|\bar{\theta}_0 - \theta_*\|^2 e^{-2\lambda t}$$

Proof: $\frac{d}{dt} \frac{1}{2} \|\bar{\theta}_t - \theta_*\|^2 = \langle \bar{\theta}_t - \theta_*, \frac{d}{dt} \bar{\theta}_t \rangle$

$$= - \langle \bar{\theta}_t - \theta_*, D_{\bar{\theta}} R(\bar{\theta}_t) - D_{\bar{\theta}} R(\theta_*) \rangle$$

$$\leq -\lambda \|\bar{\theta}_t - \theta_*\|^2$$

→ Grönewall