

Deep Learning Theory - Lecture 3

Q: how about higher dimensions? $d > 1$

Idea: We would like to approximate with sums.

$$\prod_e \prod_{x \in A_e} (x \in A_e) \quad A_e = \sum_{j=1}^d [b_{e,j}, b_{e,j}^T]$$

However, this cannot be done (at least directly) with shallow nets.

Consider $\sigma(z) = \cos(z)$. Then Q: can it?

$$\begin{aligned} \sigma(z) \cdot \sigma(y) &= \cos(z) \cos(y) \\ &= \cos(z+y) + \cos(z-y) \\ &= \sigma(z+y) + \sigma(z-y) \end{aligned}$$

So, at least in principle, using the above property of cosines and the Fourier approximation of step functions:

$$g(x) \approx \sum_j \alpha_j \prod_e \prod_{x \in [b_{j,e}, b_{j,e}^T]} \cos(\delta_{j,e}^T x_e) \approx \sum_j \alpha_j \prod_e \sum_k \beta_{e,k} \cos(\delta_{j,e}^T x_e)$$

algebra $\approx \sum_j \alpha_j \sum_e \beta_{e,e} \prod_e \cos(\delta_{j,e}^T x_e) \approx \sum_j \alpha_j \sum_e \beta_e \sum_m \delta_{e,m} \cos(\sum_j \delta_{j,e}^T x_e)$

$$\text{explosivity} \approx \sum_j \alpha_j \sum_a \beta_a \sum \delta_m \sum n_m \mathbb{1} [y_m^j \cdot x \leq b_m]$$

In practice, this is painful, but the heavy lifting was done for us.

Theorem 2.5 (Stone-Weierstrass): Let $\bar{F} \subseteq C(X)$ for compact $X \subseteq \mathbb{R}^d$ satisfy.

a) for every $x \in X$, there exists $f \in \bar{F}$ such that $f(x) \neq 0$

b) for every pair $x, x' \in X$ with $x \neq x'$ there exists $f \in \bar{F}$ with

$$f(x) \neq f(x') \quad (\bar{F} \text{ separates points})$$

c) \bar{F} is closed under pointwise multiplication (\bar{F} is an algebra)

then \bar{F} is an universal approximator.

Lemma 2.6 \bar{F}_{\cos} is universal

Pf: a) each $f \in \bar{F}_{\cos}$ is continuous (finite sum of cont. functions)

$$b) \cos(0 \cdot x) = 1 \quad \forall x \in X$$

c) $x \neq x' \Rightarrow f(x) = \cos\left(\frac{(x-x') \cdot (x-x')}{\|x-x'\|^2}\right)$ satisfies $\begin{cases} f(x') = 1 \\ f(x) = 0 \end{cases}$

d) already checked. \square

Theorem 2.7 Suppose $\sigma \in C(\mathbb{R})$ is sigmoidal: $\begin{cases} \lim_{z \rightarrow -\infty} \sigma(z) = 0 \\ \lim_{z \rightarrow \infty} \sigma(z) = 1 \end{cases}$

then \bar{F}_σ is universal

Also, \bar{F}_{ReLU} is universal

PF (sketch): By Lemma 2.7 we have there exists $n \in \mathbb{N}$,

$$h_n(x) = \sum_{j=1}^n \tilde{a}_j \cos(\tilde{\omega}_j \cdot x + \tilde{b}_j) \in \mathcal{F}_{\cos}$$

$$\text{with } \|h_n - g\|_\infty \leq \frac{\varepsilon}{2}$$

Then, since $h_{n,\delta}(x) = \tilde{a}_\delta \cos(\tilde{\omega}_\delta \cdot x + \tilde{b}_\delta) \in C(X)$, by

exercise we have $\exists f_{n,\delta} \in \mathcal{F}_{\text{sigmoid}} : \|f_\delta - h_{n,\delta}\| \leq \frac{\varepsilon}{2^n}$

$$\Rightarrow \text{for } f(x) = \sum_{\delta=1}^n f_{n,\delta}(x) \in \mathcal{F}_{\text{sigmoid}}$$

$$\|f_n - g\|_\infty \leq \|f_n - h_n\| + \|h_n - g\| \leq \sum_{j=1}^n \frac{\varepsilon}{2^n} + \frac{\varepsilon}{2} \leq \varepsilon. \quad \square$$

Note: the algebra condition does not hold for polynomials of bounded degree. In fact.

Theorem (Deshnoe, 1993): \mathcal{F}_σ is universal iff $\sigma \in C(X)$ is not a polynomial

Multi-layer neural networks

Def: Let $L \in \mathbb{N}$. A fully connected feedforward neural network of widths $(u_1, \dots, u_L) \in \mathbb{N}^L$ is a function of the form

$$f_\theta(x) = \sigma_{L+1}(z^{L+1}(x))$$

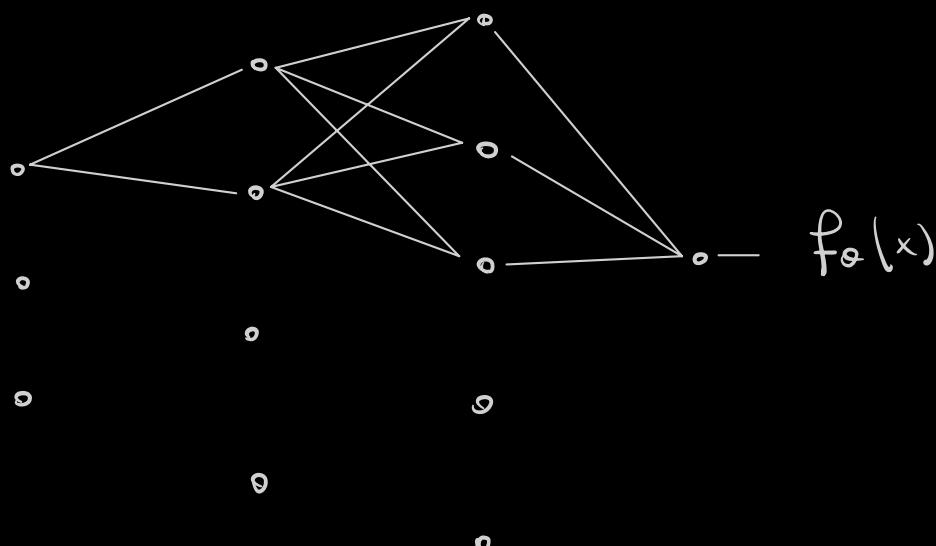
where the preactivations are given by.

$$z_j^e(x) = \alpha_{e-1} \sum_{k=1}^{u_{e-1}} w_{jk}^e \sigma_e(z_{k-1}^{e-1}(x)) + b_j^e \quad j \in \{1, \dots, u_e\}$$
$$e \in \{2, \dots, L+1\}$$

$$z_j^1(x) = \sum_{k=1}^d w_{jk}^1 x_k + b_j^1$$

$$\text{for a choice of } \theta = \left(\left(w_{jk}^e \right)_{j=1, k=1}^{u_e, u_{e-1}}, \left(b_j^e \right)_{j=1}^{u_e} \right)_{e=1}^{L+1} \in \mathbb{R}^{\sum_{e=1}^L (u_{e-1} + 1) u_e}$$

Note: This network can be represented as a graph.



- Letting σ_e act componentwise we can write

$$f_\theta(x) = \sigma_{L+1}(w_{L+1}\sigma_L(\dots w_2\sigma_1(w_1x + b_1) + b_2 \dots + b_{L+1}))$$

for $w^e \in \mathbb{R}^{n_e \times n_{e-1}}$, $b^e \in \mathbb{R}^{n_e}$

- σ_i are the same as in the single layer setting.

Lemma: Deep neural networks with ReLU activation are universal approximators.

Proof: since for $z \in \mathbb{R}$ $\mathbb{1}(z) = -(-z)_+ + z_+ = -1\sigma((-1)z)_+ + 1\cdot\sigma(1\cdot z)_+$ we can construct a network of depth L containing $L-1$ layers of $\mathbb{1}$ with the network from Thm 2.7.

Q: Why using deep neural networks?

Thm (Telgarsky 2015): for any $L \geq 2$ there exists a depth $2L^2+4$ ReLU NN with $3L^2+6$ nodes f_L such that for any depth L NN with $\leq 2^L$ nodes we have $\|g - f_L\|_1 \geq \frac{1}{32}$.

Neural network training

For a given dataset D_n , we aim to minimize the empirical risk

$$\hat{R}(\theta) = \hat{R}(f_\theta) = \frac{1}{n} \sum_{j=1}^n e(f_\theta(x_j), y_j) \quad (\text{training error})$$

For an algorithm \mathcal{A} , we aim to characterize the optimization error

$$\hat{R}(\mathcal{A}(D_n)) - \inf_{f \in \mathcal{F}} \hat{R}(f)$$

While in some cases this can be done explicitly (e.g. linear regression) in general the problem of finding the minimum of a function \hat{R} is hard.

One method to (hopefully) solve this problem: move sequentially in the direction (in Θ) of steepest descent of \hat{R} by updating

$$\theta \leftarrow \theta - \gamma D_\theta \hat{R}(\theta)$$



for a small timestep parameter γ . This method is called gradient descent:

the update reads:

$$\theta_{k+1} = \theta_k - \gamma_k D_\theta \hat{R}(\theta_k)$$

Note: Why using this and not trying to solve $D_\theta \hat{R}(\theta) = 0$?

Computation of $D_\theta \hat{R}$ is cheap: consider

$$D_{w_{11}^1} f(\theta) = \sigma_{L+1}^{-1}(z_{L+1}(x)) W^L \sigma_L^{-1}(z_L(x)) \dots \sigma_1^{-1}(z_1(x)) \cdot x$$

In the above update, provided that we know σ'_ϵ and τ_ϵ
we are computing a complicated derivative by taking a
product of known numbers (τ_ϵ were evaluated to find $f_\epsilon(x)$)
so that

$$\begin{aligned}\sigma_{\epsilon+1} &= \sigma_\epsilon - \gamma_\epsilon D_\sigma \hat{R}(\sigma_\epsilon) \\ &= \sigma_\epsilon - \gamma_\epsilon \frac{1}{n} \sum_{j=1}^n \underbrace{D_\sigma f_{\sigma_\epsilon}(x_j)}_{\text{"easy"}} \underbrace{D_f e(f_{\sigma_\epsilon}(x_j), y_j)}_{\text{"easy": just evaluate } f_{\sigma_\epsilon}}\end{aligned}$$

To study the dynamics of σ_ϵ we write formally

$$\sigma_{\epsilon+1} = \sigma_\epsilon - \gamma D_\sigma R(\sigma_\epsilon) \rightarrow \frac{\sigma_{\epsilon+1} - \sigma_\epsilon}{\gamma} = - D_\sigma R(\sigma_\epsilon)$$

Based on the above, one expects that $\sigma_\epsilon \approx \bar{\sigma}_{\epsilon, \gamma}$ where $\bar{\sigma}: \mathbb{R}_+ \rightarrow \Theta$
solves

$$\begin{cases} \frac{d}{dt} \bar{\sigma}_t = - D_\sigma R(\bar{\sigma}_t) \\ \bar{\sigma}_0 = \sigma_0 \end{cases} \quad (\text{gradient flow})$$

Lemma: Let $D_\sigma R$ be Lipschitz. For every $T > 0$ there exists $C > 0$ s.t

$$\|\bar{\sigma}_{\epsilon, \gamma} - \sigma_\epsilon\| \leq C \gamma. \quad \forall k \in \{0, \dots, \lfloor \frac{T}{\gamma} \rfloor\}$$

Proof: $\bar{\sigma}_{\epsilon, \gamma} = \bar{\sigma}_\epsilon - \gamma D_\sigma R(\bar{\sigma}_\epsilon) + C \gamma^2$

$$e_{\epsilon+1} = \|\bar{\sigma}_{(\epsilon+1)\gamma} - \sigma_{\epsilon+1}\| = \|\bar{\sigma}_{\epsilon\gamma} - \gamma D_\sigma R(\bar{\sigma}_{\epsilon\gamma}) - \sigma_\epsilon + \gamma D_\sigma R(\sigma_\epsilon)\| + C \gamma^2$$

$$\leq (1 + \gamma \lambda) e_\epsilon + C \gamma$$

$$\Rightarrow e_{k+1} = C \delta^2 \sum_{j=1}^k (1 + \lambda \delta^j)^d = \frac{C \delta^2}{\lambda \delta} \left((1 + \lambda \delta)^{k+1} - 1 \right) \leq \frac{C \delta}{\lambda} (e^{\lambda \delta^{k+1}} - 1) \leq C' \delta$$

□

This problem simplifies when \hat{R} is convex and has Lipschitz derivative.

Def. $\hat{R}(\theta)$ is λ strongly convex if

$$\hat{R}(\theta') \geq \hat{R}(\theta) + \langle D_\theta \hat{R}(\theta), \theta' - \theta \rangle + \frac{\lambda}{2} \|\theta' - \theta\|^2 \quad \text{for any } \theta, \theta' \in \Theta$$

$$\Rightarrow \hat{R}(\theta') \geq \hat{R}(\theta) + \langle D_\theta \hat{R}(\theta), \theta - \theta' \rangle + \frac{\lambda}{2} \|\theta - \theta'\|^2$$

adding the two inequalities we have

$$\langle D_\theta \hat{R}(\theta') - D_\theta \hat{R}(\theta), \theta' - \theta \rangle \geq \lambda \|\theta - \theta'\|^2$$

Thm. Let $R(\theta)$ be λ -convex, then there exists a unique θ^* and

$$\|\bar{\theta}_t - \theta_*\|^2 \leq \|\bar{\theta}_0 - \theta_*\|^2 e^{-2\lambda t}$$

$$\begin{aligned} \text{Proof: } \frac{d}{dt} \frac{1}{2} \|\bar{\theta}_t - \theta_*\|^2 &= \langle \bar{\theta}_t - \theta_*, \frac{d}{dt} \bar{\theta}_t \rangle \\ &= - \langle \bar{\theta}_t - \theta_*, D_\theta R(\bar{\theta}_t) - D_\theta R(\theta_*) \rangle \\ &\leq -\lambda \|\bar{\theta}_t - \theta_*\|^2 \end{aligned}$$

→ Grönwall