

Lezione del 15/10/2013

Sottospazio vettoriale: è un sottogruppo rispetto alla somma, e inoltre se  $\underline{v} \in W \Rightarrow \alpha \underline{v} \in W, \forall \alpha \in K$

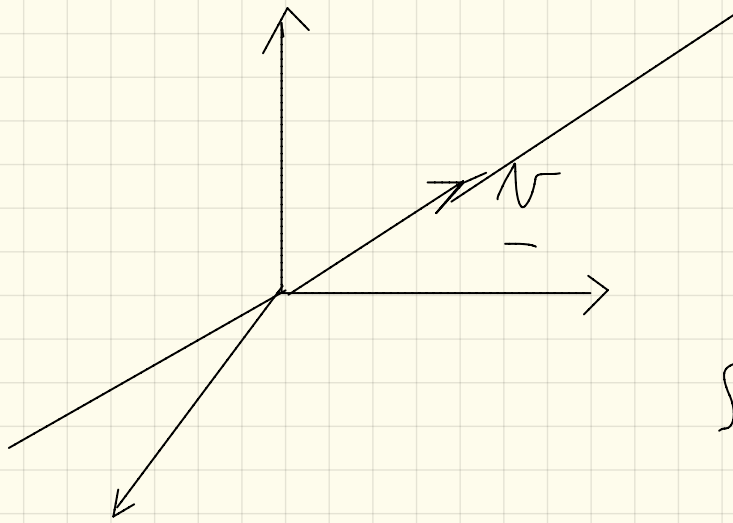
Def. Un'espressione del tipo

$$\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2 + \dots + \alpha_n \underline{v}_n$$

dove i  $\underline{v}_i \in V$  e gli  $\alpha_i \in K$  si chiama una combinazione lineare

$\alpha \underline{v}_1$  comb. lineare di 1 solo vett.

$\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2$  2 vettori



$$A = \{ \underline{v} \}$$

$$\text{Span}(A) = \left\{ \alpha \underline{v} \mid \alpha \in K \right\}$$

$$\text{Span}(\{ \underline{0} \}) = \{ \underline{0} \}$$

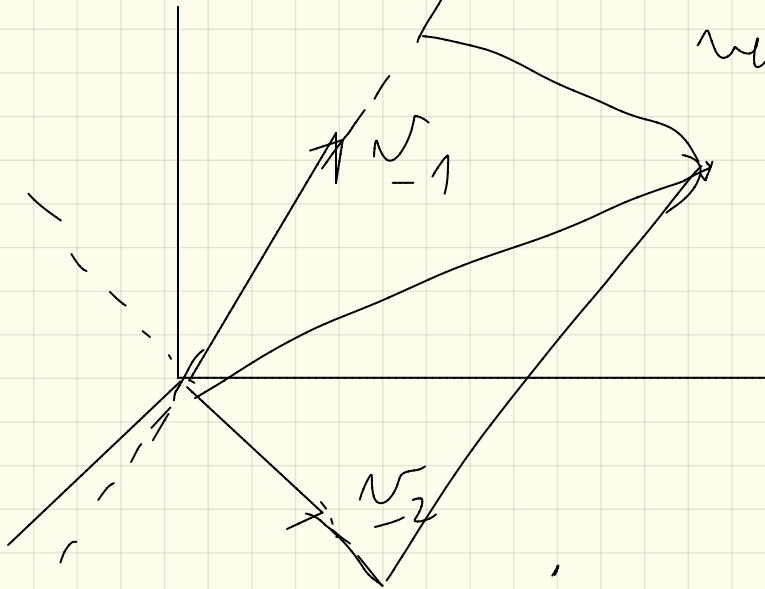
Notation Defo  $A \subset V$  definition

$$\text{Span}(A) = \left\{ \underline{v} \in V \mid \exists \underline{v}_1, \dots, \underline{v}_n \in A \right. \\ \left. \text{e } \alpha_1, \dots, \alpha_n \in K \text{ t.c. } \underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n \right\}$$

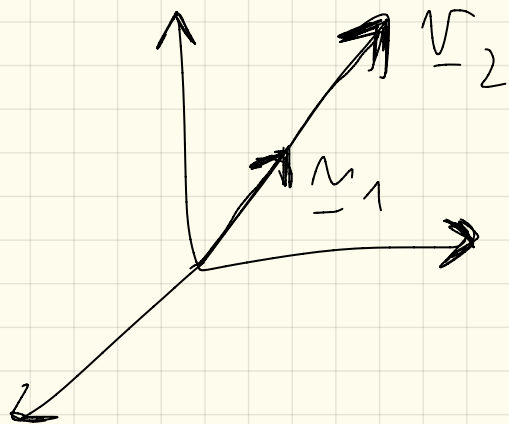
$$\text{Span}\{\underline{v}_1, \underline{v}_2\}$$

Se  $\underline{v}_1$  e  $\underline{v}_2$  non allineati

$\{\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2\}$  è il piano che  
contiene i due  
vettori.



Si  $\underline{v}_1, \underline{v}_2$  sono aliniati



$\{ \alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2 \}$   
retta che contiene  
 $\underline{v}_1$  e  $\underline{v}_2$

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$A \subset V$  ,  $\underline{0} \notin A$  ,

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$$\text{Span}(A \cup \{\underline{0}\}) = \text{Span}(A)$$

$\cup$   
 $\cup$

Eser  $A \subset B \subset V \implies$

$$\underline{\text{Span}(A) \subset \text{Span}(B)}$$

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Es'è  $\underline{v} \in \text{Span}(A)$  per def.

$\exists \underline{v}_1, \dots, \underline{v}_n \in A$ ,  $\alpha_1, \dots, \alpha_n \in \mathbb{K}$  t.c.

$$\underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n$$

Esicome  $\underline{v}_1, \dots, \underline{v}_n \in B$   $\uparrow$  è unbr. lin di  
notti di  $B$  e quindi  $\underline{v} \in \text{Span}(B)$

Dimostriamo che  $\text{Span}(A \cup \{0\}) \subseteq \text{Span}(A)$

Sia  $\underline{v} \in \text{Span}(A \cup \{0\})$ . Per def.  $\exists$

$\underline{v}_1, \dots, \underline{v}_n \in A \cup \{0\}$  e  $\alpha_1, \dots, \alpha_n \in K$

t.c. 
$$\underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n$$

Si osserva  $\underline{v}_i = \underline{0}$  ha limite

superiore ad es. che  $\underline{v}_m = \underline{0}$

$$\underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_{m-1} \underline{v}_{m-1} + \alpha_m \cdot \underline{0}$$

$$\alpha \underline{0} = \underline{0} \quad \forall \alpha \in K.$$

$$\begin{aligned} \underline{v} &= \alpha_1 \underline{v}_1 + \dots + \alpha_{n-1} \underline{v}_{n-1} + \underline{0} = \\ &= \alpha_1 \underline{v}_1 + \dots + \alpha_{n-1} \underline{v}_{n-1} \end{aligned}$$

hence  $\underline{v}_1, \dots, \underline{v}_{n-1} \in A$

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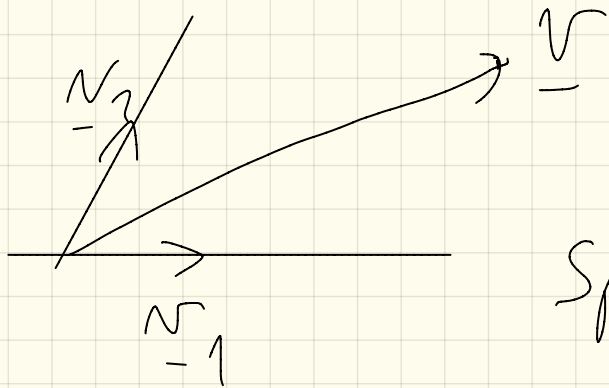
oss  $\text{Span}(A)$  è un sottosp. vett. di  $V$ .

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$$\begin{matrix} v_1, v_2 \in \text{Span}(A) \Rightarrow & d_1 v_1 + d_2 v_2 \in \\ -1, -2 & \text{Span}(A) \\ & \forall d_1, d_2 \in \mathbb{K} \end{matrix}$$

↑  
le  
di  
inestere

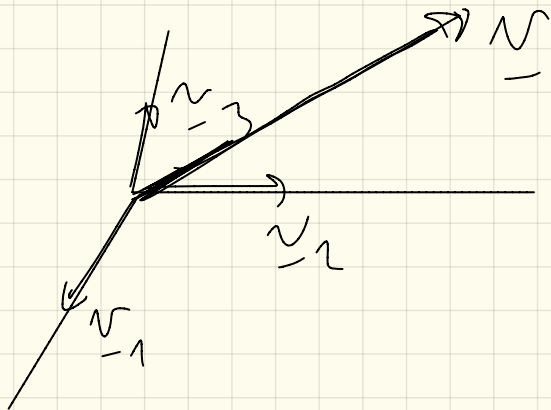
tutte le possibili combinazioni lineari finite  
di vettori di  $A$ , in particolare quelle  
di 2 vettori



$$\underline{v} = x \underline{v}_1 + y \underline{v}_2$$

$$\text{Span}(\{\underline{v}_1, \underline{v}_2\}) = V_2$$

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$$\underline{v} = x \underline{v}_1 + y \underline{v}_2 + z \underline{v}_3$$

$$\text{Span}(\{\underline{v}_1, \underline{v}_2, \underline{v}_3\}) = V_3$$

1 idea  $\{v_1, \dots, v_n\}$  che possa essere  
preso come riferimento per introdurre delle coordinate  
che soddisfano

$$\text{Span}(\{v_1, \dots, v_n\}) = V$$

cioè ogni  $v = x_1 v_1 + \dots + x_n v_n$   
 $x_i \in K$

Se  $A \subset V$  è t.c.  $\text{Span} A = V$

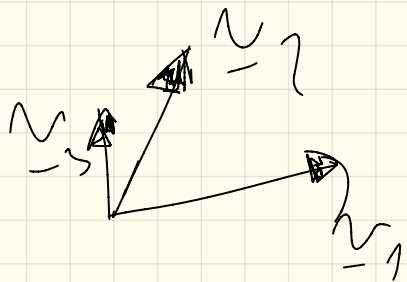
allora  $A$  si chiama insieme di generatori

Per l'es. visto prima:

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es Se  $\text{Span}(A) = V \Rightarrow$   
 $\text{Span}(B) = V$  se  $A \subset B$

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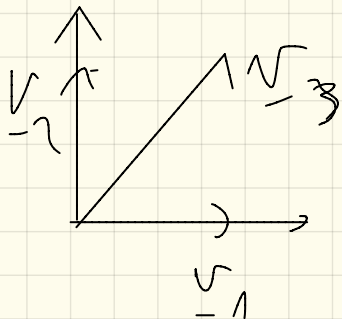
$\subset V_2$

Ogni  $\underline{v}$  si scrive  
in infiniti modi  
come:

$$\underline{v} = x_1 \underline{v}_{-1} + x_2 \underline{v}_{-2} + x_3 \underline{v}_{-3}$$

25.09.16.  $\underline{v} = \underline{0}$

$$\underline{0} = 0 \underline{v}_1 + 0 \underline{v}_2 + 0 \underline{v}_3$$



$$\underline{v}_1 = (1, 0)$$

$$\underline{v}_2 = (0, 1)$$

$$\underline{v}_3 = (1, 1)$$

$$\underline{v}_3 = \underline{v}_1 + \underline{v}_2 \rightarrow \underline{0} = \underline{v}_1 + \underline{v}_2 - \underline{v}_3$$

Coeff.: 1, 1, -1

Def - I vettori  $\underline{v}_1, \dots, \underline{v}_n \in V$

si dicono

**LINEARMENTE DIPENDENTI**

se  $\exists \alpha_1, \dots, \alpha_n \in K$  non tutti nulli

tali che  $\alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n = \underline{0}$

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Def I vettori  $\underline{v}_1, \dots, \underline{v}_n \in V$  si dicono

**LINEARMENTE INDIPENDENTI**

se l'unica soluzione

di  $\alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n = \underline{0}$  è  $\alpha_1 = \dots = \alpha_n = 0$

Oss. Siamo  $\underline{v}_1, \dots, \underline{v}_n$  linear. indipendenti.

Allora se

$$\underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n = \beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n$$

$$\Rightarrow \alpha_1 = \beta_1, \dots, \alpha_n = \beta_n$$

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$$(\alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n) - (\beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n) = \underline{0}$$

$$(\alpha_1 - \beta_1) \underline{v}_1 + \dots + (\alpha_n - \beta_n) \underline{v}_n = \underline{0}$$

$$\Rightarrow \alpha_1 = \beta_1, \dots, \alpha_n = \beta_n$$

DEF Una BASE dello spazio  $V$

è un insieme ordinato di vettori  $\{\underline{v}_1, \dots, \underline{v}_n\} \in V$   
tale che

$$1) \text{ Span } \{\underline{v}_1, \dots, \underline{v}_n\} = V \quad (\rightarrow \text{generatori})$$

2) I  $\underline{v}_1, \dots, \underline{v}_n$  sono linearmente indipendenti



Esampi.  $V = \mathbb{R}$  sp. vett. su  $\mathbb{R}$

en  $\{\underline{v}\}$  e' linear. indep.  $\Leftrightarrow \underline{v} \neq \underline{0}$

$\Rightarrow$  se  $\underline{v} = \underline{0}$  allora  $1 \cdot \underline{v} = 1 \cdot \underline{0} = \underline{0}$

$\nexists \alpha \underline{v} \neq \underline{0}$  e  $\alpha \neq \underline{0}$

$\alpha \underline{v} = \underline{0}$  ,  $\underline{v} \neq \underline{0} \Rightarrow \alpha = \underline{0}$

e  $\alpha \neq \underline{0} \exists \alpha^{-1}$

$\alpha^{-1}(\alpha \underline{v}) = \alpha^{-1} \cdot \underline{0} \rightarrow (\alpha^{-1} \alpha) \underline{v} = \underline{0}$

si ha contraddizione  $\rightarrow 1 \cdot \underline{v} = \underline{0}$

$\Sigma_1$   $0 \in A \Rightarrow A$  non è lin. indep.

CASO GENERALE  $A \subset V$  (ogni si ammette  $A$  infinito)  
si dice linearmente dipendente

se  $\exists \underline{v}_1, \dots, \underline{v}_m \in A$  e  $\alpha_1, \dots, \alpha_m \in \mathbb{K}$   
numeri non tutti nulli t.c.

$$\alpha_1 \underline{v}_1 + \dots + \alpha_m \underline{v}_m = \underline{0}$$

$A$  indipendente se l'unica soluzione di

$$\alpha_1 \underline{v}_1 + \dots + \alpha_m \underline{v}_m = \underline{0} \quad \text{è la soluzione nulla } \boxed{\alpha_i = 0 \forall i}$$

$\forall$  scelta di vettori  $\underline{v}_1, \dots, \underline{v}_m \in V$

$1 \cdot \underline{0} = \underline{0}$   $\bar{e}$  combin. lineare non  
basse che da  $\underline{0}$

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$V = \mathbb{R}$  basi  $\{ \underline{v}_1 \}$   $\underline{v}_1 \neq 0$

es  $\underline{v}_1 = 1$

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$V = \mathbb{R}^2$  basi canonica  $\underline{e}_1 = (1, 0)$   
 $\underline{e}_2 = (0, 1)$

verifichiamo

1. Sono generatori

$$\text{Span} \{e_1, e_2\} = \mathbb{R}^2$$

$$\forall \underline{v} = (a, b)$$

devo poter risolvere:

$$\exists x, y \in \mathbb{R} \text{ t.c.}$$

$$\underline{v} = x e_1 + y e_2$$

$$(a, b) = a(1, 0) + b(0, 1)$$

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2. Sono linearmente indipendenti

devo dimostrare che l'equazione nelle incognite  $\alpha_1, \alpha_2$

$$\alpha_1 \underline{e}_1 + \alpha_2 \underline{e}_2 = \underline{0}$$

ha solo la soluzione  $\alpha_1 = \alpha_2 = 0$

$$\alpha_1 (1, 0) + \alpha_2 (0, 1) = (0, 0)$$

$$\begin{cases} \alpha_1 \cdot 1 + \alpha_2 \cdot 0 = 0 \\ \alpha_1 \cdot 0 + \alpha_2 \cdot 1 = 0 \end{cases} \rightarrow \begin{cases} \alpha_1 = 0 \\ \alpha_2 = 0 \end{cases}$$

in  $\mathbb{R}^3$  : base canonice

$$\underline{e}_1 = (1, 0, 0)$$

$$\underline{e}_2 = (0, 1, 0)$$

$$\underline{e}_3 = (0, 0, 1)$$

$$\underline{v} = (a, b, c)$$

$$\exists x, y, z \in \mathbb{R}$$

$$\underline{v} = x \underline{e}_1 + y \underline{e}_2 + z \underline{e}_3$$

?

$$(a, b, c) = a(1, 0, 0) + b(0, 1, 0) + c(0, 0, 1)$$

$$x = a, y = b, z = c$$

$$\text{Span}(\underline{v}_1, \underline{v}_2, \underline{v}_3) = \mathbb{R}^3$$

$$\mathbb{K}^m = V$$

base canonica  $\underline{e}_1 = (1, 0, \dots, 0)$

$$\underline{e}_2 = (0, 1, 0, \dots, 0)$$

$$\underline{e}_i = (0, \dots, 1, \dots, 0)$$

$$\underline{e}_m = (0, \dots, 0, 1)$$

1 al posto  
i-simo

verificare che  $\text{Span}(\{\underline{v}_1, \dots, \underline{v}_m\}) = \mathbb{K}^m$

e sono linearmente indipendenti.

$$V = \mathbb{R}[X] = \left\{ a_0 + a_1 X + \dots + a_n X^n, \right. \\ \left. a_i \in \mathbb{R} \right\}$$

non  $\exists$  base finita

se  $\underline{v}_1, \dots, \underline{v}_n$  fossero generatori

$$\text{grado} \left( d_1 \underline{v}_1 + \dots + d_n \underline{v}_n \right) \leq \max_i \{ \text{grado } \underline{v}_i \}$$



$$\underline{\text{Base}} = \left\{ \underset{\substack{|| \\ \underline{v}_0}}{1}, \underset{\substack{|| \\ \underline{v}_1}}{X}, \underset{\substack{|| \\ \underline{v}_2}}{X^2}, \underset{\substack{|| \\ \underline{v}_3}}{X^3}, \dots, \underset{\substack{|| \\ \underline{v}_n}}{X^n}, \dots \right\}$$

$$p(x) = a_0 + a_1 X + \dots + a_n X^n$$

$\bar{v}$  comb. lineare

$$p(x) = a_0 \underline{v}_0 + a_1 \underline{v}_1 + \dots + a_n \underline{v}_n$$

$$a_0 X^{n_0} + a_1 X^{n_1} + \dots + a_k X^{n_k} = \underline{0}$$

$$\Leftrightarrow a_0 = \dots = a_k = 0$$

$n_j$ : esponenti  
diversi tra loro

$$V = \{f: \{1, 2, 3\} \rightarrow \mathbb{R}\}$$

es. trovare una base

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es.  $\{f: \{1, \dots, n\} \rightarrow \mathbb{R}\}$

trovare base

abbiamo visto:  $\text{Span}(A) \subset \text{Span}\{A \cup B\}$   
 $\forall A, B \subset V$

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es se  $\text{Span}(A) = \text{Span}(A \cup B)$

allora  $\forall \underline{v} \in B \implies \underline{v} \in \text{Span}(A)$

[in altri termini:  $B \subset \text{Span}(A)$ ]

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