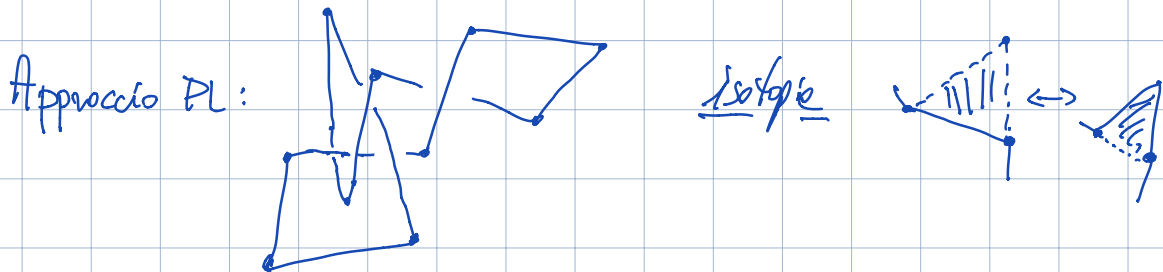
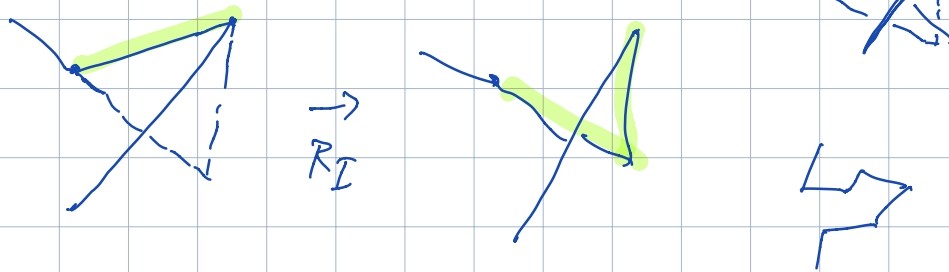


LDT - IUSS 4/4/2020

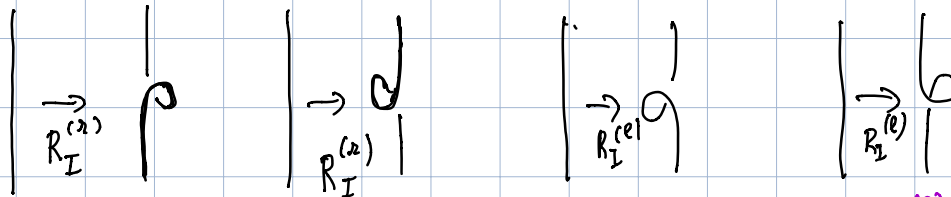
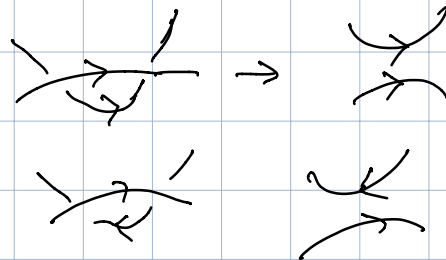
$\{ \text{link DIFT} \} / \text{isotopia} \longleftrightarrow \{ \text{diagrammi planari} \} / \text{isotopia planare} + \text{mon } R_I, R_{II}, R_{III}$



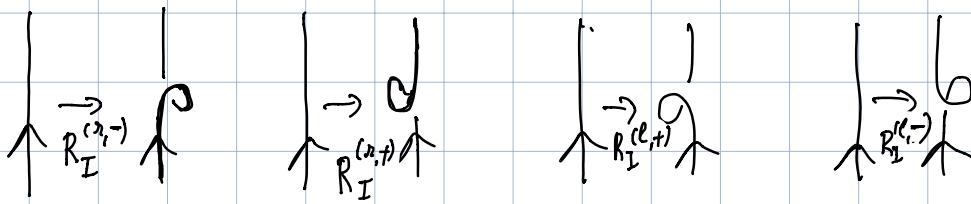
posso suddividere il triangolo in triangoli in cui accade un solo accidente



Versioni orientate delle unioni



Fatto : $R_I^{(2)} \neq R_I^{(e)}$

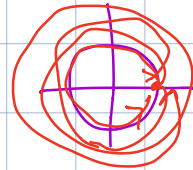


$$R_I^{(n,-)} \neq R_I^{(n,+)}$$

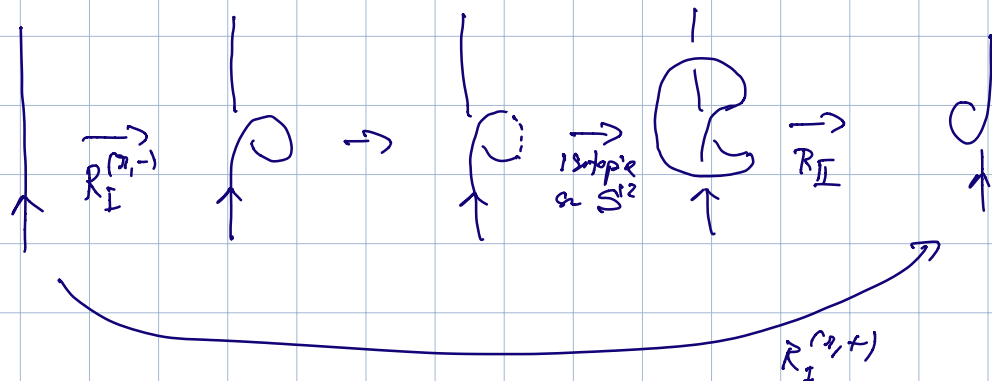
$$\alpha: S^1 \rightarrow \mathbb{R}^2$$

$$\frac{\alpha'}{\|\alpha'\|}: S^1 \rightarrow S^1$$

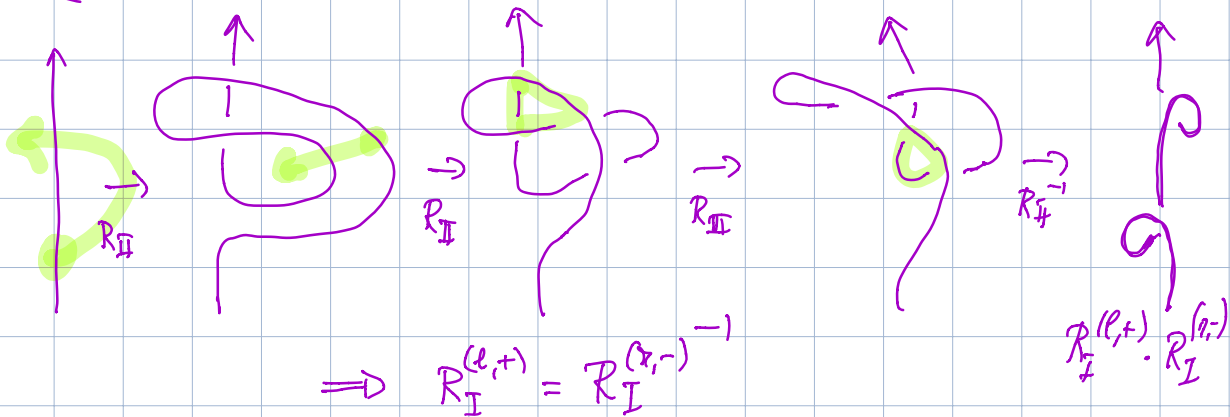
$$\pi_1(S^1) = \mathbb{Z}$$



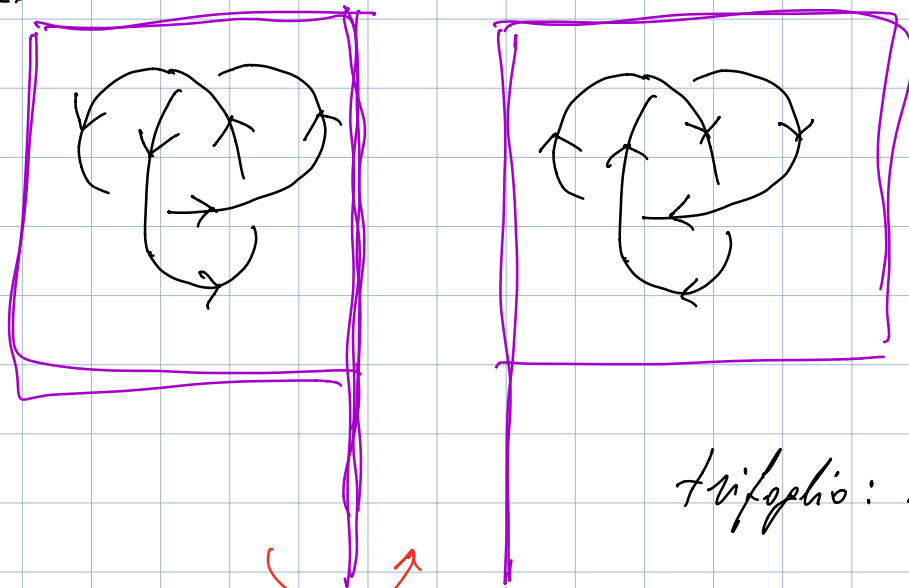
Oss: i diagrammi posso vederli in $S^2 = \mathbb{R}^2 \cup \{\infty\}$.



Oss:

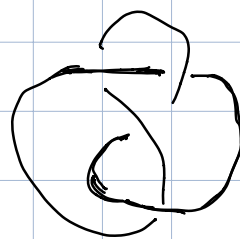


invertibile:



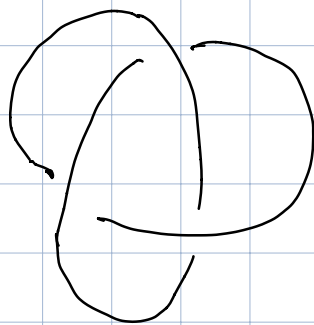
trifoglio: π

Esercizio: tradurre $\nearrow$
in mosse R_I, R_{II}, R_{III} .

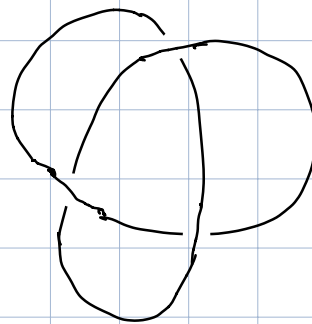


non invertibile

chirale:



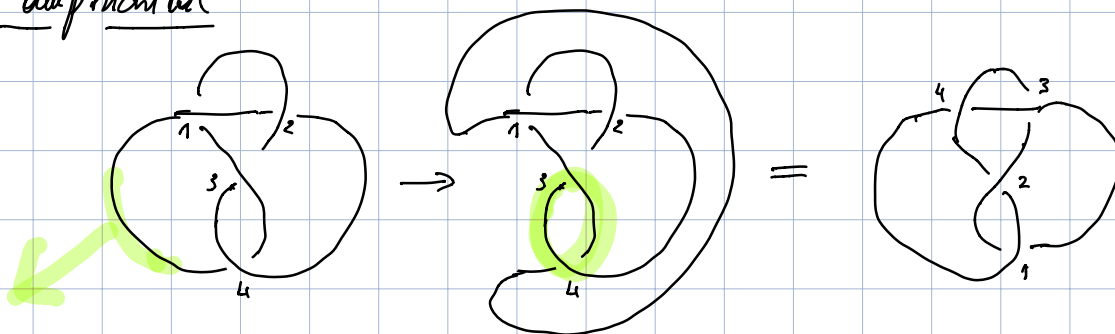
$\neq$
(vedremo)



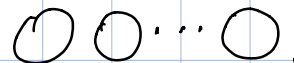
trifoglio sinistro

trifoglio destro

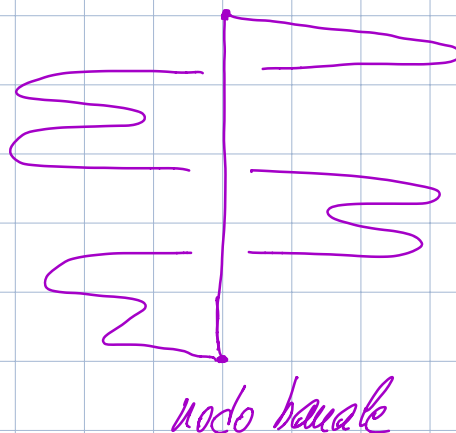
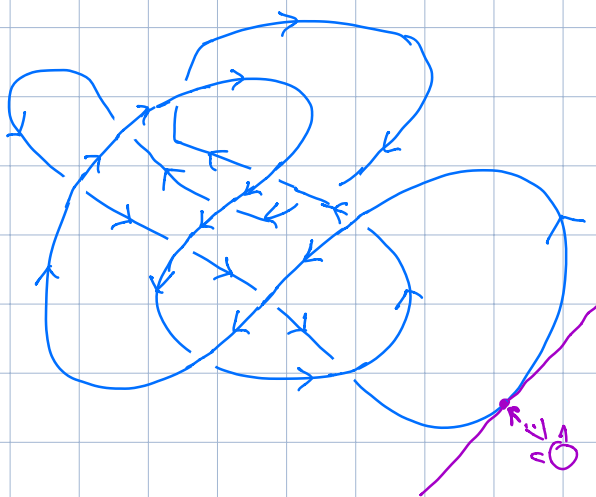
amphichiral



Prop: dato D qualsiasi diagramma di link esistono scambi
di incroci del vertice D diagramma del link banale



Dimo: per un nodo:



nodo banale

link $K_1 \cup \dots \cup K_m$

K_1 segue sopra gli altri, lo spondo ...



Invarianti per nodi:

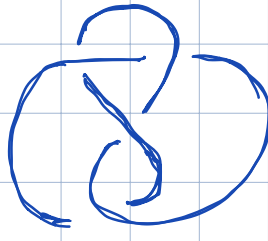
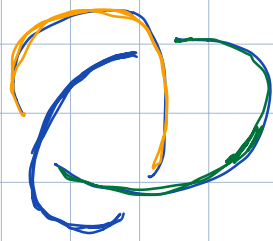
$I : \{\text{diagrammi}\} \rightarrow \mathbb{S}$

t.c. se due diagrammi sono legati da
mosse R_I, R_{II}, R_{III} allora I ha
lo stesso valore.

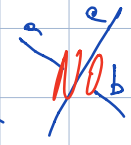
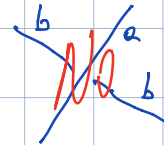
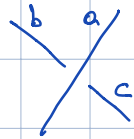
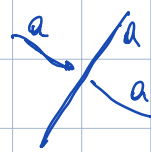
Tricolorazioni:

$\{a, b, c\}$ tricolorazioni di diag. D

un colore per gli overarc (gli archi
con cui D è disegnato) t.c. a ogni
incrocio vedo o 3 volte lo stesso colore o



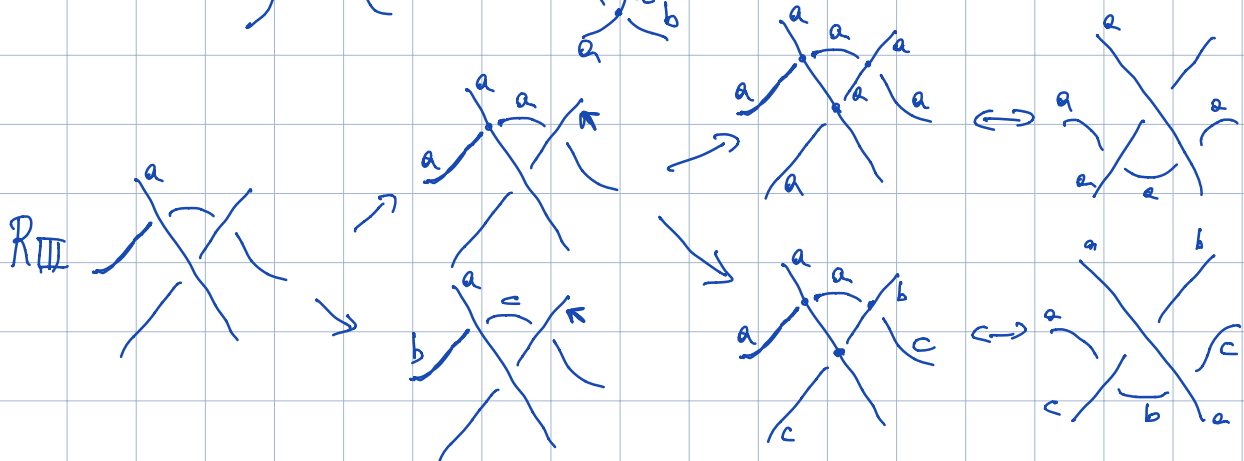
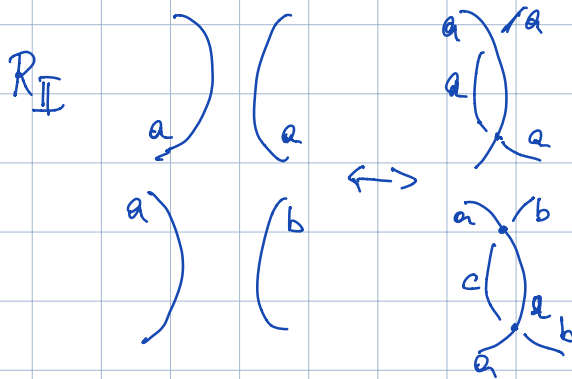
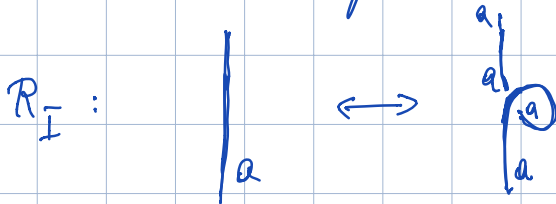
tutti e tre i colori:

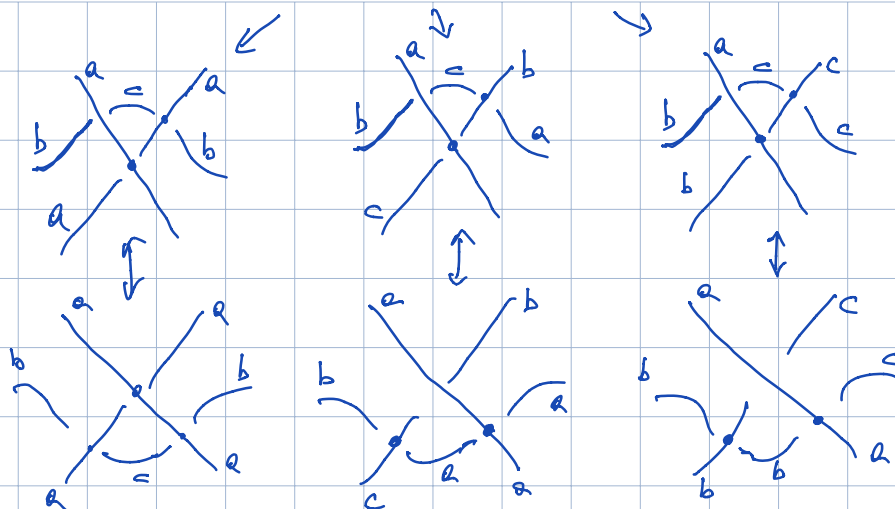


Def: $c_3(D) = \# \{ \text{tricolorazioni} \} / \sim_{\{a,b,c\}}$

Teo: c_3 è un invariante.

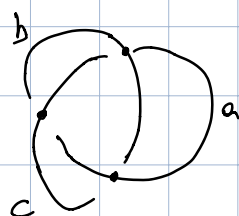
Dimo: provo che per ogni mossa R_I, R_{II}, R_{III} c'è una naturale bijezione tra le tricolorazioni prima e dopo.





Con: $\bigcirc \neq 0$

Dim: $c_3(\bigcirc) = 1$



$c_3(\text{trif}) = 2.$

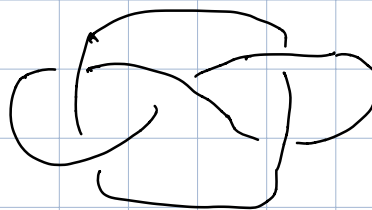


Oss: $c_3 \left(\begin{array}{c} \text{graph with vertices and edges labeled a, b, c} \end{array} \right) = 1$

Con:

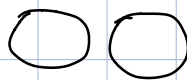


Hopf



Whitehead

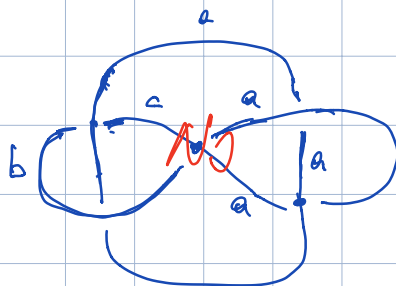
diversi da



(Hopf $\neq$ $\bigcirc\bigcirc$ facile
Hopf $\neq$ Whitehead facile)

$$c_3(\bigcirc\bigcirc) = 2$$

$$c_3\left(\begin{array}{c} a \\ \bigcirc \\ a \end{array}\right) = 1$$



$$c_3(\text{Whitehead}) = 1.$$

Linking number per coppie di nodi orientati

$\vec{K}_1, \vec{K}_2$

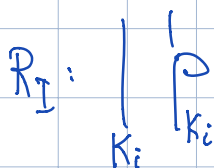
$$lk(\vec{K}_1, \vec{K}_2) = \sum \pm 1 = \sum (+1) + \sum (-1)$$

$\begin{array}{c} \uparrow \\ \text{---} K_2 \\ \uparrow \\ K_1 \end{array}$

$\leftarrow \begin{array}{c} K_1 \\ \text{---} \\ K_2 \end{array}$

$\begin{array}{c} \uparrow K_1 \\ \text{---} \\ K_2 \end{array}$

Prop: è ben def (i.e. per R_I, R_{II}, R_{III}):



Es: $lk(\bigcirc \bigcirc) = 0$

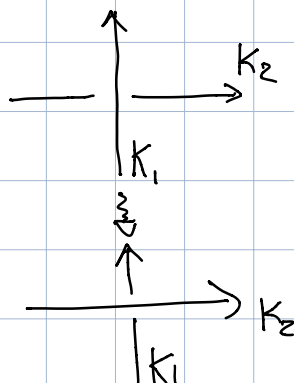
$lk(K_1 \bigcirc K_2) = |-1| = 1$

$lk \left(\begin{array}{c} \text{Diagram with two loops } K_1 \text{ and } K_2 \text{ intersecting at two points. The intersection points are labeled } -1 \text{ and } +1. \end{array} \right) = 0$
 $\Rightarrow \text{Whithead} \neq \text{Hopf}$

Prop: $lk(\vec{K}_2, \vec{K}_1) = lk(\vec{K}_1, \vec{K}_2)$

Dimo: se sono lontani $\bigcirc K_1 \bigcirc K_2$
sono entrambi 0.

Tramite scambi incroci diventano isotopi e lontani:
 $\Rightarrow$ basta vedere che $lk(\vec{K}_2, \vec{K}_1) - lk(\vec{K}_1, \vec{K}_2)$
non cambia con scambi incroci:
 $lk(K_1, K_2) - lk(K_1, K_2)$



$0 - (-1) = +1$

$+1 - 0 = +1$



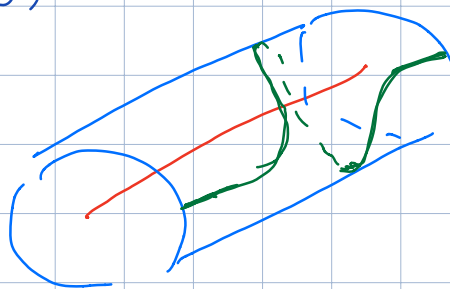
$$\underline{\text{Oss}}: \quad lk(\vec{K}_1, \vec{K}_2) = \frac{1}{2} \left(\sum_{\substack{\leftarrow \uparrow -K_j \\ K_i \\ \{i,j\} = \{1,2\}}} (+1) + \sum_{\substack{-\downarrow \rightarrow K_j \\ K_i \\ \{i,j\} = \{1,2\}}} (-1) \right)$$

Def: chiamo nodo con framing un nodo con una scelta di una sua longitudine / isotopia:

$$K, \quad U(K) \cong D^2 \times S^1, \quad \lambda \in \partial U(K)$$

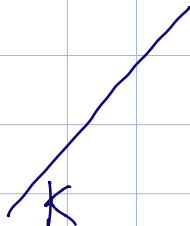
$$[\lambda] = \text{generatore di } H_1(U)$$

visto a meno di isotopia di U
e isotopia delle longitudini
su ∂U .

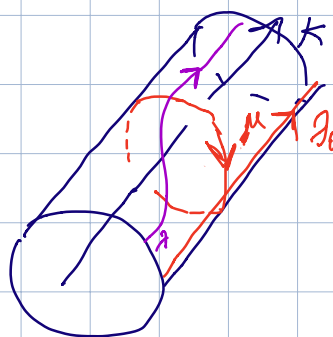


Visto: c'è una longitudine privilegiata.

Oss: se λ_0 è la long. privilegiata le altre sono parametrizzate da $\mathbb{Z}$ così:



$\leadsto$

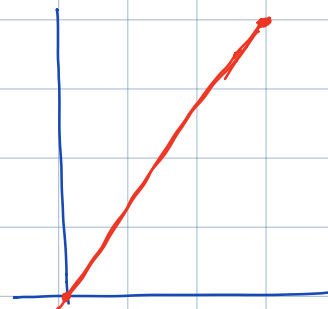
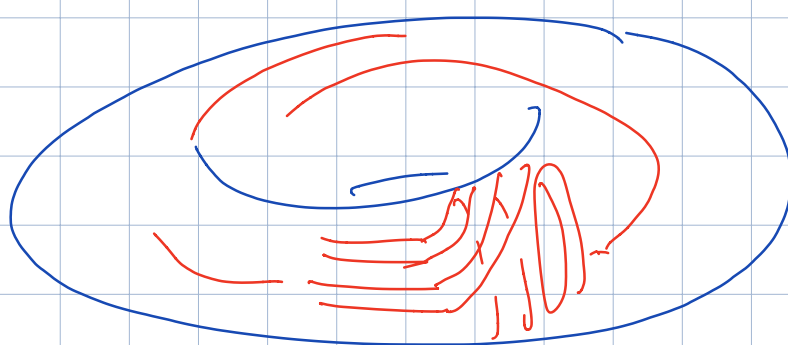


$$[\lambda] = [\lambda_0 + p\mu] \in H_1(\partial U)$$

$$\gamma \leftrightarrow p \in \mathbb{Z}$$

Oss: non dipende da orientazione.

Oss: su ∂U una qualsiasi curva semplice chiusa non
 boudle α ($\alpha \neq \partial U$) si scrive come
 $[\vec{\alpha}] = [a\gamma + b\gamma_0]$ con $(a,b) = 1$.



Corrispondenza: $\left\{ \begin{array}{l} \text{curve semplici chiuse} \\ \text{non boudle in } \partial U \end{array} \right\} / \sim \longleftrightarrow \mathbb{Q} \cup \{\infty\}$

$$[\alpha] \longleftrightarrow a/b \in \mathbb{Q} \cup \{\infty\}$$

$$n[\vec{\alpha}] = [a\gamma + b\gamma_0]$$

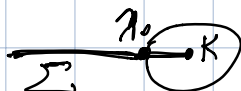
$$\bigcup \left\{ \text{longitudinali} \right\} \longleftrightarrow \mathbb{Z} \text{ in } H_1(\partial U)$$

Prop: dato $\vec{K} \subset S^3 \exists \Sigma$ sup. orientata $\subset S^3$ t.c $\partial \Sigma = \vec{K}$.

Def Ogni tale Σ è detta sup. di Seifert per K .

Diamo: (1) $[\gamma_0] = 0 \in H_1(E)$ ($E = S^3 \setminus U$)

" $\Rightarrow$ " γ_0 boudle superficie orientata in E

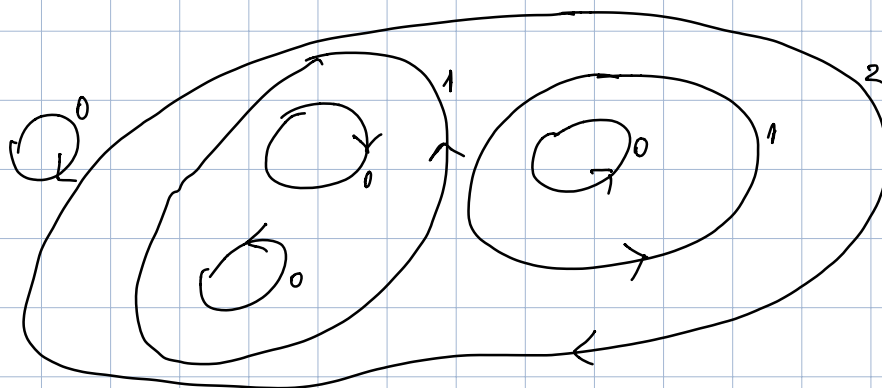


(2) algoritmo di Seifert:

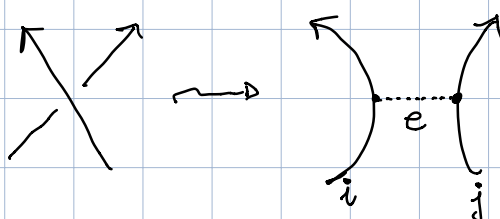
- parto da diagramma D
- semplifico incroci usando orientazione:



- trovo circonferenze in $\mathbb{R}^2$: le ordino dichiarando livello 0 quelle che non circondano altre, livello 1 quelle che circondano solo quelle 0 etc.



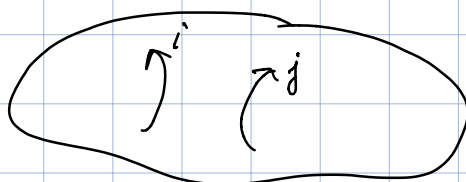
- unto il livello l a l altezza l e in $\mathbb{R}^2 \times \{l\}$ considero dischi orientati bordati positivamente dalle circ. a livello l .

- affermo: 

$e \in [i, j]$ non incontra alcun disco

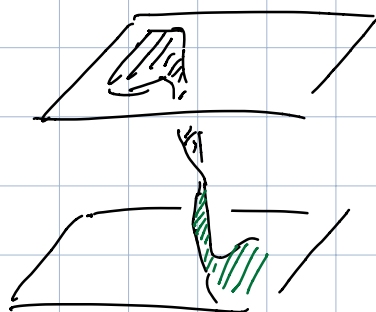
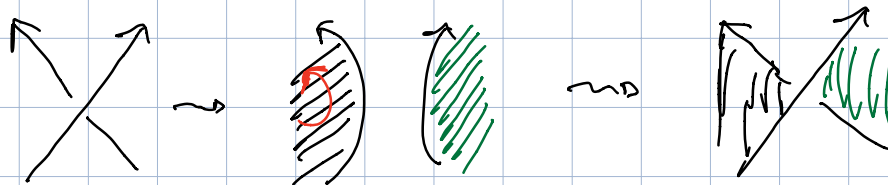
abbinamenti

$$j < k < i$$

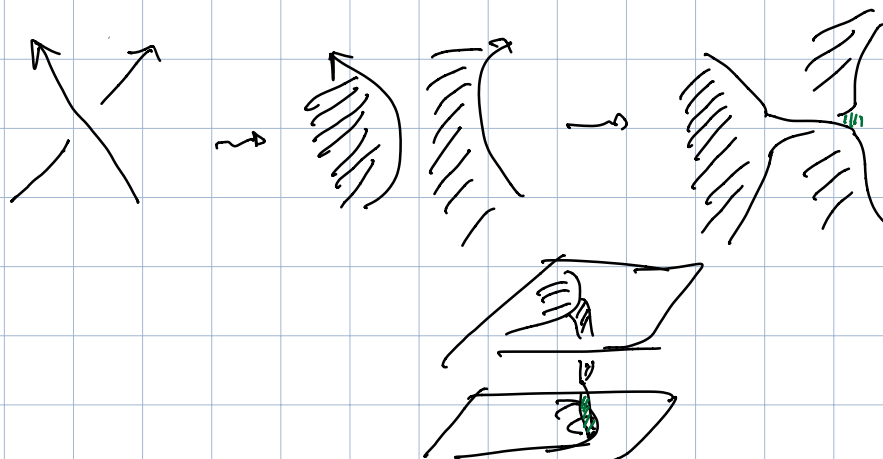


$k \Rightarrow k$ circonda i
ASSURDO

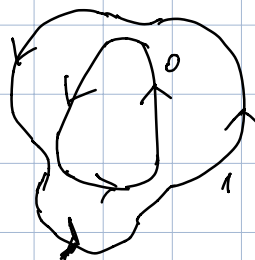
• ripristino gli incroci incollando pezzi di disco:



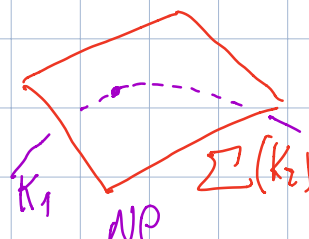
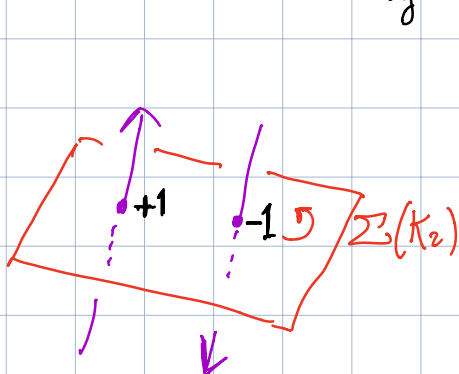
oppure:



Es:

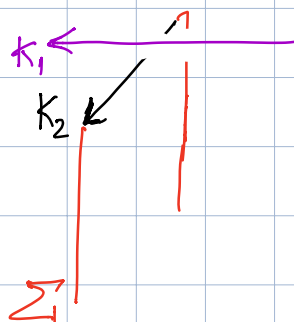
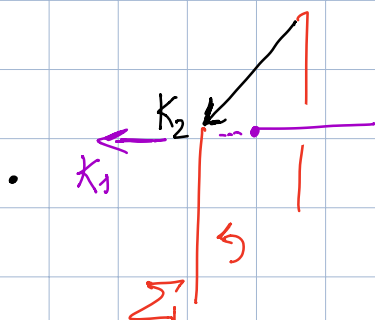
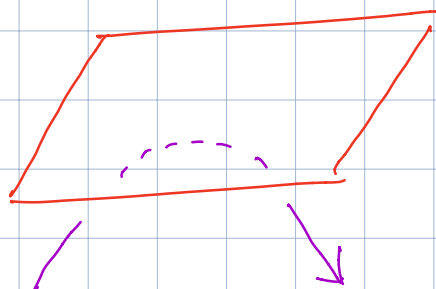
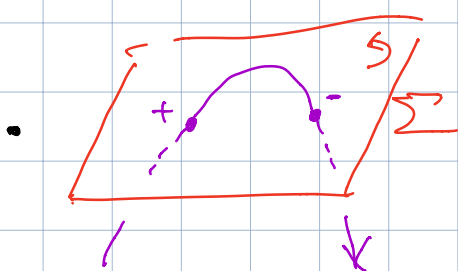


Prop: $lk(K_1, K_2) = \#_{alg} (K_1 \cap \Sigma(K_2))$

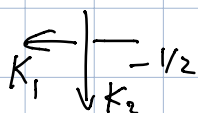


Dico: se K_1 è lontano da $\Sigma(K_2)$ entrambi 0.

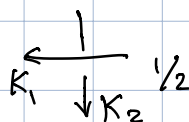
Provo che spostando K_1 lontano da $\Sigma(K_2)$ la differenza non cambia:



+1



0

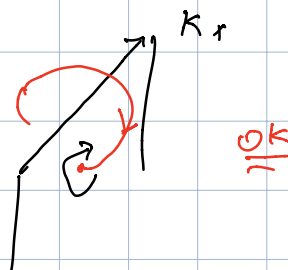


$$\# K_1 \cap \Sigma(K_2) = \frac{1}{2} \ell k(K_1, K_2)$$

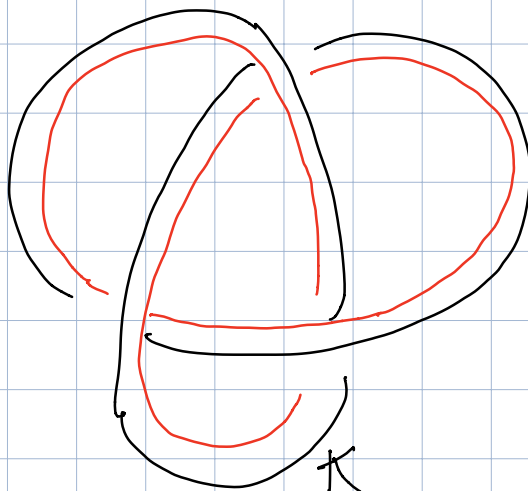


Con: $\ell k(\vec{K}_1, \vec{K}_2) = p$ ac $[\vec{K}_2] = p \cdot [\vec{K}_1] \in H_1(E(K_1))$

Dimo: basta vedere che $\# \vec{K}_1 \cap \Sigma(K_1) = +1$



Def: chiamiamo framing diagrammatico di un diagramma D di un nodo K quello in cui la longitudine è parallela a D sul piano:

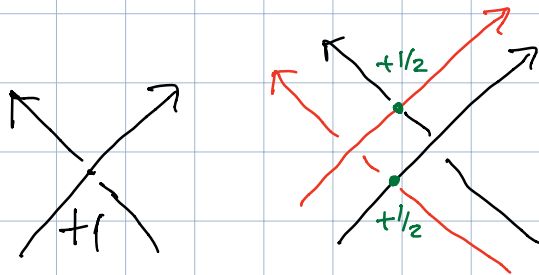


Def: $slk(D) = \sum_{\leftarrow \uparrow -} (+1) + \sum_{-\uparrow \rightarrow} (-1)$

(any two orientations a case $\leftarrow \uparrow_{+1} \rightsquigarrow - \downarrow_{+1}$)

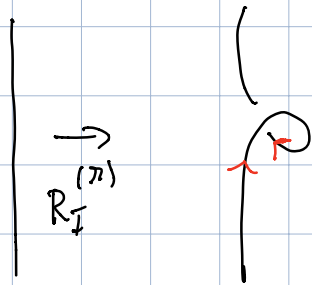
Prop: l'intero che corrisponde al framing diag è $slk(D)$

Dimo:



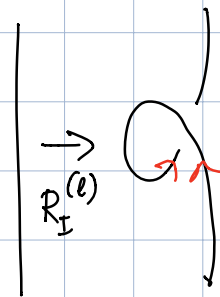
Oss: $1 \leftrightarrow p$
 se $[1] = [20 + p1]$
 $\Rightarrow p = lk(K, 1)$
 ■

Con: due diagrammi legati da move R_I definiscono nodi con framing diversi:



$slk=0$

$slk=+1$

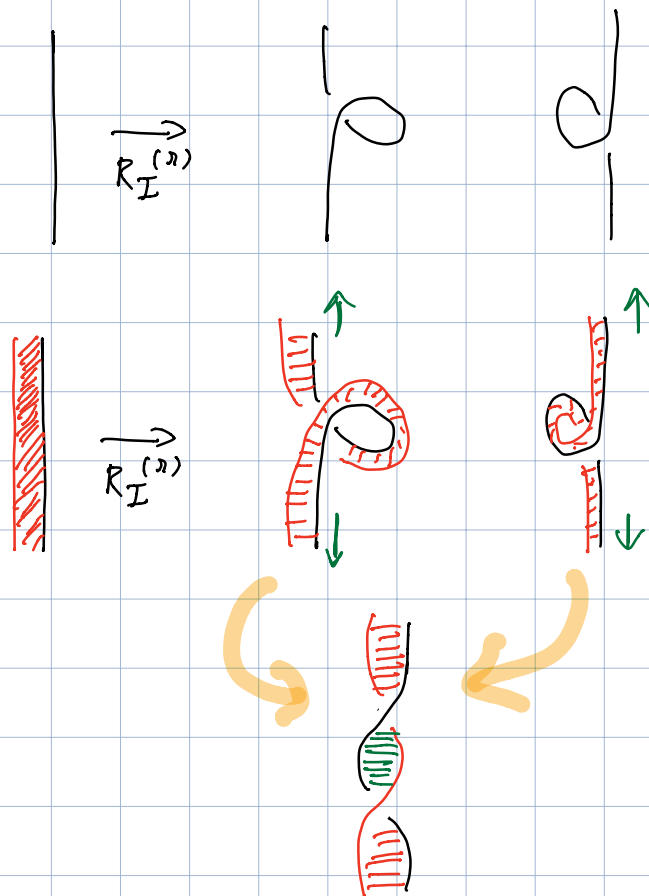


$slk=0$

$slk=-1$

Oss: R_{II} e R_{III} e move che preservano il framing

Con: $R_I^{(n)}$ è generata da R_{II}, R_{III} , isotope ottimali ∞
 ma non senza $R_I^{(e)-1}$ e $R_I^{(e)-1}$



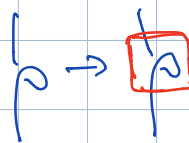
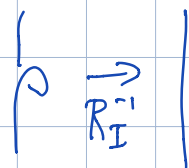
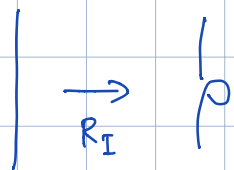
Teo: due diagrammi rappresentano lo stesso nodo con framinge
 $\Leftrightarrow$ si ottengono uno dall'altro tramite
 • R_{II}, R_{III} + isotopia su S^2
 • R_I, R_{III} + mosse $\begin{matrix} p & \leftrightarrow & q \\ \hline & & \end{matrix}$

Dico: equivalenza dei due set segue da quanto visto all'inizio.
 Faccio dico con secondo

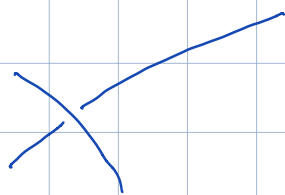
D_1, D_2 rappresentano stesso nodo

$\Rightarrow$ eqvt. da R_I, R_{II}, R_{III} .

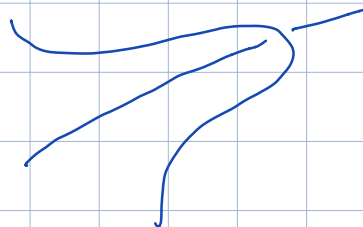
Modifico successione così:



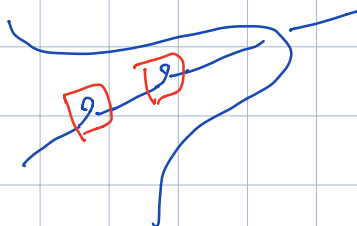
esempio solo R_{II} e R_{III} ma faccio comparsare



$\rightsquigarrow$
involge
piano



$\rightsquigarrow$
 R_{II}, R_{III}

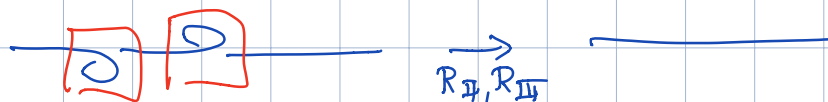


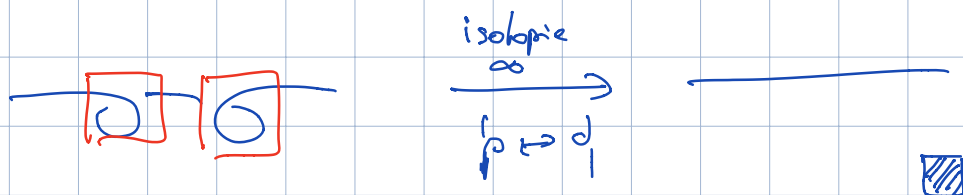
Alla fine ho $D_1 \rightsquigarrow_{R_{II}, R_{III}} \overline{D}_2 = D_2 + \text{alcuni riccioli}$

$\Rightarrow \overline{D}_2$ e D_2 danno lo stesso framing:

$\Rightarrow$ numero algebrico di riccioli $= 0$

li faccio sciogliere vicini $\Rightarrow$ ne ho due disordi adiacenti





$\mathcal{L} = \{\text{link con framing}\} / \sim$

Kauffman bracket

$$[\cdot] : \mathcal{L} \rightarrow \mathbb{Z}[A^{\pm 1}]$$

$$\cdot \quad [X] = A \cdot [\text{diagram with crossing resolved to two arcs}] + A^{-1} [\text{diagram with crossing resolved to two arcs}]$$

sopra verso sinistra sopra verso destra

$$\cdot \quad [D \sqcup O] = (-A^2 - A^{-2}) \cdot [D] \quad D \neq \emptyset$$

$$\cdot \quad [\emptyset] = 1$$

oppure: chiamo stato s la scelta di segni $+$ o $-$
 per ciascun incrocio j $p(s) = \# "+"$ $m(s) = \# "-"$

$|s| = \#$ circonferenze del diagramma
 semplificato $+/- \rightarrow) ($

$$[D] = \sum_s A^{p(s)-m(s)} \cdot (A^2 - A^{-2})^{|s|}$$

$\mathcal{L}$ ben def. sui diagrammi.

Teo: $\bar{c}$ invariante rispetto alle mosse con framing $\Rightarrow \bar{c}$ ben def. in $\mathcal{F}$.

Dimo:

• $\rho \leftrightarrow \phi$

provo invece che
hanno stesso spillo in $[\cdot]$

$\mid \rightarrow \rho \quad \mid \rightarrow \phi$

$$\begin{aligned} \begin{bmatrix} \rho \end{bmatrix} &= A \cdot \begin{bmatrix} 0 \end{bmatrix} + A^{-1} \cdot \begin{bmatrix} 1 \end{bmatrix} = (A(-A^2 - A^{-2}) + A^{-1}) \cdot [1] \\ &= (-A^3) \cdot [1] \end{aligned}$$

$\begin{bmatrix} \phi \end{bmatrix} = \dots$ stesso.

$$\begin{aligned} \bullet \quad \begin{bmatrix} \text{X} \end{bmatrix} &= A^2 \cdot \begin{bmatrix} \text{>} \end{bmatrix} + \begin{bmatrix} \text{<} \end{bmatrix} \\ &+ \begin{bmatrix} \text{>} \end{bmatrix} \begin{bmatrix} \text{<} \end{bmatrix} + A^{-2} \begin{bmatrix} \text{>} \end{bmatrix} \begin{bmatrix} \text{<} \end{bmatrix} \\ &= \cancel{(A^2 - A^{-2} - A^{-2} - A^2)} \begin{bmatrix} \text{>} \end{bmatrix} \begin{bmatrix} \text{<} \end{bmatrix} + 1 \cdot \begin{bmatrix} \text{X} \end{bmatrix} \end{aligned}$$

$$\bullet \quad \begin{bmatrix} \text{X} \end{bmatrix} = A \begin{bmatrix} \text{X} \end{bmatrix} + A^{-1} \begin{bmatrix} \text{>} \end{bmatrix} \begin{bmatrix} \text{<} \end{bmatrix}$$

$$= A \cdot \left[\text{Diagram 1} \right] + A^T \left[\text{Diagram 2} \right]$$

$$= \left[\text{Diagram 3} \right]. \quad \square$$