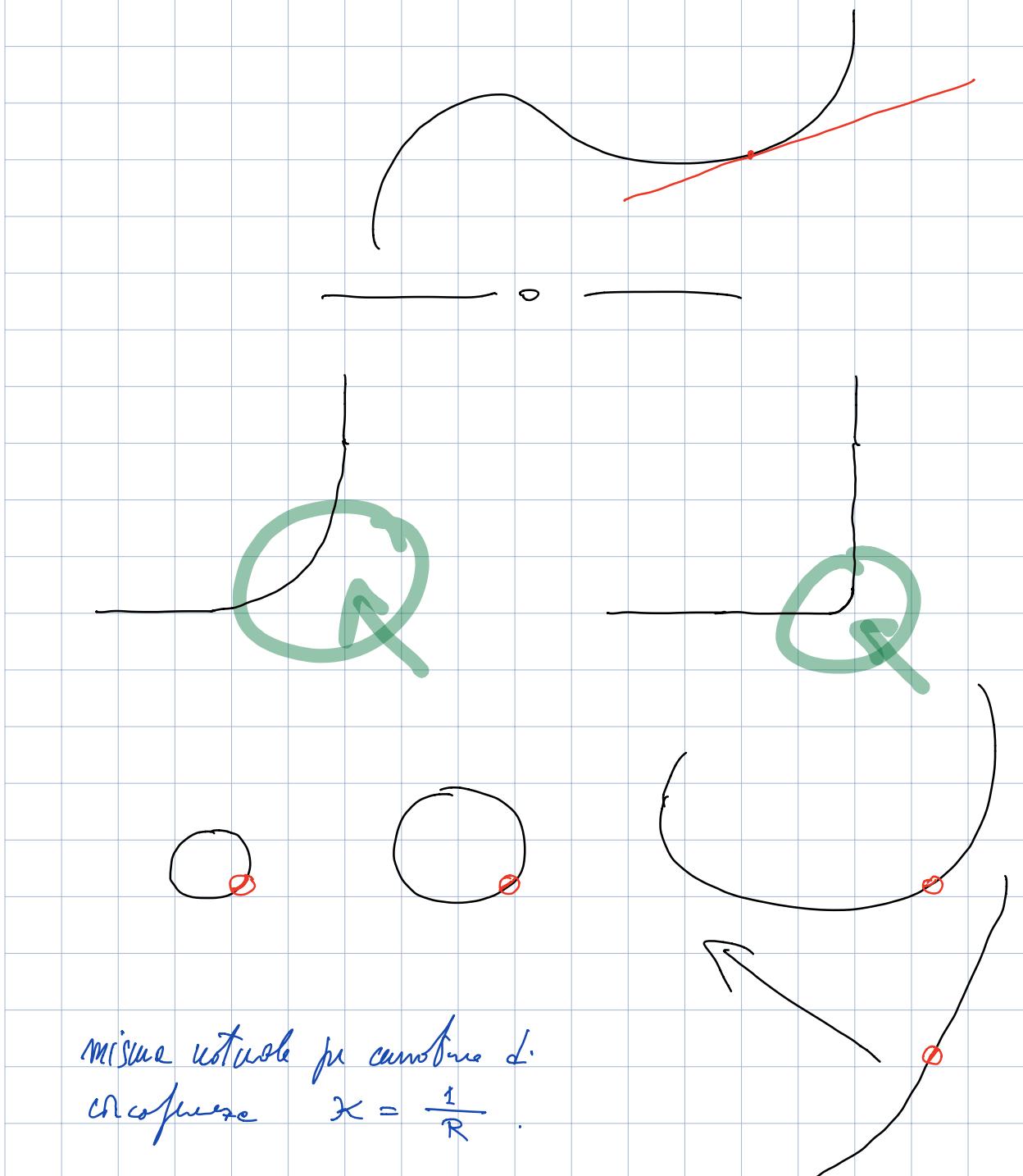
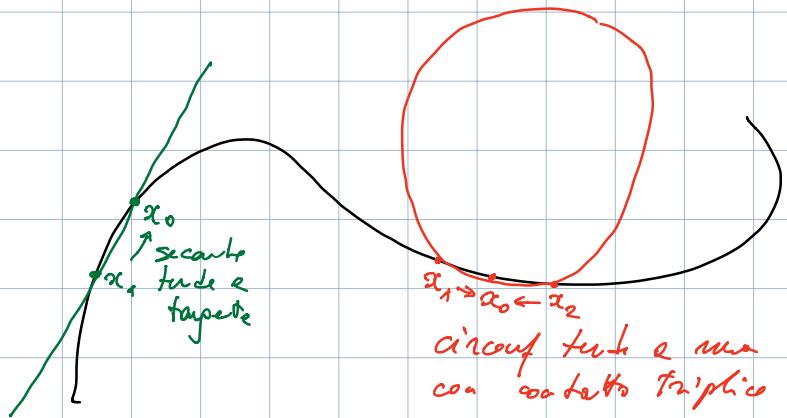


Geometrieis 6/5/20

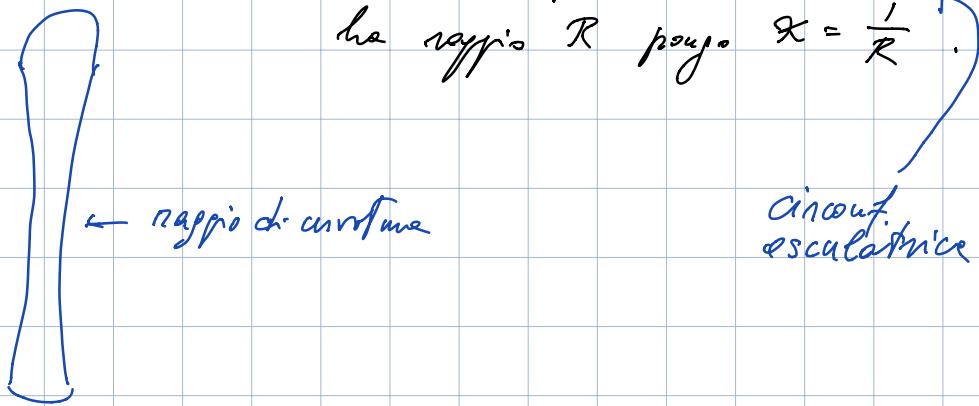
$$\alpha: [a, b] \rightarrow \mathbb{R}^m \quad (m=2)$$





Se la circonf. con centro triplice

ha raggio  $R$  poggia  $\alpha = \frac{1}{R}$ .



Tangente :  $\alpha(t_0) \in \text{Span}(\alpha'(t_0))$ .

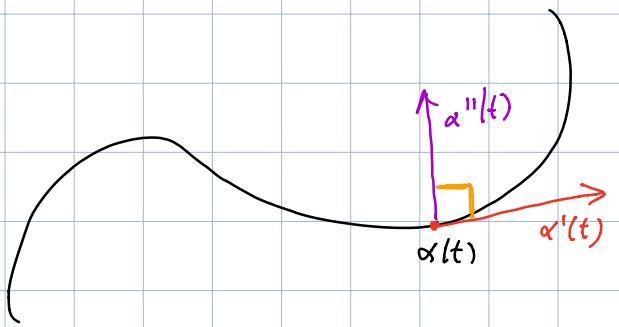
Lem: se  $r: [a,b] \rightarrow \mathbb{R}^n$  e  $\|v(t)\| = 1$  allora  $v'(t) \perp v(t) \forall t$ .

$$\text{Dim: } \|v(t)\|^2 = v_1(t)^2 + \dots + v_n(t)^2 = 1$$

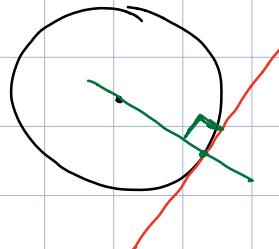
$$\rightarrow 2v_1(t) \cdot v'_1(t) + \dots + 2v_n(t) \cdot v'_n(t) = 0$$

$$\Rightarrow \langle v(t) | v'(t) \rangle = 0 \quad \square$$

Con: se  $\alpha: [a,b] \rightarrow \mathbb{R}^n$  è in p.d.a. ( $\|\alpha'(t)\| = 1$ )  
allora  $\alpha''(t) \perp \alpha'(t) \forall t$ .



Oss: se circuito  $\mathcal{C}$  ha contatto triplice con  $\alpha$  in  $\alpha(t_0)$  allora  $\alpha$  è anche tangibile  $\Rightarrow$  ha stessa tangente in  $\alpha(t_0)$   $\Rightarrow$  de  $\dot{\alpha}$  è in p.d. al centro in  $\alpha(t_0) + \text{Span}(\alpha''(t_0))$



Prop: se  $\alpha$  è in p.d. al centro di circuito oscillettante in  $\alpha(t_0)$  il raggio è  $\alpha(t_0) + \frac{\alpha''(t_0)}{\|\alpha''(t_0)\|^2}$ .

$$\begin{aligned}\text{Cor: raggio} &= \left\| \alpha(t_0) - \left( \alpha(t_0) + \frac{\alpha''(t_0)}{\|\alpha''(t_0)\|^2} \right) \right\| \\ &= \left\| \frac{\alpha''(t_0)}{\|\alpha''(t_0)\|^2} \right\| = \frac{1}{\|\alpha''(t_0)\|}\end{aligned}$$

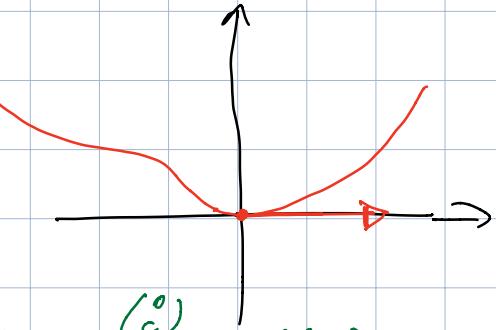
$$\Rightarrow \mathcal{R}(t_0) = \|\alpha''(t_0)\|.$$

Oss:  $\alpha''(t_0) = 0 \Rightarrow$  le circuiti oscillettanti degenerano in rette (tranne che i contatti triplici).

Dim: Sappiamo  $t_0 = 0$   $\alpha(t_0) = (0)$   $\alpha'(t_0) = (1)$

$$\Rightarrow \alpha''(0) = (c)$$

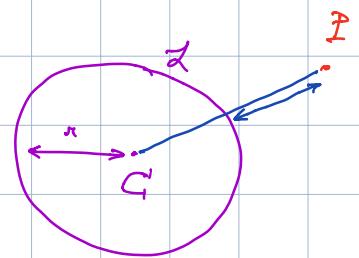
Oss: centro  $(r)$   $r \in \mathbb{R}$



Ten:  $r = \frac{1}{c}$  poiché  $\frac{\alpha''(0)}{\|\alpha''(0)\|^2} = \frac{(c)}{c^2} = (1/c)$ .

$$f(t) = d(\alpha(t), \mathcal{L}) = d(\alpha(t), (r)) - |r|$$

$$= \sqrt{x(t)^2 + (y(t) - r)^2} - |r|.$$



$$d(P, \mathcal{L}) = d(P, C) - r$$

controlla tralice:

$$f(0) = 0 \quad (\text{passo})$$

$$f'(0) = 0 \quad (\text{stessa tangente})$$

$$f''(0) = 0$$

} generalizzate

$$f'(t) = \frac{x(t) \cdot x'(t) + (y(t) - r) \cdot y'(t)}{\sqrt{x(t)^2 + (y(t) - r)^2}}$$

$$f''(t) = \frac{(x \cdot x' + (y - r) y')^2}{\sqrt{(x \cdot x' + (y - r) y')^2}} + \frac{x'^2 + x x'' + y'^2 + (y - r) y''}{\sqrt{(x \cdot x' + (y - r) y')^2}}$$

molti in  $t=0$   
ma rapporto tende a 0

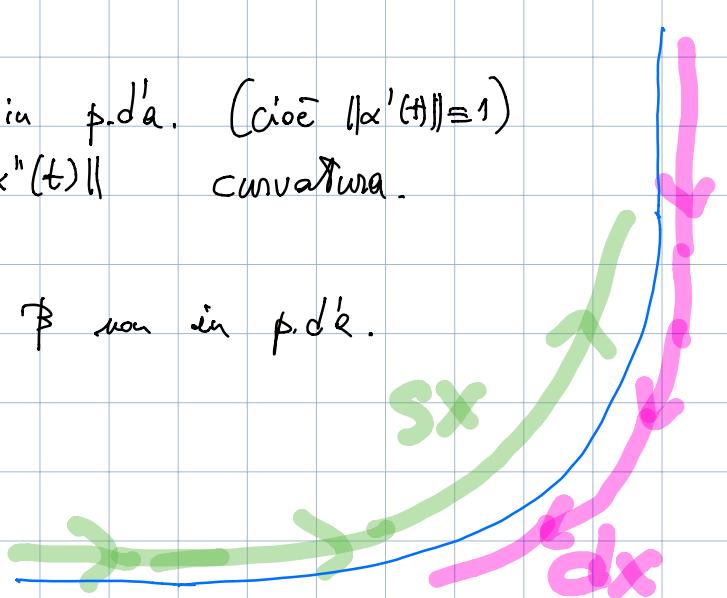
dove annullarsi

$$1 + 0 + 0 + (0 - r) \cdot c = 0. \quad \square$$

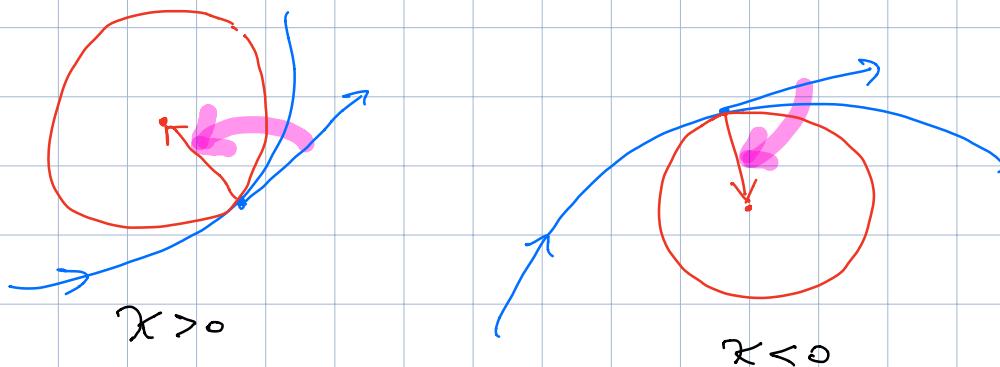
Recap: se  $\alpha$  è in p.d'a. (cioè  $\|\alpha'(t)\|=1$ )

$$K(t) = \|\alpha''(t)\| \quad \text{curvatura.}$$

Q: come calcolare per  $\beta$  non in p.d'a.



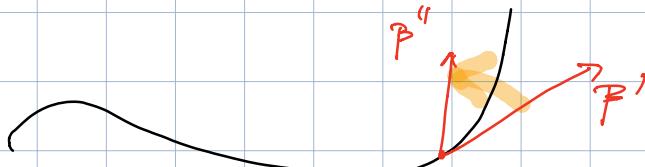
Def: diciamo che  $\alpha$  orientata ha curvatura positiva in  $\alpha(t_0)$  se l'angolo tra  $\alpha'(t_0)$  e la tangente di  $\alpha(t_0)$  con il centro della circ. osculatrice è il verso orario



Prop: se  $\beta$  è curva orientata qualsiasi la sua curvatura nel punto  $\beta(t)$  è

$$\frac{\det(\beta'(t), \beta''(t))}{\|\beta'(t)\|^3}.$$

Ydea:  $\alpha(s) = \beta(\sigma(s))$   $\|\alpha'(s)\| = 1$   $\sigma'(s) = \frac{1}{\|\beta'(s)\|}$   
 si calcula  $K = \|\alpha'(s)\|$  derivando ...



$$\gamma(t) = \beta(k \cdot t) \quad k \in \mathbb{R}$$

$$\frac{\det(\gamma'(t), \gamma''(t))}{\|\gamma'(t)\|^3} = \frac{\det(k \cdot \beta'(kt), k^2 \cdot \beta''(kt))}{\|k \cdot \beta'(kt)\|^3}$$

$$= \frac{\det(\beta', \beta'')}{\|\beta'\|^3}.$$

Prop: dati  $P_0 \in \mathbb{R}^2$ ,  $v_0 \in \mathbb{R}^2$ ,  $|v_0|=1$ ,  $K : [0, L] \rightarrow \mathbb{R}$   
 $\exists$  unica  $\alpha : [0, L] \rightarrow \mathbb{R}^2$  curva in p.d'a.  
 t.c.  $\alpha(0) = P_0$ ,  $\alpha'(0) = v_0$  con curvatura  
 $K(t)$  in  $\alpha(t)$   $\forall t$ .

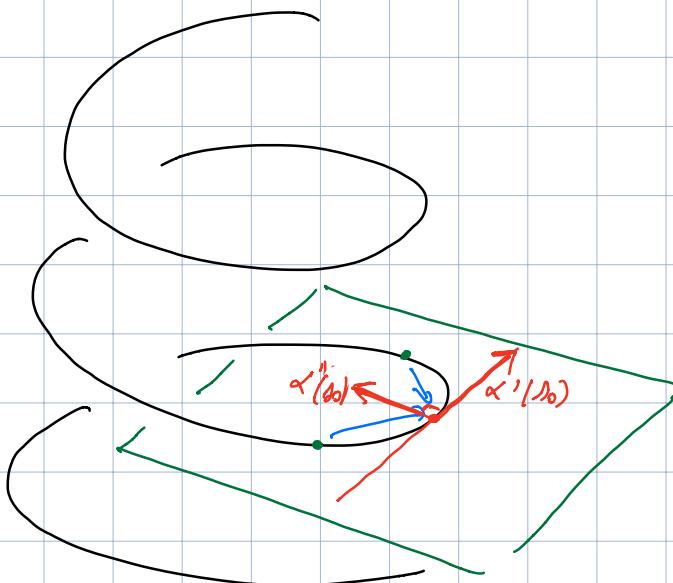


$$\alpha: [a, b] \rightarrow \mathbb{R}^3$$

- $\alpha'(t_0)$  de' rette tip.  
(contatto doppio)

- esiste un unico piano con contatto triplo  
(di solito)

e da tale piano grazie alla concavità  
con circonference con contatto tipiche:



Per  $\alpha$  in p.d'a.

piano:  $\alpha(t_0) + \text{Span}(\alpha'(t_0), \alpha''(t_0))$

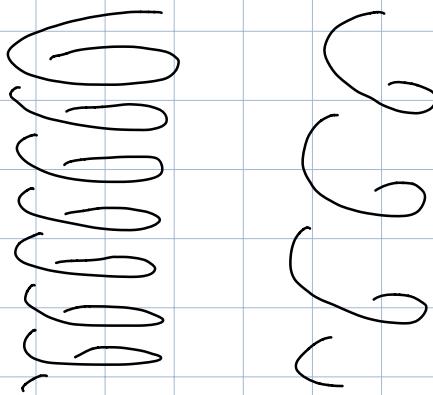
circosf: quelle per  $\alpha(t_0)$  con centro  $\alpha(t_0) + \frac{\alpha''(t_0)}{\|\alpha''(t_0)\|^2}$

$$\Rightarrow K(t_0) = \|\alpha''(t_0)\| \quad \text{curvatura}$$

Q: come si calcola  $K$  per  $\beta$  non il p.d'a?

Oss: nello spazio essa ha senso soprattutto di  $K$

curve col rotolo  
curvatura ma  
diverse mani-  
plamentate



Q: Come misurare la curvatura?

Def: chiamiamo riferimento di Frenet per  $\alpha$  nel punto  $s$  ( $t(s), n(s), b(s)$ ) in p.  $s$  ortonormale positiva

tangente normale binormale

$$t(s) = \alpha'(s)$$

$$( \|t(s)\| = 1 )$$

$$n(s) = \frac{\alpha''(s)}{\|\alpha''(s)\|}$$

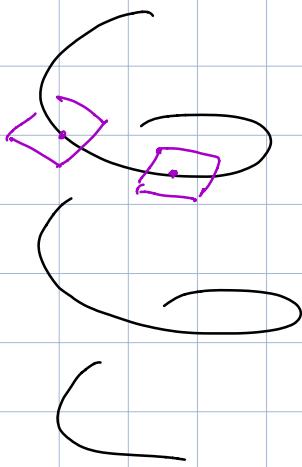
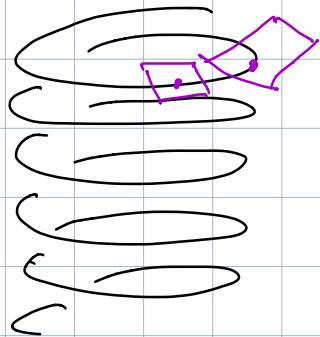
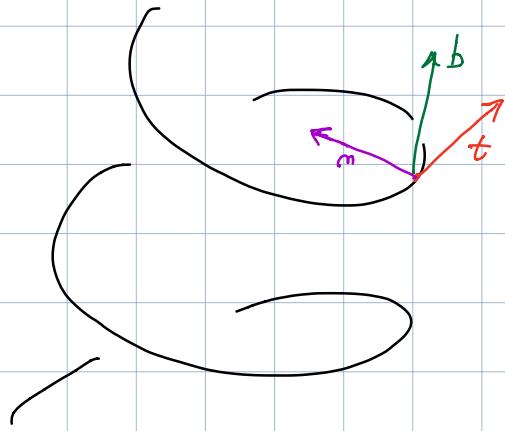
$$n(s) \perp t(s)$$

$$b(s) = t(s) \wedge n(s).$$

Oss: piano osculatore è

$$\text{Span}(t, n) = b^\perp$$

$\Rightarrow$  misura della curvatura è  $b'$



Prop: data  $\alpha: [a, b] \rightarrow \mathbb{R}^3$  i.p.d'a. esistono

$\kappa, \tau: [a, b] \rightarrow \mathbb{R}$  curvatura, torsione t.c.

$$\begin{cases} t' = \kappa \cdot m \\ m' = -\kappa \cdot t + \tau \cdot b \\ b' = -\tau \cdot m \end{cases}$$

Dim:  $t = \alpha'$   $m = \frac{\alpha''}{\|\alpha''\|} \Rightarrow \alpha'' = (\alpha')' = t'$

$$\|\alpha''\| \cdot m \Rightarrow \kappa = \|\alpha''\|$$

$$b = t \wedge m; \quad \|b\| = 1 \Rightarrow b' \perp b$$

$$b = t \wedge m \Rightarrow b' = t' \wedge m + t \wedge m'$$

$$= \underbrace{\kappa m \wedge m}_0 + t \wedge m' = t \wedge m'$$

$$\Rightarrow b' \perp t$$

$\Rightarrow b'$  multiplo di  $m$ ;

pongo  $\tau$  f.c.  $b' = -\tau \cdot m$ .

Ora:

$$m' = (b \wedge t)' = b' \wedge t + b \wedge t'$$

$$= -\tau \cdot m \wedge t + b \wedge \kappa \cdot m$$

$$= \underbrace{\kappa \cdot b \wedge m}_{-t} - \underbrace{\tau \cdot m \wedge t}_{-b}$$

$$= -\kappa \cdot t + \tau \cdot b.$$

( $t, m, b$ )

$$\begin{aligned} b &= t \wedge m \\ m &= b \wedge t \\ t &= m \wedge b \end{aligned}$$

□

Oss:

$$\begin{cases} t' = \kappa \cdot m \\ m' = -\kappa \cdot t + \tau \cdot b \\ b' = -\tau \cdot m \end{cases} \Rightarrow (t, m, b)' = \underbrace{(t, m, b)}_{\text{matr. orfog}} \cdot \underbrace{\begin{pmatrix} 0 & -\kappa & 0 \\ \kappa & 0 & -\tau \\ 0 & \tau & 0 \end{pmatrix}}_{\text{antisimm.}}$$

Prop:  $M: [a, b] \rightarrow M_{\text{max}}(\mathbb{R})$        $M(t)$  antis.  $\forall t$   
 $\Rightarrow M'(t) = M(t) \cdot A(t)$        $A(t)$  antisim.

Dim:  ${}^t M \cdot M = I_m$

$$\underbrace{{}^t M' \cdot M}_{{}^t A} + \underbrace{{}^t M \cdot M'}_A = 0 ; \quad M' = I_m \cdot M' = M \underbrace{{}^t M \cdot M'}_A$$

$\Rightarrow A$  antisimmetro □

Prop: Se  $\beta$  è curva qualiasi le sue curvature e tensione nel punto  $\beta(s)$  sono:

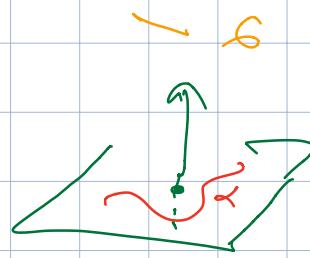
$$K(s) = \frac{\|\beta'(s) \wedge \beta''(s)\|}{\|\beta'(s)\|^3} \quad T(s) = \frac{\langle \beta'(s) \wedge \beta''(s) | \beta'''(s) \rangle}{\|\beta'(s) \wedge \beta''(s)\|^2}$$

Oss  $\sigma(s) = \beta(s, s)$

$$\frac{\langle \sigma' \wedge \sigma'' | \sigma''' \rangle}{\|\sigma' \wedge \sigma''\|^2} = \frac{\langle (k\beta' \wedge k^2\beta'' | k^3\beta''' \rangle}{\|k\beta' \wedge k^2\beta''\|^2} \xrightarrow{6}$$

Oss:  $\alpha: [a, b] \rightarrow \mathbb{R}^2$  qualiasi:

$$\beta = \begin{pmatrix} \alpha \\ 0 \end{pmatrix}$$



$$\frac{\det(\alpha', \alpha'')}{\|\alpha'\|^3} \quad \frac{\|\beta' \wedge \beta''\|}{\|\beta'\|^3}$$

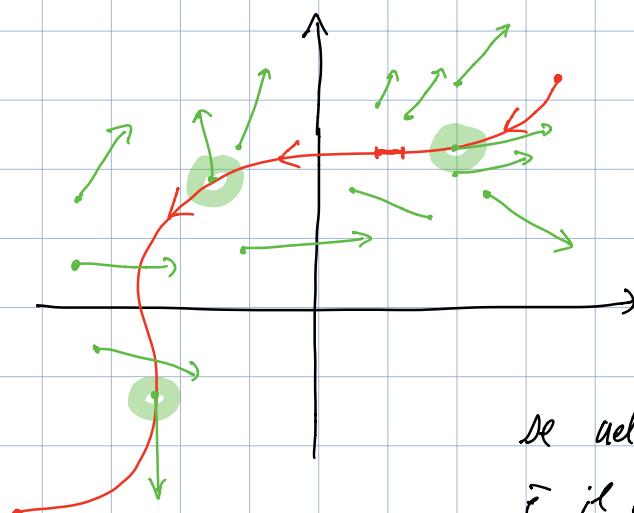
$$\alpha = \begin{pmatrix} x \\ y \end{pmatrix} \quad \beta = \begin{pmatrix} x' \\ y' \end{pmatrix}$$

$$\|\beta' \wedge \beta''\| = \left\| \begin{pmatrix} x' \\ y' \end{pmatrix} \wedge \begin{pmatrix} x'' \\ y'' \end{pmatrix} \right\| = \left\| \begin{pmatrix} 0 \\ x'y'' - y'x'' \end{pmatrix} \right\|$$

$$= |x'y'' - y'x''| = \left| \det \begin{pmatrix} x' & x'' \\ y' & y'' \end{pmatrix} \right|$$

————— o —————

1-forme e loro integrazione



Se nel punto  $(x, y)$  il vettore

$\vec{v} = (f(x, y), g(x, y))$  è

centro di un campo vettoriale

nel punto  $\alpha(t) = (X(t), Y(t))$  è

$$\int f(X(t), Y(t)) \cdot X'(t) dt + g(X(t), Y(t)) \cdot Y'(t) dt$$

Dato  $\Omega \subset \mathbb{R}^2$  aperto chiuso 1-forme su  $\Omega$  su

oggetto  $\omega = f \cdot dx + g \cdot dy$

$$\omega(x, y) = f(x, y) \cdot dx + g(x, y) \cdot dy$$

con  $f, g : \Omega \rightarrow \mathbb{R}$ .

spontaneo: elementi  
nelle due direzioni

Su  $\Omega$  c'è campo vettoriale  $(\begin{matrix} f \\ g \end{matrix})$

Se  $\alpha : [a, b] \rightarrow \mathbb{R}^2$  piano

$$\int_{\alpha} \omega = \int_a^b (f(\alpha(t)) \cdot X'(t) + g(\alpha(t)) \cdot Y'(t)) dt.$$

ATTENZIONE

$F : \Omega \rightarrow \mathbb{R}$

$$\int_{\alpha} F = \int_a^b F(\alpha(t)) \cdot \|\alpha'(t)\| dt$$

integrale di  
funzione scalare

$f, g : \Omega \rightarrow \mathbb{R}$

$$\int_{\alpha} f dx + g dy = \int_a^b (f(\alpha(t)) \cdot X'(t) + g(\alpha(t)) \cdot Y'(t)) dt$$

integrale di  
1-forma ( $10 \|\alpha'(t)\|$ )