

Geom 17/5/2017

13. 4.1

ERRATA

close

c) $(+ - +) -$

$$x^2 - y^2 + z^2 - 1 = 0$$

$$x^2 + z^2 = y^2 + 1$$

NOL

iperboloidi a 2 folde

MA

" a 1 folde



$$d) \quad 2x^2 + y^2 + z^2 + 2xy - 4yz + 6z = 0$$

$$\begin{pmatrix} 2 & 1 & 0 & 0 \\ 1 & 1 & -2 & 0 \\ 0 & -2 & 1 & 3 \\ 0 & 0 & 3 & 0 \end{pmatrix}$$

$$d_1 \geq 0$$

$$d_2 > 0$$

$$d_3 = 2(-3) - 1 \cdot 3 = -9 < 0$$

$$d_4 = -3 \cdot [2 \cdot 3 - 1 \cdot 3] = -9 < 0$$

Ans. $(+ + -) +$

$$x^2 + y^2 - z^2 + 1 = 0$$

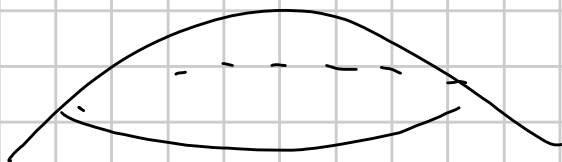
ciol

$$z^2 = x^2 + y^2 + 1$$



1 hyperboloid a

2 folde



(g)

$$\begin{pmatrix} 1 & 1 & 0 & -2 \\ 1 & 2 & -2 & 1 \\ 0 & -2 & 5 & 0 \\ -2 & 1 & 0 & 0 \end{pmatrix}$$

$$d_1 > 0$$

$$d_2 > 0$$

$$d_3 = 10 - 4 - 5 > 0$$

$$d_4 = \det \begin{pmatrix} 3 & 1 & 0 & -2 \\ 5 & 2 & -2 & 1 \\ -4 & -2 & 5 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} =$$

$$= \det \begin{pmatrix} 3 & 0 & -2 \\ 5 & -2 & 1 \\ -4 & 5 & 0 \end{pmatrix} = -2(17) - 15 < 0$$

Autovel (+ + +) -

$$x^2 + y^2 + z^2 - 1 = 0$$

elipse

$$(m) \begin{pmatrix} 1 & 1 & -k & 0 \\ 1 & 5 & k & 0 \\ -k & k & k^2 + 9 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$d_1 > 0$$

$$d_2 > 0$$

$$d_3 = 5k^2 + 45 - k^2 - k^2 - 5k^2 - k^2 - 9 - k^2$$

$$= 36 - 4k^2 = 4(9 - k^2)$$

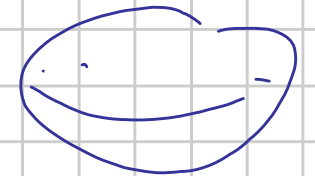
Ultimo autovelocidade é sempre -1

$$\text{Se } g - k^2 > 0$$

$$+ + + -$$

, over $|K| < 3$

ellipsoid



$$\text{Se } g - k^2 = 0$$

$$+ + 0 -$$

$$|K| = 3$$

cylinder

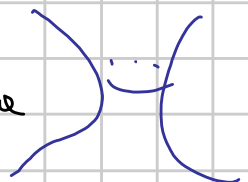


$$\text{Se } g - k^2 < 0$$

$$+ + - -$$

$$|K| > 3$$

hyperboloid a 2 del 1^a



$$(P) \begin{pmatrix} 1 & 1 & 0 & -1 \\ 1 & 2 & k & -1 \\ 0 & k & k^2 - 1 & 0 \\ -1 & -1 & 0 & 1 - k^2 \end{pmatrix}$$

$$d_1 > 0$$

$$d_2 > 0$$

$$d_3 = 2k^2 - 2 - k^2 + 1 - k^2 = -1 < 0$$

$$d_4 = \dots = k$$

$$k > 0 \quad \text{Antos.} \quad + \quad + \quad - \quad -$$

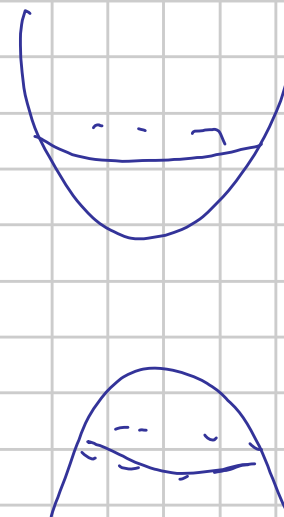
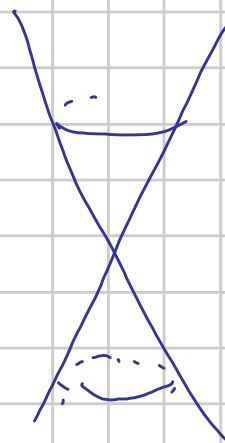
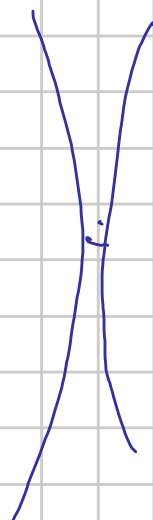
$$k = 0 \quad \text{Antos.} \quad + \quad + \quad - \quad 0$$

$$k < 0 \quad \text{Antos.} \quad + \quad + \quad - \quad +$$

iperb. a 1 folde

cono

iperb. a 2 folde



$$(9) \begin{pmatrix} 1 & -k & 0 & -2 \\ -k & k^2+k & k & 2k \\ 0 & k & k+1 & k \\ -2 & 2k & k & k^2+3 \end{pmatrix}$$

$$d_1 > 0$$

$$d_2 = k$$

$$d_3 = \dots = k$$

$$d_4 = \dots = -k$$

$$k > 0$$

Antwort

$(+ + +) -$ ellipsoide

$$k < 0$$

Antwort

$(+ - +) -$ hyperbolisches 1-feld

14.1.4

Dire a curve param. α, β definites
la steme curve orientate -

$$\alpha: [0, 1] \rightarrow \mathbb{R}^2$$

$$\alpha(t) = (\cos(\pi t), \sin(\pi t))$$

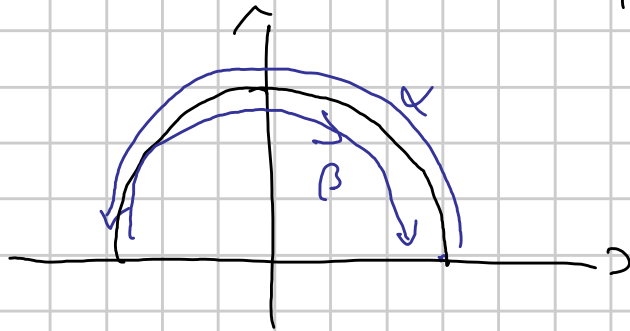
$$\beta: [-1, 1] \rightarrow \mathbb{R}^2$$

$$\beta(t) = (t, \sqrt{1-t^2})$$

β' non è continua in $\lim_{t \rightarrow -1} \beta'(t) = (1, +\infty)$

In $(-1, 1)$ aperto β è regolare -

$$\text{Im } \alpha = \text{Im } \beta = \{ (x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1, y \geq 0 \}$$



α, β non definiscono la
stessa curva orientata

$$\alpha\left(\frac{1}{2}\right) = \beta(0) = (0, 1)$$

$$\beta'(0) = (1, 0)$$

$$\alpha'(0) = \left(-\frac{\pi}{2}, 0\right)$$

derivate di segno
opposto

quindi posso parametrizzare α in β , ma

il cambio di parametro ha derivata < 0 -

Dove se $\beta(s) = \alpha(\tau(s))$

$$\beta'(s) = \alpha'(\tau(s)) \cdot \tau'(s) =$$

$$= \alpha\left(\frac{1}{2}\right) \tau'(s)$$

$$\tau'(s) = -\frac{\pi}{2} < 0$$

14.1.5

$$\alpha: [0, 2\pi] \rightarrow \mathbb{R}^3$$

$$\alpha(t) = \begin{pmatrix} \sin t \\ \cos t \\ t^2 \end{pmatrix}$$

$$\beta: [0, \pi] \rightarrow \mathbb{R}^3$$

$$\beta(t) = \begin{pmatrix} \sin 2t \\ \cos 2t \\ 4t^2 \end{pmatrix}$$

ovvero $\beta(t) = \alpha(2t)$, cioè dato

$$\tau: [0, \pi] \rightarrow [0, 2\pi] \quad \tau(t) = 2t$$

$$\beta(t) = \alpha(\tau(t)) \Rightarrow L(\alpha) = L(\beta)$$

perché β è ~~stessa~~ α per cambio di

parameter

$$\alpha'(t) = \begin{pmatrix} \cos t \\ -\sin t \\ 2t \end{pmatrix}$$

$$L(\alpha) = \int_0^{2\pi} \|\alpha'(t)\| dt =$$

$$= \int_0^{2\pi} \sqrt{1 + 4t^2} dt$$

14.1.6

Calculator

$$\int \sqrt{1 + x^2 + y^2}$$

$$\alpha: [0, 1] \rightarrow \mathbb{R}^2$$

$$\alpha(t) = \begin{pmatrix} t \cos t \\ t \sin t \end{pmatrix}$$

$$\alpha'(t) = \begin{pmatrix} \cos t & -t \sin t \\ \sin t & t \cos t \end{pmatrix}$$

$$\|\alpha'(t)\| = \sqrt{1+t^2}$$

$$\int_0^1 \sqrt{1+x^2+y^2}^2 = \int_0^1 \sqrt{1+t^2 \cos^2 t + t^2 \sin^2 t} \cdot \|\alpha'(t)\| dt =$$

$$= \int_0^1 \sqrt{1+t^2} \cdot \sqrt{1+t^2} dt = \int_0^1 (1+t^2) dt =$$

$$= \left(t + \frac{t^3}{3} \right) \Big|_0^1 = \frac{4}{3}$$

14.1.3

$$\alpha: [0, 1] \rightarrow \mathbb{R}^2$$

$$\alpha(t) = \begin{pmatrix} t \\ e^t \end{pmatrix}$$

$$\alpha'(t) = \begin{pmatrix} 1 \\ e^t \end{pmatrix}$$

$$\int_{\alpha} \sqrt{1+y^2} = \int_0^1 \sqrt{1+e^{2t}} \cdot \sqrt{1+e^{2t}} dt =$$

$$= \int_0^1 (1+e^{2t}) dt = \left(t + \frac{e^{2t}}{2} \right) \Big|_0^1 = 1 + \frac{1}{2}e^2 - \frac{1}{2} =$$

$$= \frac{1}{2}(e^2 - 1)$$