

Es. geom. 10/3/2017

(9.1.8) Dato $A \in M_{n \times n}(\mathbb{R})$

B definita da $b_{ij} = (-1)^{i+j} a_{ij}$

A determina un p. scalare sse lo fa B .

• A simmetrica $\Leftrightarrow B$ simmetrica

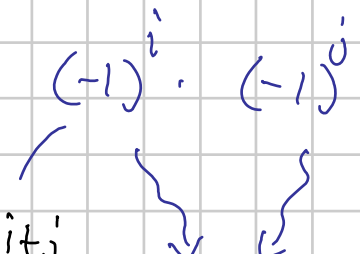
$$a_{ij} = a_{ji}$$

$$\begin{aligned} b_{ij} &= b_{ji} \\ (-1)^{i+j} a_{ij} &= (-1)^{i+j} a_{ji} \end{aligned}$$

* A def. pos $\Leftrightarrow B$ def. pos.

$$\begin{aligned} \langle x | x \rangle_A &= \sum_{i=1}^n x_i (A \cdot x)_i \\ &= \sum_{i=1}^n x_i \sum_{j=1}^n a_{ij} x_j \\ &= \sum_{i,j=1}^n a_{ij} x_i x_j \end{aligned}$$

$$\langle x | x \rangle_B = \sum_{i,j=1}^n b_{ij} x_i x_j = \sum_{i,j=1}^n (-1)^{it_j} a_{ij} x_i x_j$$

$(-1)^{it_j}$ $(-1)^{jt_i}$


Pongy. $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$(\mathbb{T}x)_i = (-1)^i x_i$$

$$\mathbb{T}: \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \longmapsto \begin{pmatrix} -x_1 \\ x_2 \\ -x_3 \\ x_4 \\ \vdots \\ (-1)^n x_n \end{pmatrix}$$

$$> \langle x | x \rangle_B = \langle \mathbb{T}x | \mathbb{T}x \rangle_A$$

Si come $\mathbb{T}$ invertibile

$$(\mathbb{T}^{-1} = \mathbb{T})$$

$$\langle x | x \rangle_B > 0 \quad \forall x \neq 0$$

$$\langle x | x \rangle_A > 0 \quad \forall x \neq 0$$

(9.1.9) Dati $v_1, \dots, v_n \in \mathbb{R}^n$ $A \in M_{n \times n}(\mathbb{R})$

$$a_{ij} = \langle v_i | v_j \rangle_{\mathbb{R}^n} \quad (A \text{ è determinata dai vettori})$$

Per quali ipotesi per i vett. $v_1, \dots, v_n$
 $\langle \cdot | \cdot \rangle_A$ è p. scalare in $\mathbb{R}^n$?

$$\bullet \quad a_{ij} = \langle v_i | v_j \rangle_{\mathbb{R}^n} = \langle v_j | v_i \rangle_{\mathbb{R}^n} = a_{ji}$$

$\Rightarrow A$ è sempre simm.

$$\bullet \quad \text{Def pos} \quad \langle x | x \rangle_A = \sum_{i,j=1}^n a_{ij} x_i x_j =$$

$$= \sum_{i,j=1}^n \langle v_i | v_j \rangle_{\mathbb{R}^n} x_i x_j =$$

$$= \left\langle \underbrace{\sum_{i=1}^n v_i x_i} \mid \underbrace{\sum_{j=1}^n v_j x_j} \right\rangle =$$

$$= \left\| \sum_{i=1}^n x_i v_i \right\|_{\mathbb{R}^n}^2 \geq 0 \text{ sempre} \quad \overset{\text{se}}{\sum_{i=1}^n x_i v_i = 0}$$

A def. pos. quando $x = 0 \in \mathbb{R}^n$ l'unico
 $x \in \mathbb{R}^n$ t.c. $\sum_{i=1}^n x_i v_i = 0$ cioè se

$v_1, \dots, v_n$ sono lin. indep., cioè se sono bese.

(9.2.1) V sp. vett su $\mathbb{R}$, e $f: V \times V \rightarrow \mathbb{R}$

forma bilineare simmetrica, definiamo la

forma quadratica $q: V \rightarrow \mathbb{R}$ associata

ed f $q(v) := f(v, v)$

Dato $q(v)$ trovare f associata

ovvero se conosco $\langle v | v \rangle$ voglio

trovare $\langle v | w \rangle$

(e) $V = \mathbb{R}^2$ $q(x) = 3x_1^2 + 2x_1x_2 - x_2^2$

$$A = \begin{pmatrix} 3 & \boxed{1} \\ \boxed{1} & -1 \end{pmatrix} \leftarrow \text{detour par 2} =$$

$$v = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\langle v | v \rangle_A = 3x_1^2 + \underbrace{x_1 x_2} + \underbrace{x_1 x_2} - x_2^2 =$$

$$= q(v)$$

$$(b) \quad V = \mathbb{R}^3$$

$$q(x) = \underline{-2x_1^2} + \underline{x_2^2} - \underline{5x_3^2} - x_1 x_2$$

$$+ 3x_1 x_3 + 2x_2 x_3$$

$$A = \begin{pmatrix} -2 & -1/2 & 3/2 \\ -1/2 & 1 & 1 \\ 3/2 & 1 & -5 \end{pmatrix}$$

$$(c) \quad V = M_{2 \times 2}(\mathbb{R}) \quad g(A) = \det(A) =$$

$$g(A, B) = \frac{1}{2} (a_{11}b_{22} + a_{22}b_{11}) + \frac{1}{2} (a_{12}b_{21} + a_{21}b_{12}) + \frac{1}{2} (a_{11}a_{22} - a_{12}a_{21})$$

$$g \text{ is symmetric.} \quad g(A, A) = g(A)$$

$$(e) \quad V = \mathbb{R}_{\leq 2}[t] \quad g(p(t)) = p(1) \cdot p(-2)$$

$$J(p(t), z(t)) = \frac{1}{2} (p(1)z(-2) + p(-2)z(1))$$

(3.2.2) Su $V = \mathbb{R}_{\leq 2}[t]$, p. valore:

$$\langle p(t) | q(t) \rangle = p(0)q(0) + p(1)q(1) + p(2)q(2)$$

(oss. : è def. positivo : $\langle p(t) | p(t) \rangle \geq 0$)

$$\Rightarrow p(0)^2 + p(1)^2 + p(2)^2 \geq 0$$

$$\Rightarrow p(0) = p(1) = p(2) = 0 \quad \Rightarrow p = 0$$

(un pol. di grado n è determinato dal valore in $n+1$ punti)

Trovare un polinomio $p(t)$ di norma $\sqrt{5}$,
ortogonale a $1+t$, $1+t^2$ -

Intanto $\hookrightarrow$ cerco ortogonale, poi sistemo la
norma

$$\langle p(t) | 1+t \rangle = 0$$

$$\langle p(t) | 1+t^2 \rangle = 0$$

$$p(t) = a_0 + t a_1 + t^2 a_2$$

$$p(0) = a_0$$

$$p(1) = a_0 + a_1 + a_2$$

$$p'(2) = a_0 + 2a_1 + 4a_2$$

$$\left\{ \begin{array}{l} a_0 \cdot 1 + (a_0 + a_1 + a_2) \cdot 2 + (a_0 + 2a_1 + 4a_2) \cdot 3 = 0 \\ a_0 \cdot 1 + (a_0 + a_1 + a_2) \cdot 2 + (a_0 + 2a_1 + 4a_2) \cdot 5 = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} a_0 \cdot 1 + (a_0 + a_1 + a_2) \cdot 2 + (a_0 + 2a_1 + 4a_2) \cdot 3 = 0 \\ a_0 \cdot 1 + (a_0 + a_1 + a_2) \cdot 2 + (a_0 + 2a_1 + 4a_2) \cdot 5 = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} q_2 + 2q_1 + 4q_2 = 0 \\ 3q_2 + 2q_1 + 2q_2 = 0 \end{array} \right.$$

$$Q = \begin{pmatrix} 4 \\ -10 \\ 4 \end{pmatrix} \quad \begin{pmatrix} 2 \\ -5 \\ 2 \end{pmatrix}$$

$$p(t) = 2 - 5t + 2t^2$$

$$\|p(t)\|^2 = p(0)^2 + p(1)^2 + p(2)^2 = 4 + 1 + 0 = 5$$

$$\|p(t)\| \approx \sqrt{5}$$

$p(t)$ è il pol. cercato.

(9.2.3) Def. 1. Funktion $\mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$

$$SNCF(x, y) := \begin{cases} \|x - y\| & \text{wenn } x, y \text{ lin. dep.} \\ \|x\| + \|y\| & \text{wenn } x, y \text{ indep.} \end{cases}$$

$$NYC(x, y) := \sum_{j=1}^n |x_j - y_j|$$

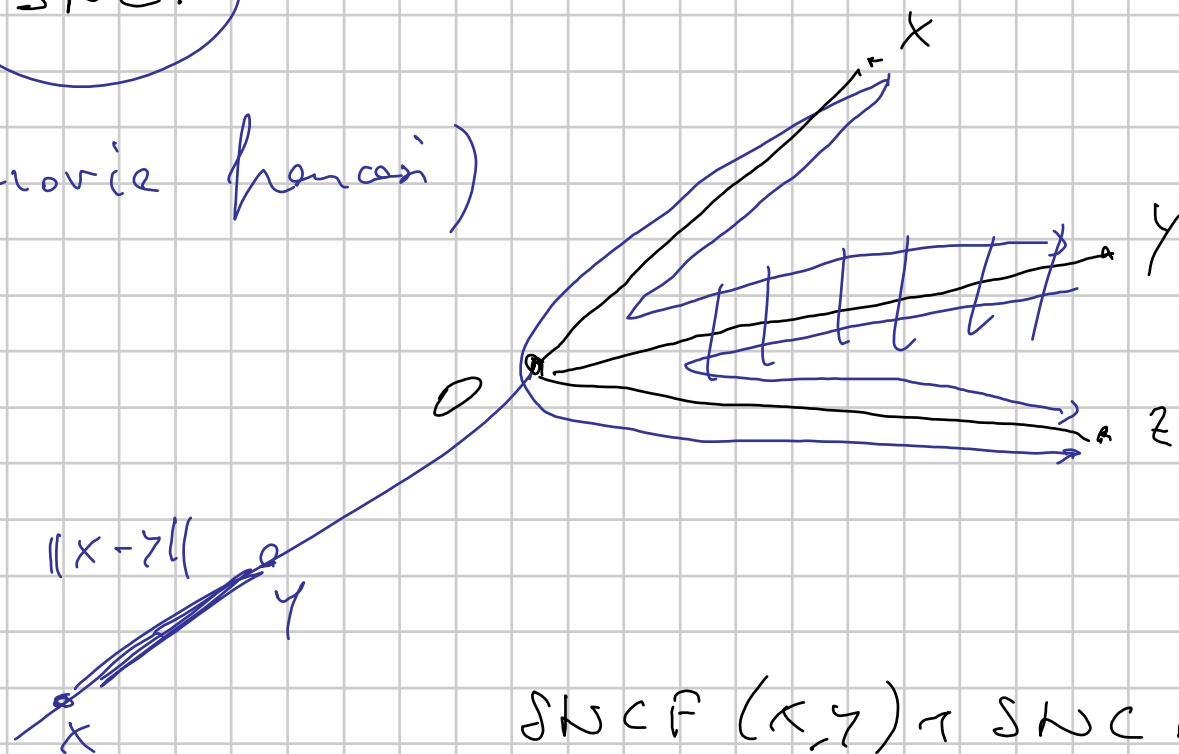
SNCF $\in$ NYC $\hookrightarrow$ distance

kl. , sim. OK

Dim. zue. gl. anse $\hookrightarrow$ an. gehen

SNCF

(ferrovie francesi)



triangolare.

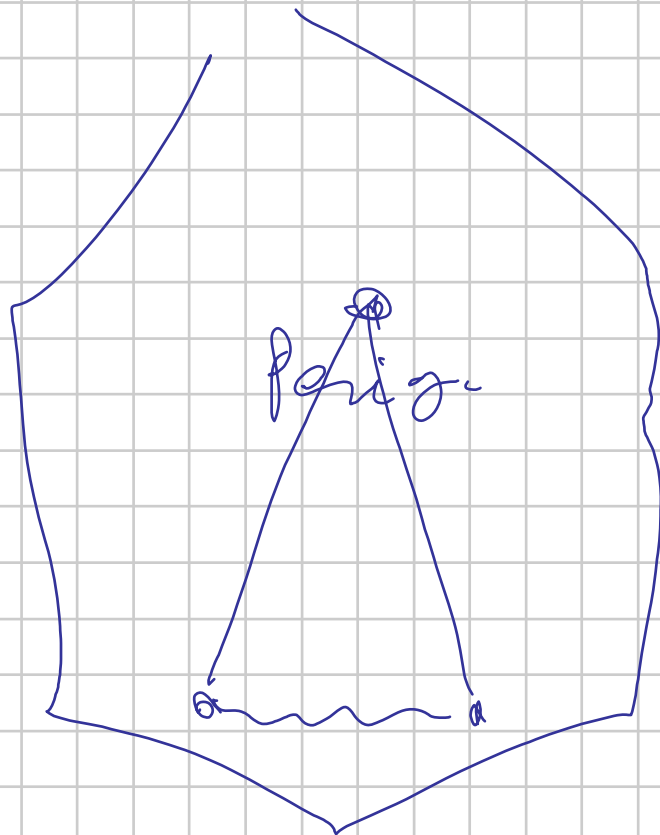
dividiamo per
caso: x, y allineati?

e z n,

x, y, z non

allineati, --

$$SNCF(x, y) + SNCF(y, z) = SNCF(x, z)$$



NYC