

ANALISI MATEMATICA (B)

LEZIONE 77

(8.4.2020)

ES

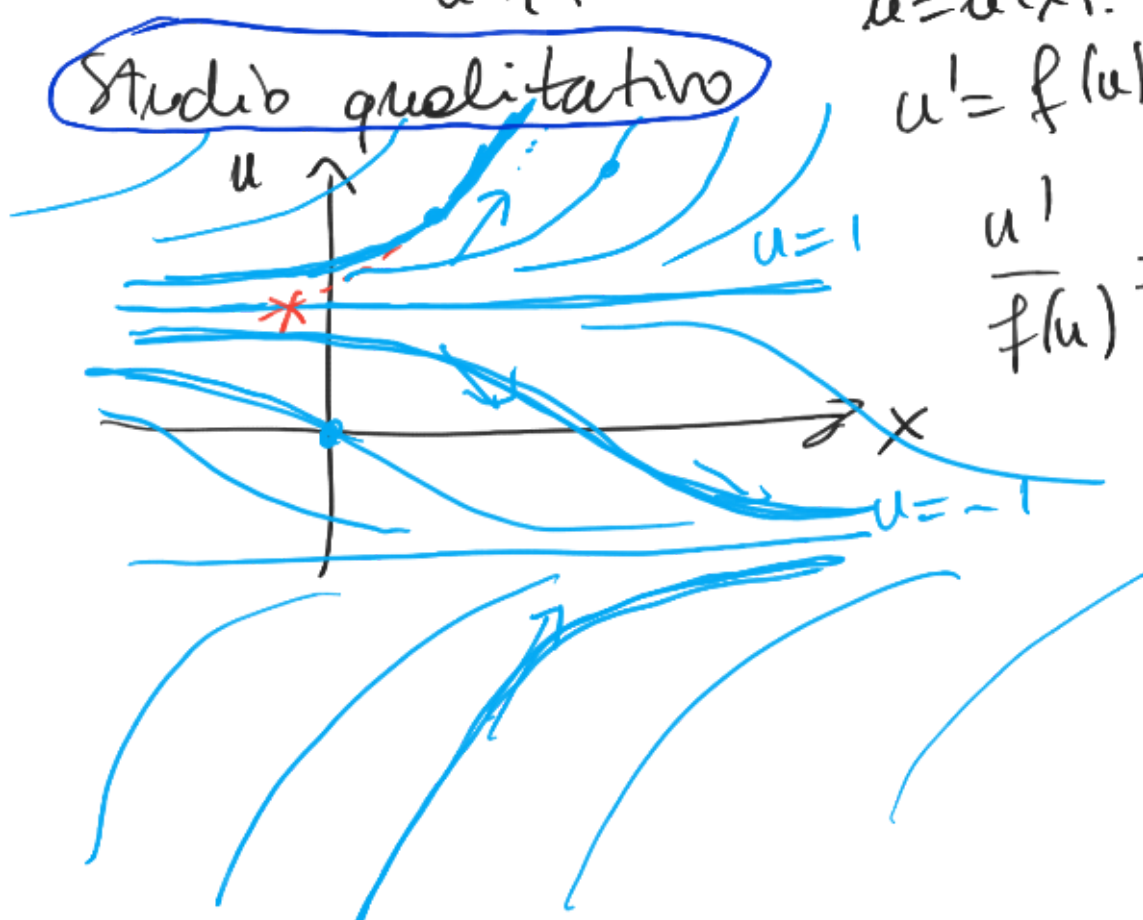
$$u' = \frac{u^2 - 1}{u^2 + 1}$$

Eq. autonoma
 $u = u(x)$.

$$u' = f(u)$$

Studio qualitativo


$$\frac{u'}{f(u)} = 1.$$



Orli zeri di f corrispondono
a soluzioni arbitrarie
(costanti) ||

$$\frac{u^2 - 1}{u^2 + 1} = 0 \quad \begin{cases} u = 1 \\ u = -1 \end{cases}$$


$$u = u(x) \quad u'(x) = \frac{u^2(x) - 1}{u^2(x) + 1} \quad \left\| \leftarrow \right.$$

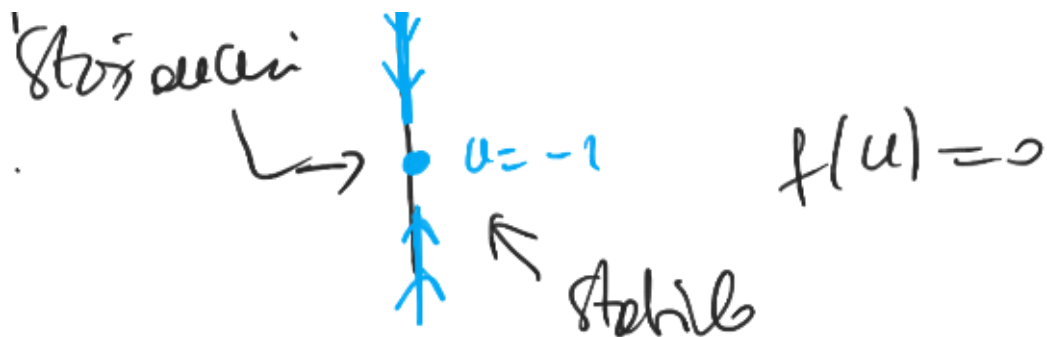
ES Se $u^{(v)}$ è una soluzione
 $u(x) > 1$ è crescente
 limit $u(x) = l$ esiste
 $x \rightarrow -\infty$

Dimostrare che $l = 1$

Se $u'(x) = f(x, u(x))$



multi- \rightarrow  u
 instabile $u' = f(u)$
 $u = 1$ $f(u) = 0$

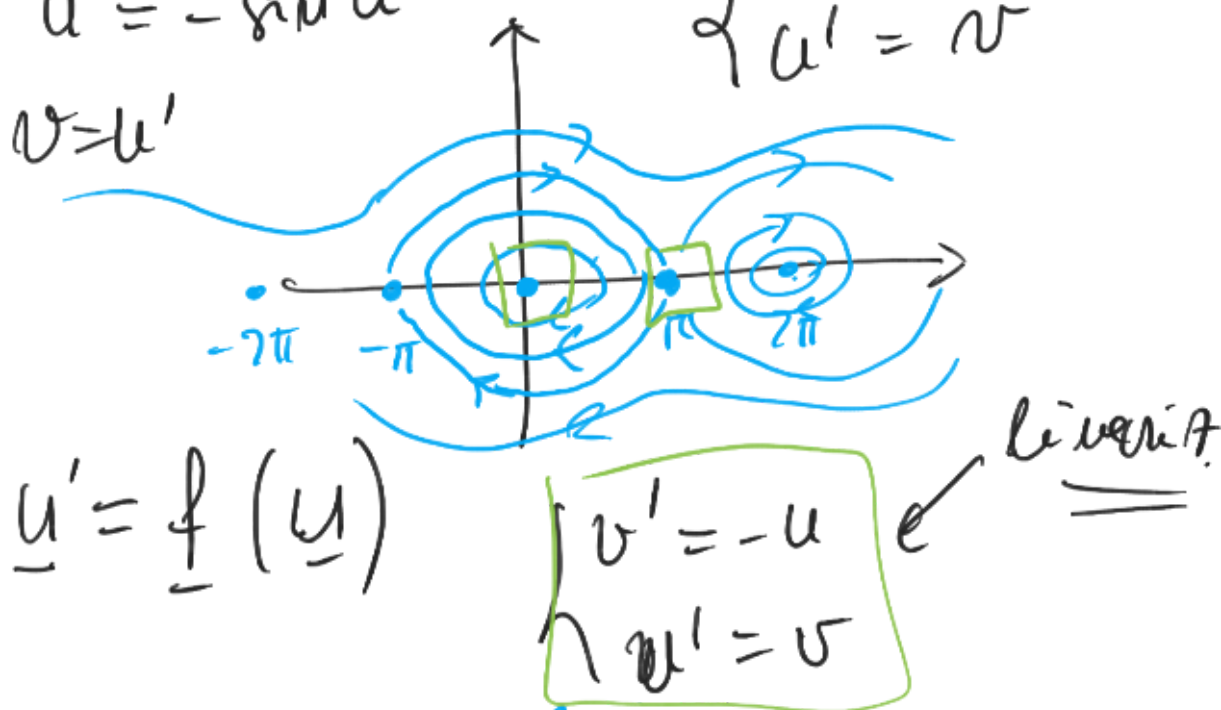


Sistemi di equazioni del I ordine

$u'' = -\sin u$

$v = u'$

$$\begin{cases} v' = -\sin u \\ u' = v \end{cases}$$



Sistemi lineari del I ordine

a coefficienti costanti (omogeneo.)

$$\underline{u}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

2 equazioni
2 incognite

$$\begin{cases} x'(t) = a \cdot x(t) + b \cdot y(t) \\ y'(t) = c \cdot x(t) + d \cdot y(t) \end{cases}$$

$\leftarrow \underline{u} \in \mathbb{R}^2$

$$\underline{u}'(t) = A \cdot \underline{u}(t).$$

$\underline{u} \in \mathbb{R}^n$

Sistemi
 $n \times n$

$$\underline{u}'(t) - A \cdot \underline{u}(t) = 0$$

$$e^{-At} \cdot \underline{u}'(t) - e^{-At} \cdot A \cdot \underline{u}(t) = 0$$

$$\left(e^{-At} \cdot \underline{u}(t) \right)' = 0$$

$$e^{-At} \cdot \underline{u}(t) = \underline{u}_0$$

$$\underline{u}(t) = e^{At} \cdot \underline{u}_0$$

$$e^{At} = \sum_{k=0}^{+\infty} \frac{(At)^k}{k!}$$

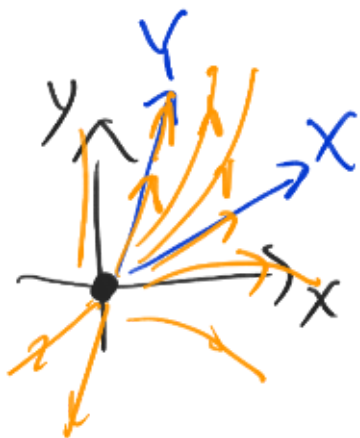
Sistemi 2×2

$$\begin{cases} x'(t) = a x(t) + b y(t) \\ y'(t) = c x(t) + d y(t) \end{cases}$$

$$\begin{pmatrix} x \\ y \end{pmatrix}'(t) = A \cdot \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

Cambiamo stepwise delle variabili "migliori".



$$\begin{pmatrix} X \\ Y \end{pmatrix} = M \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} X \\ Y \end{pmatrix}' = M \begin{pmatrix} x' \\ y' \end{pmatrix}$$

$$= M A \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= \underbrace{M A M^{-1}}_B \begin{pmatrix} X \\ Y \end{pmatrix}$$

$$\begin{pmatrix} X \\ Y \end{pmatrix}' = B \begin{pmatrix} X \\ Y \end{pmatrix} \quad B \sim A.$$

Si sono λ, μ gli autovalori di A .

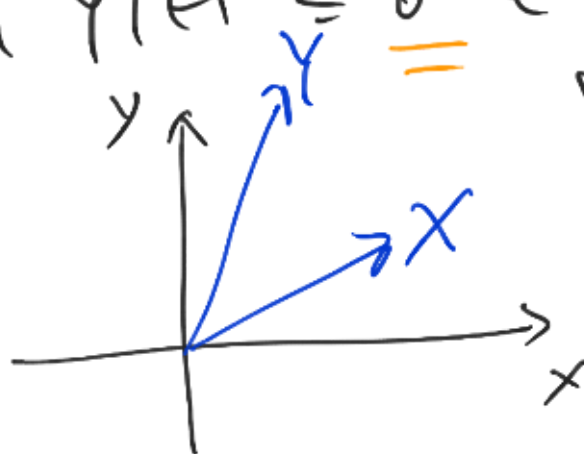
(soluzioni di $\det(A - tI) = 0$)

① Se λ, μ sono reali distinte

$$A \sim \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}$$

$$\begin{cases} X' = \lambda X \\ Y' = \mu Y \end{cases}$$

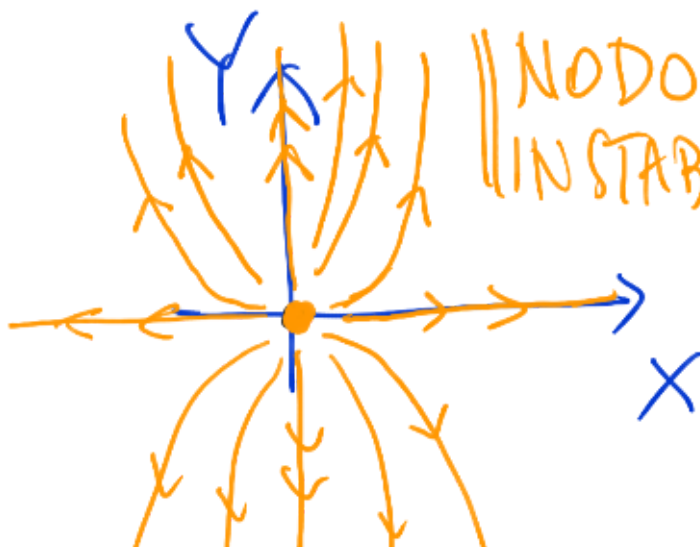
$$\begin{cases} X(t) = a \cdot e^{\lambda t} \\ Y(t) = b \cdot e^{\mu t} \end{cases}$$



$$Y(t) = b \cdot (e^{\lambda t})^{\frac{\mu}{\lambda}}$$

$$Y = \pm b \left(\frac{|X|}{|a|} \right)^{\frac{\mu}{\lambda}}$$

$$Y = k \cdot |X|^{\frac{\mu}{\lambda}}$$



NODO
INSTABILE $\mu, \lambda > 0$
 $\mu > \lambda$

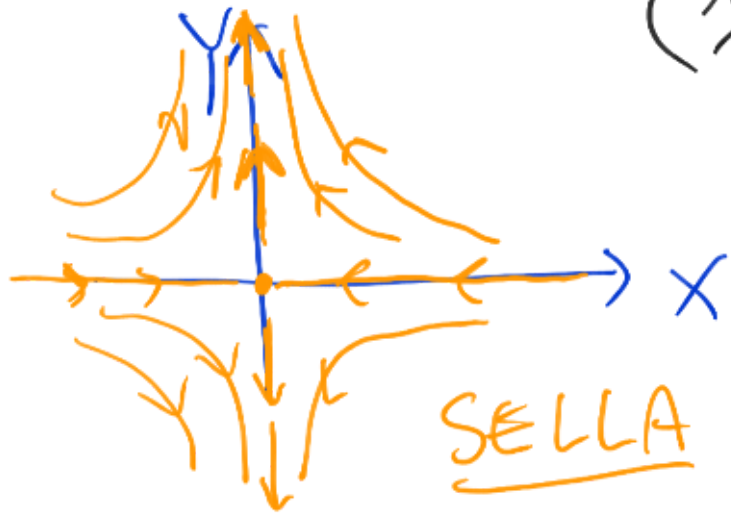
$\mu, \lambda < 0$
NODO
STABILE

|||||

INSTABILE

$\lambda < 0 < \mu$

($\lambda = 0$ o $\mu = 0$)
CASI
DEGENERI



SELLA (INSTABILE)

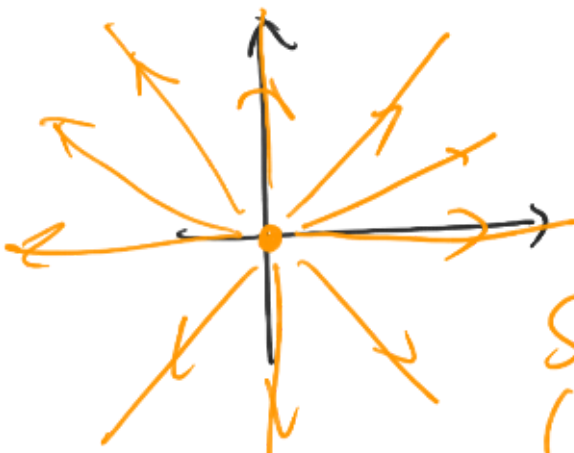
(2) Autovalori reali coincidenti

$\lambda = \mu$

(2a) se A è diag. bile:

$A = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$

$\begin{cases} x' = \lambda x \\ y' = \lambda y \end{cases} \quad \begin{cases} x(t) = a e^{\lambda t} \\ y(t) = b e^{\lambda t} \end{cases}$



$\lambda > 0$



STELLA
(INSTABILE)

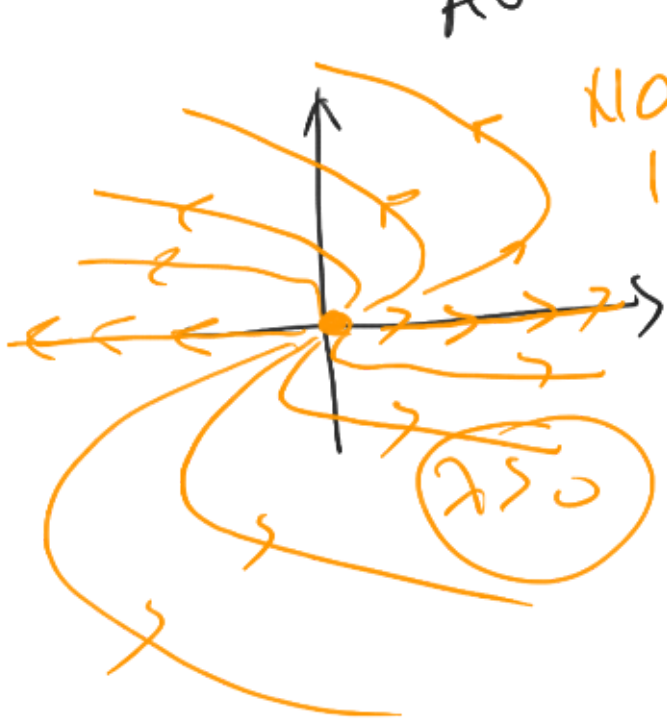
(26) A non è diag. bilib:

$$A \sim \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$$

↑ autovettore v
↑ autovettore w

$$Av = \lambda v$$

generalizzato w
 $Aw = \lambda w + v$



NO DO (INSTABILE)
IMPROPRIO

$$\begin{cases} X' = \lambda X + Y \\ Y' = \lambda Y \end{cases}$$

$$Y = b \cdot e^{\lambda t}$$

$$\boxed{\begin{matrix} b=0 & Y=0 \\ X = a \cdot e^{\lambda t} \end{matrix}}$$

3. Autovalori complessi coniugati

$$\lambda = \alpha - i\beta, \quad \underline{v} + i\underline{w} \text{ autovettore complesso}$$

$$\mu = \alpha + i\beta, \quad \underline{v} - i\underline{w}$$

$$\Lambda (\cos \dots) (\alpha - i\beta) (\alpha + i\beta)$$

$$A(\underline{v}, \underline{w}) = \dots$$

Allora $A(\underline{v} - i\underline{w}) = (d + i\beta)(\underline{v} - i\underline{w})$

$$A \sim \begin{pmatrix} d - i\beta & 0 \\ 0 & d + i\beta \end{pmatrix} \sim \begin{pmatrix} \rho \cos \theta & -\rho \sin \theta \\ \rho \sin \theta & \rho \cos \theta \end{pmatrix}$$

(Forma di Jordan reale)

$$\begin{cases} A\underline{v} = d\underline{v} + \beta\underline{w} \\ A\underline{w} = -\beta\underline{v} + d\underline{w} \end{cases}$$

$$A \sim \begin{pmatrix} d & -\beta \\ \beta & d \end{pmatrix}$$

$$\beta Y' = dX - X$$

$$\begin{cases} X' = dX - \beta Y \\ Y' = \beta X + dY \end{cases}$$

$d, \beta \in \mathbb{R}$

$d \pm i\beta$
autovalori

Portando il sistema ad una equazione del

ikonomo oia me.

$$\begin{aligned}X'' &= \alpha X' - \beta Y' = \alpha X' - \beta(\beta X + \alpha Y) \\&= \alpha X' - \beta^2 X - \alpha\beta Y \\&= \alpha X' - \beta^2 X - \alpha(\alpha X - X') \\&= 2\alpha X' - \beta^2 X - \alpha^2 X\end{aligned}$$

$$X'' - 2\alpha X' + (\alpha^2 + \beta^2)X = 0$$

$$P(\lambda) = \lambda^2 - 2\alpha\lambda + (\alpha^2 + \beta^2)$$

$$\lambda_{1,2} = \alpha \pm \sqrt{\alpha^2 - (\alpha^2 + \beta^2)}$$

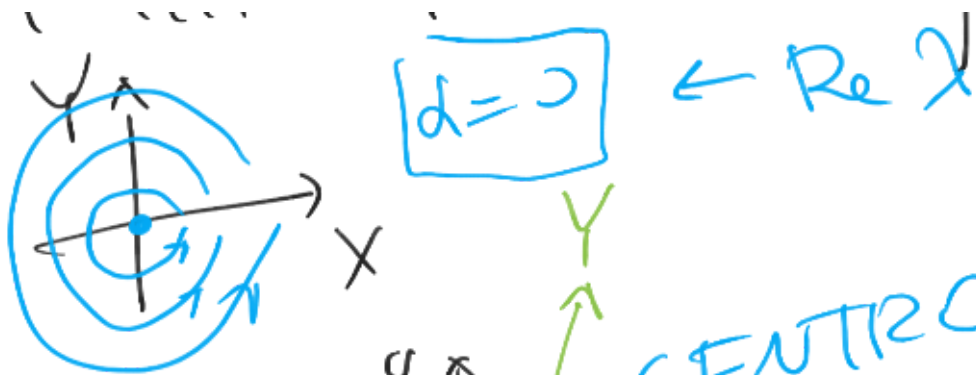
$$= \alpha \pm \sqrt{-\beta^2} = \alpha \pm i\beta.$$

$$X(t) = e^{\alpha t} (a \cdot \cos \beta t + b \cdot \sin \beta t)$$

↑ autovelsi!
⋮ ← contorni

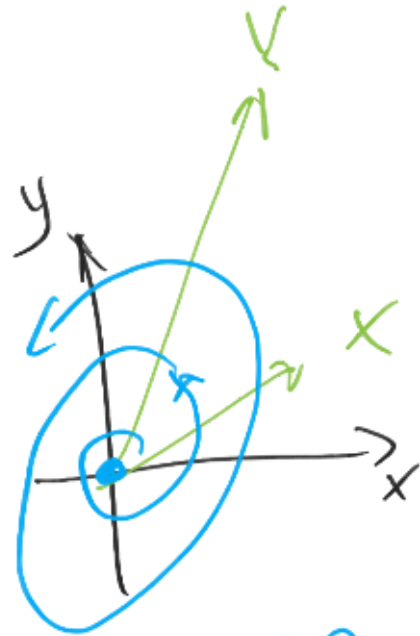
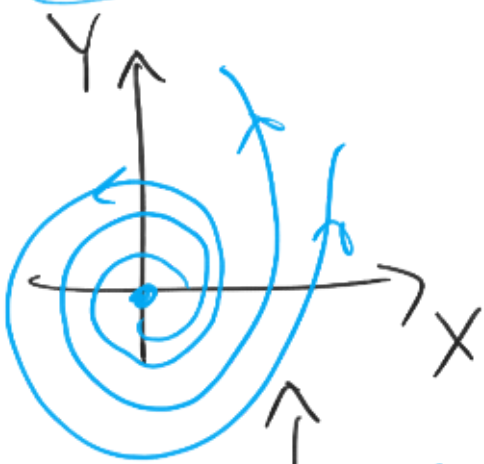
$$Y(t) = \dots = e^{\alpha t} (a \sin \beta t - b \cos \beta t)$$

$$\begin{cases} X(t) = p e^{\alpha t} \cos(\beta t + \theta) \\ Y(t) = p e^{\alpha t} \sin(\beta t + \theta) \end{cases} \quad \begin{array}{l} a \text{ o } b \end{array}$$

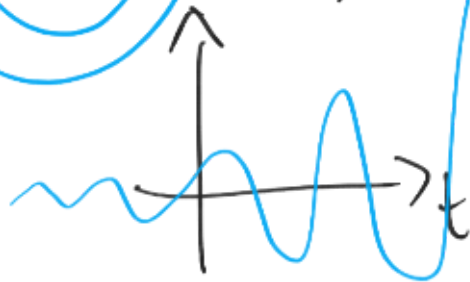


CENTRO
STABILE
 (NON ASINTOTICAMENTE)

$d > 0$



FUOCO
 INSTABILE



FUOCO
 STABILE

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