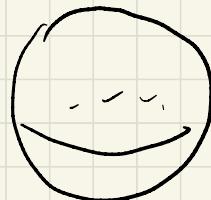


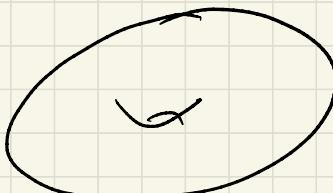
## Teo (CLASSIFICAZIONE DELLE SUPERFICI)

Ogni superficie  $\Sigma$  connessa cpt orientabile senza  
||  
2-varietà

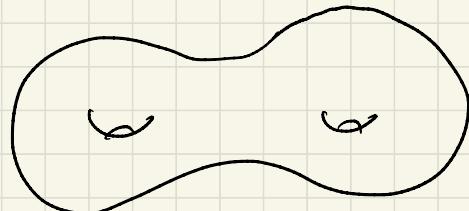
è diffeomorfa a una di queste:



$$S^2$$



$$S^1 \times S^1$$

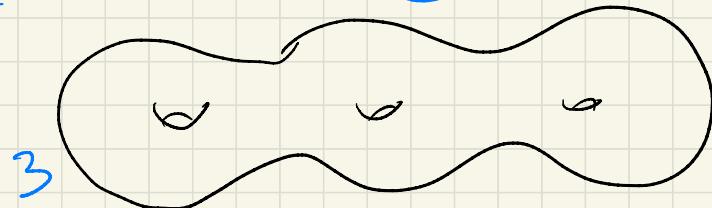


$$1$$

GENERE

$$g = 0$$

$$2$$



$$3$$

$$\dots - - -$$

---

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---

---

---



$\circ$   $S^1$

$$\begin{array}{c} \bullet - \bullet \\ \bullet - C \\ ) - C \end{array} \quad \begin{array}{l} [0,1] \\ [0,1) \\ (0,1) \end{array}$$

1-varietà connesse

$$\varphi_1' = r \circ \varphi_1 \rightarrow \varphi_1$$

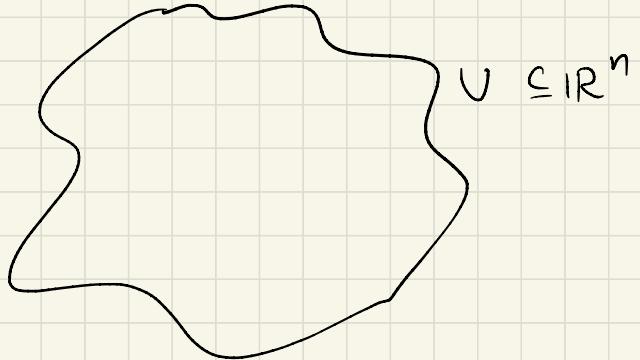
A diagram consisting of three horizontal arrows pointing to the right. The top arrow is black, the middle arrow is red, and the bottom arrow is blue. The red arrow has a small circle at its left end.

## Lezione 11

$$\mathbb{R}^2_+$$

$$r(x,y) = (-x, y)$$

$r: \mathbb{R}_+^2 \xrightarrow{\sim} \mathbb{R}_+^2$  inverte orientazione  
 $\mathbb{R}_+^n$  è SPECCHIA BILE



Cioè  $\exists \varphi: \mathbb{R}^n_+ \xrightarrow{\sim} \mathbb{R}^n$  diffeo  
di interazione

$$U = B^n$$

$$g^+ = \left( \frac{2}{1 - \|x\|^2} \right)^2 g^E$$

Def:  $(M, g)$  varietà pR

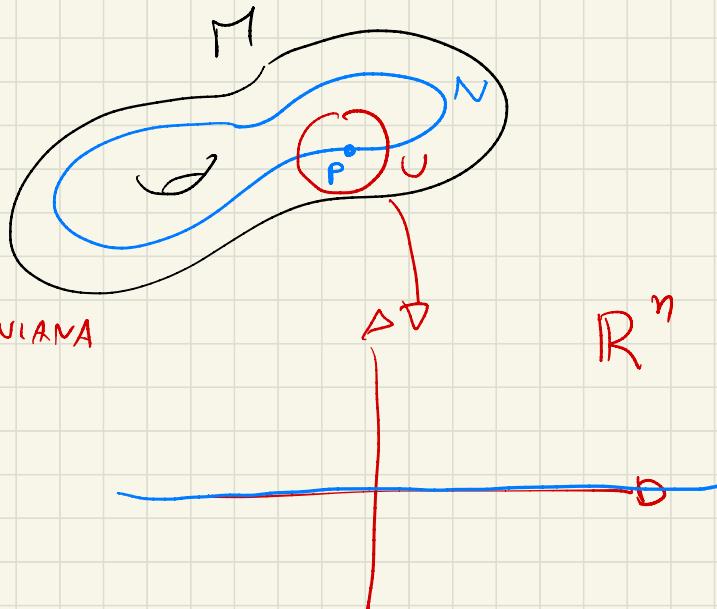
Sia  $N \subseteq M$  sottovarietà liscia connessa

Lei è **SOTTOVARIETÀ PSEUDO-RIEMANNIANA**

se  $\forall p \in N$

$T_p N \subseteq T_p M$  sottospazio

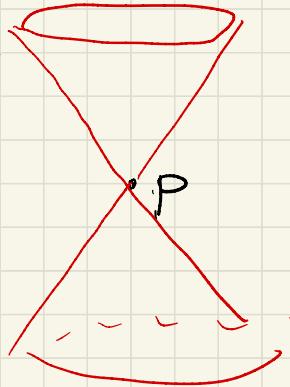
$g|_{T_p N}$  è NON DEGENERE



Oss: Se  $g$  è detr questo è reificato sempre

Ese:  $\mathbb{R}^{2,1} \ni g$

è sottovarietà p.R  
se è tipo tempo  
o spazio



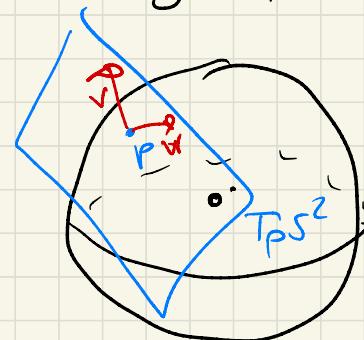
Oss:  $N$  è varietà p.R  $(N, g')$

$$\forall p \in N \quad g'(p) := g|_{T_p N}$$

Ese:  $S \subseteq \mathbb{R}^n$  sottovarietà

Ese:  $S^{n-1} \subseteq \mathbb{R}^n$

$(\mathbb{R}^n, g^E)$

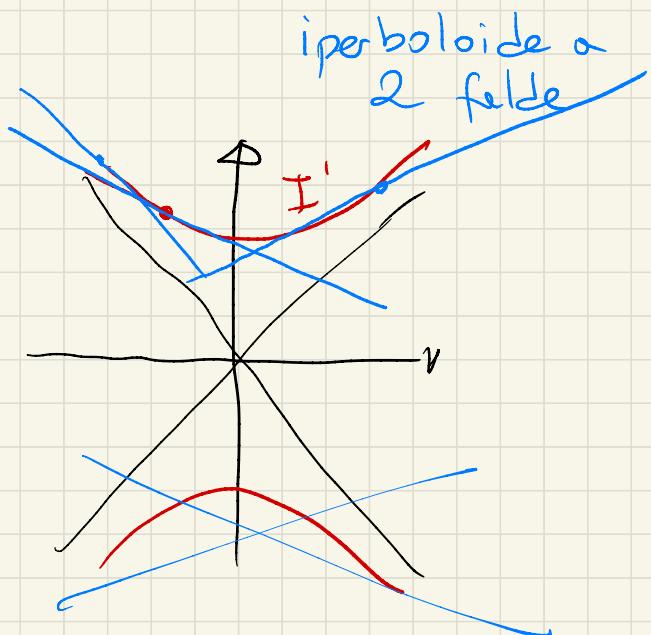


$$S^2 \subseteq \mathbb{R}^3$$

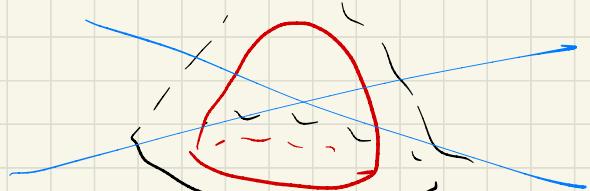
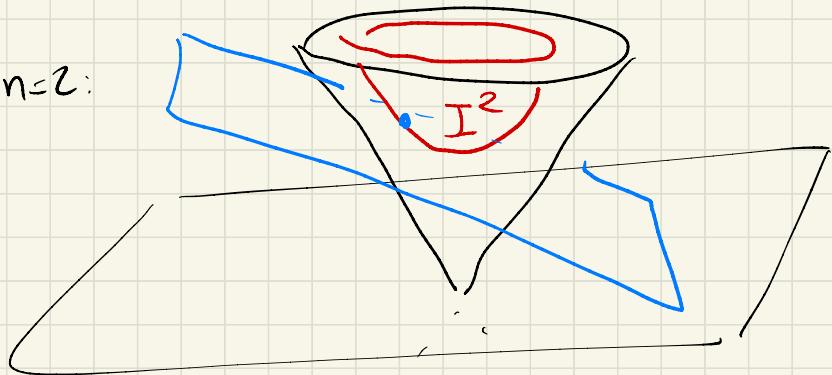
Es:  $I^n \subseteq \mathbb{R}^{n,1} = (\mathbb{R}^{n+1}, n)$   $n = \begin{pmatrix} -1 & & \\ & 1 & \\ & & \ddots \\ & & & 1 \end{pmatrix}$

$$I^n = \left\{ x \in \mathbb{R}^{n,1} : \langle x, x \rangle = -1 \right\} \cap \left\{ x_1 \geq 0 \right\}$$

$$-x_1^2 + x_2^2 + \dots + x_{n+1}^2 = -1$$



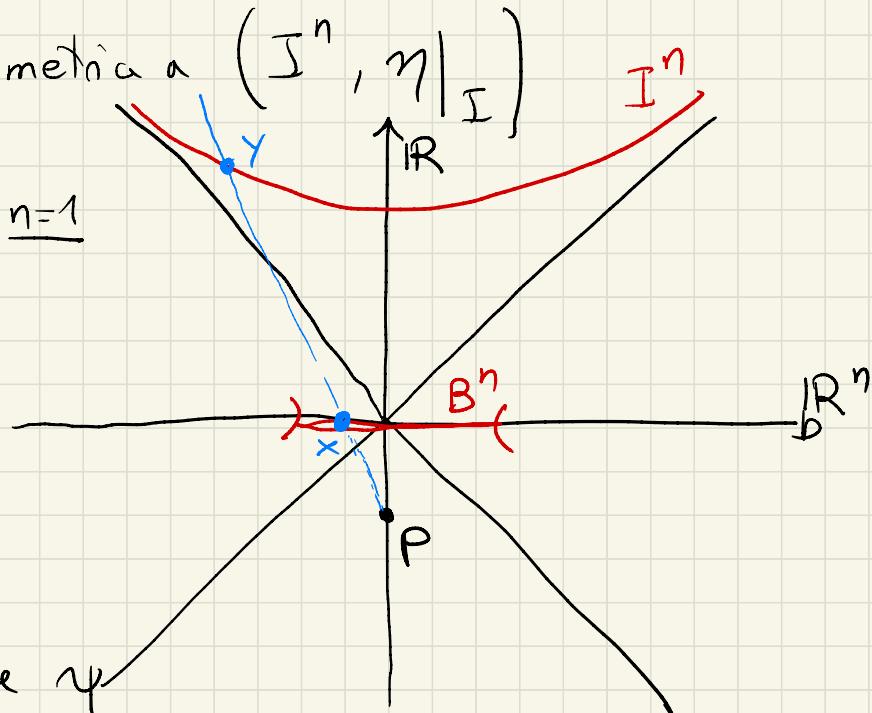
$n=2$ :



Ex:  $I^n \subseteq \mathbb{R}^{n,1}$  è sottovietù p.R Riemanniana

$I^n$  è il MODELLO DELL'IPERBOLOIDE dello SPAZIO IPERBOlico

Ex:  $(B^n, g^+)$  è isometrica a  $(I^n, \eta|_I)$



$$P = (-1, 0, \dots, 0)$$

$\psi: B^n \xrightarrow{\sim} I^n$  diffeo

$$\psi(x) = y$$

Facendo i conti si vede che  $\psi$  è isometrica

cioè  $\forall x \in B^n, \quad \forall v, w \in T_x B^n$

$$\begin{aligned} \langle v, w \rangle &= \langle v', w' \rangle & v' &= d\varphi_x(v) \\ g^+ & & |v|_I & \\ & & w' &= d\varphi_x(w) \end{aligned}$$

Prop: Ogni  $M$  ha struttura Riemanniana.

$$\stackrel{\text{dim}}{\dim} \quad \star = \left\{ \varphi_i : U_i \rightarrow \mathbb{R}^n \right\} \text{ atlante} \rightarrow \left\{ U_i \right\} \text{ n.c. aperto}$$

$$\rightarrow \exists \, g_i : M \rightarrow [0, \infty) \quad \text{partiz. unite'}$$

$$\text{t.c. } \text{supp } g_i \subseteq U_i \quad \sum_i g_i(p) = 1$$

$$\text{Su } U_i \text{ prendo } g_i := \varphi_i^*(g^E) \quad g_i(v, w) := g^E(v', w')$$
$$v' = (d\varphi_i^*)_x(v) \quad \dots$$

Definisco  $\forall p \in M$   $g(p) := \sum_i g_i g_i(p)$

Si ottiene  $g$  campo tensoriale di tipo  $(0,2)$  su  $M$   
simmetrico

$\Rightarrow$  def +

Combinaz. lineare con coeff. positivi di prod. scalari positivi  
è definito positivo

infatti  $g(p)(v, v) = \sum_i g_i g_i(p)(v, v) > 0$

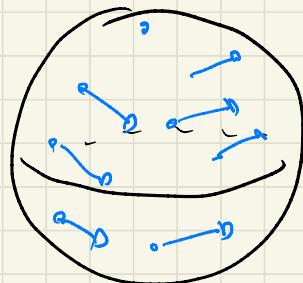
$v \neq 0$

$\uparrow$   $\nearrow > 0$   
 $> 0$

□

Oss: Non tutte le  $M$  hanno struttura Lorentziana

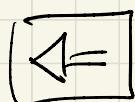
Teo:  $M$  ha struttura Lorentziana  $\Leftrightarrow$  ha un campo vettoriale mai nullo



$S^2$

$\nexists$  campo mai nullo su  $S^2$

idem per  $S^4$



$(M, g)$

$g$  Riemanniana

$\times$  campo vettoriale  
mai nullo

normalizzo  $X$ :  $\bar{X}(p) = \frac{X(p)}{\|X(p)\|} = \frac{X(p)}{\sqrt{g(p)(X(p), X(p))}}$

$$\|\bar{X}(p)\| = 1 \quad \forall p$$

$$g'(p)(v, w) := g(p)(v, w) - 2 g(p)(v, \bar{X}(p)) \cdot g(p)(\bar{X}(p), w)$$

$\forall p \in M, \forall v, w \in T_p M$

$g'$  è nuo ro tensore simm.  $(0,2)$

In coordinate:

$$g'_{ij} v^i w^j = g_{ij} v^i w^j - 2 g_{ie} v^i \bar{x}^e g_{kj} \bar{x}^k w^j \quad \text{cioè}$$

Calcolo la regolare di  $g'_{ij}$ :

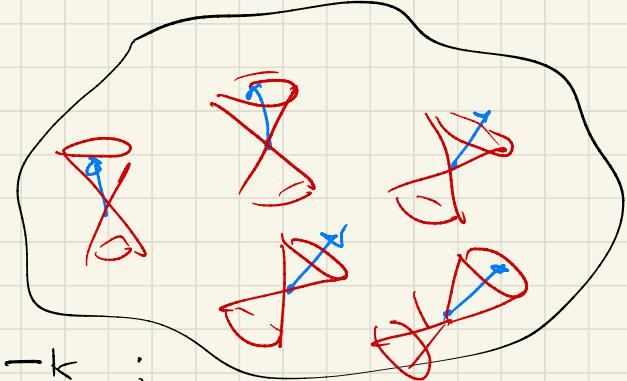
$$g'_{ij} = g_{ij} - 2 g_{ie} \bar{x}^e g_{kj} \bar{x}^k$$

$B = \{\bar{x}(p), v_2, \dots, v_n\}$  base ortonormale di  $(\mathbb{R}^n, g_{ij})$

Rischio  $g_{ij}$  e  $g'_{ij}$  rispetto a  $B$

$$\text{Otengo } g_{ij} = \delta_{ij}$$

$$g'_{ij} = \delta_{ij} - 2 \delta_{ie} \bar{x}^e \delta_{kj} \bar{x}^k$$



$$g'_{ij} = \delta_{ij} - 2\delta_{i1}\delta_{1j} = \gamma_{ij}$$

$$\begin{aligned} &= I - \begin{pmatrix} 2 & 0 & \cdots \\ 0 & 0 & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix} = \begin{pmatrix} 1 & \cdots & \cdots \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 0 \end{pmatrix} - \begin{pmatrix} 2 & 0 & \cdots \\ 0 & 0 & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix} \\ &= \begin{pmatrix} -1 & \cdots & \cdots \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 0 \end{pmatrix} \end{aligned}$$

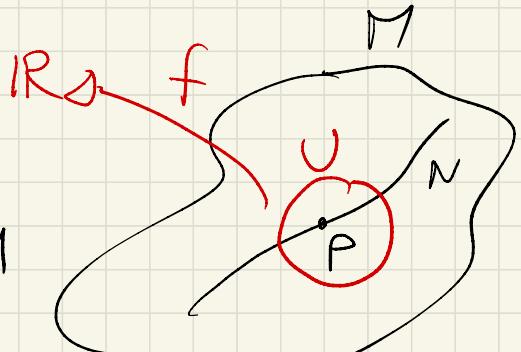
□

$N \subseteq M$  so  $\text{Niemieki}$

$$\forall p \in N \quad T_p N \subseteq T_p M$$

$$v \in T_p N \quad \dots \rightarrow ? \quad v \in T_p M$$

$$v(f) := v(f|_{N \cap U}) \quad f: U(p) \rightarrow \mathbb{R}$$



## ESERCIZI

Esercizio 1:  $A, B$  matrici quadrate

$$X_A(x) = Ax \quad \text{in } \mathbb{R}^n$$

$$[X_A, X_B] = X_{BA - AB}$$

$$X_A(x) = Ax$$

$$X_A^i = (Ax)^i = A_j^i x^j$$

$$[X, Y]^i = X^j \frac{\partial Y^i}{\partial x^j} - Y^j \frac{\partial X^i}{\partial x^j}$$

$$[X_A, X_B]^i = X_A^j \frac{\partial X_B^i}{\partial x^j} - X_B^j \frac{\partial X_A^i}{\partial x^j}$$

$$= A_e^j x^l \frac{\partial}{\partial x^j} (B_k^i x^k) - B_e^j x^l \frac{\partial}{\partial x^j} (A_k^i x^k)$$

$$= A_e^j x^l B_k^i \frac{\partial x^k}{\partial x^j} - \dots$$

$$= A^j_e \times^e B^i_k S_{jk} - \dots$$

$$= A^j_e \times^e B^i_j - \dots$$

$$= B^i_j A^j_e \times^e - \dots$$

$$= B \cdot A \cdot x - A \cdot B \cdot x = (BA - AB) \cdot x$$

Ex 2:  $[[x, y], z]^{(f)} + [[y, z], x]^{(f)} + [[z, x], y]^{(f)}$

- 1) Lavoro in coordinate  $\boxed{11}$   $\forall f \in C^\infty(U) \quad \forall U \subseteq M$
- 2) Scrivere  $[XY - YX, Z]$   $\dots \dots \dots \quad \{\}$
- 3) Lavoro su operazioni  $\boxed{11}$   $\text{altra strada scrivendo sempre } f$
- $[XY, Z] - [YX, Z]$   $\boxed{11}$

$$XYZ - ZXY - (YXZ - ZYX)$$

$$XY = x^i \frac{\partial Y}{\partial x^i}$$

$$[X, Y] Z (f) =$$

$$= [X, Y](Zf) - Z([X, Y](f)) \quad \dots \dots$$

$$[A, B](f) = ABf - BAf \quad \underline{\text{OK}}$$

Ex 3:  $[fX, gY] = f_g [X, Y] + \underbrace{f(Xg)Y}_{\text{---}} - \underbrace{g(Yf)X}_{\text{---}}$

In coordinate

$$(fX)(gY) - (gY)(fX)$$

$$= \underbrace{f(Xg)Y}_{\text{---}} + \underbrace{fgXY}_{\text{---}} - \underbrace{g(Yf)X}_{\text{---}} - \underbrace{gfYX}_{\text{---}}$$

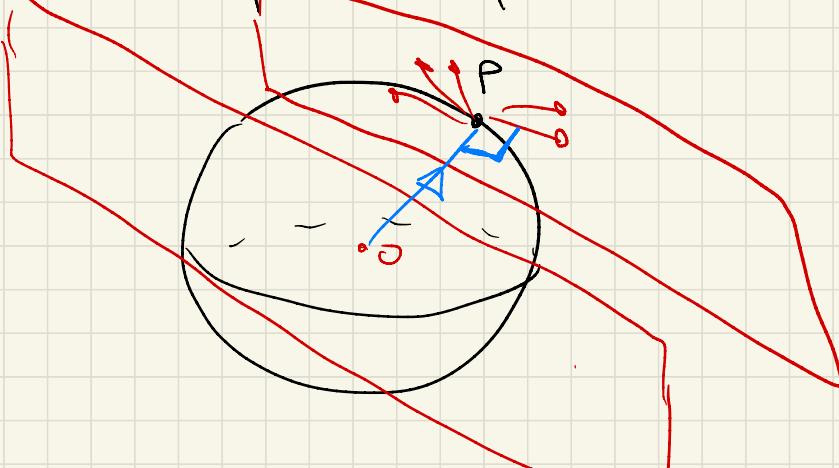
$$\underline{\text{Ex 5}}: S^{2n-1} \subseteq \mathbb{R}^{2n}$$

$$X(x_1, \dots, x_{2n}) = (x_2 - x_1, \dots, x_{2n} - x_{2n})$$

Fatti generali:

$$M \subseteq \mathbb{R}^N \text{ sottrannele'}$$

$$\forall p \in M \quad T_p M \subseteq T_p \mathbb{R}^N = \mathbb{R}^N$$



$$T_p S^{N-1} = p^\perp$$

$$X \in \mathcal{X}(M)$$

$$f \in C^\infty(M)$$

$$fX \in \mathcal{X}(M)$$

$$(fX)(p) = f(p) \cdot X(p)$$

$$Xf \in C^\infty(M)$$

$$(Xf)(p) = X(p)f$$

$$(x_2, -x_1, \dots, x_{2n}, -x_{2n-1}) \in T_x S^{2n-1} ?$$

$$\Leftrightarrow \langle \begin{matrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{matrix}, \begin{matrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{matrix} \rangle = 0 \quad \begin{matrix} ||x|| \\ x^\perp \end{matrix}$$

$$x_1 x_2 - x_2 x_1 + \dots + x_{2n-1} x_{2n} - x_{2n} x_{2n-1} = 0$$

$$\|x\|=1 \Rightarrow \sum x_i^2 = 1 \Rightarrow \|X(x)\|=1 \quad \forall x \in S^{2n-1}$$

$$\left\{ \begin{array}{l} \dot{x}_1 = x_2 \\ \dot{x}_2 = -x_1 \\ \vdots \\ \dot{x}_{2n-1} = x_{2n} \\ \dot{x}_{2n} = -x_{2n-1} \end{array} \right. \Rightarrow \ddot{x}_i = -x_i, \quad x(t) = \gamma(t)$$

$$x_1 = A \cos t + B \sin t$$

$$x_2 = \dot{x}_1 = B \cos t - A \sin t$$

$$x_1(0) = x_1^0 \quad x_2(0) = x_2^0$$

$$A = x_1^0 \quad B = x_2^0$$

$$x(t) = (x_1^0 \cos t + x_2^0 \sin t, x_2^0 \cos t - x_1^0 \sin t, \dots)$$

¶

NOTA:  $\exists \forall t \in (-\infty, \infty)$

$$x(t+2\pi) = x(t)$$

$$F_t(x) = F(x, t) = x(t)$$

$S^3$  è unione di circonference!  
di girotondo (FIBRAZIONE DI HOPF)

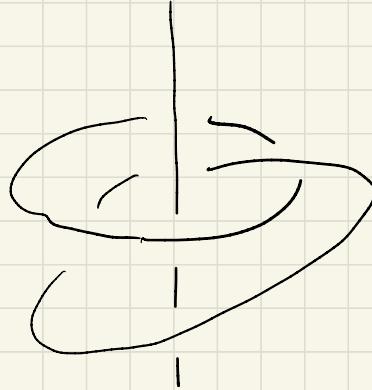
$$S^n = \mathbb{R}^n \cup \{\infty\}$$

proiez. stereografica

$$S^3 = \mathbb{R}^3 \cup \{\infty\}$$

$$S^3 \subseteq \mathbb{C}^2 \setminus \{0\} \xrightarrow{\pi} \mathbb{P}^1(\mathbb{C})$$

$$(z, w) \mapsto [z, w]$$



$$S^3 \subseteq \mathbb{R}^4 \setminus \{0\}$$

$\begin{smallmatrix} \parallel \\ \mathbb{C}^2 \end{smallmatrix}$

$$\pi: S^3 \rightarrow \mathbb{P}^1(\mathbb{C}) = S^2$$

$(z, w) \mapsto \begin{bmatrix} z \\ w \end{bmatrix} \mapsto \frac{z}{w}$

FIBRAZIONE DI HOPF

$$S^3 = \left\{ (z, w) : \|z\|^2 + \|w\|^2 = 1 \right\}$$

$$\mathbb{P}^1(\mathbb{C}) = \mathbb{C} \cup \{\infty\} = \mathbb{R}^2 \cup \{\infty\} = S^2$$

$$\mathbb{P}^1(\mathbb{C}) \rightarrow \mathbb{C} \cup \{\infty\}$$

$$[z, w] \mapsto \frac{z}{w}$$

$$\pi^{-1}([z, w]) = \left\{ (e^{i\theta}z, e^{i\theta}w) \mid \theta \in [0, 2\pi) \right\}$$

$$[z, w] = [\lambda z, \lambda w] \quad \|z\|^2 + \|w\|^2 = 1$$

$\forall \lambda \neq 0 \quad \lambda \in \mathbb{C}$

Ex 1.5:  $M^n \rightarrow (TM)^{2n}$  ORIENTABILE

$$\mathcal{A} = \left\{ \varphi_i : U_i \rightarrow V_i \subseteq \mathbb{R}^n \right\}$$

$$\pi : TM \rightarrow M \quad \mathcal{A}' = \left\{ \psi_i : \pi^{-1}(U_i) \rightarrow V_i \times \mathbb{R}^n \right\}$$

$$\psi_i(p, v) = (\varphi_i^{(p)}(\text{d}\varphi_i)_p(v)) \quad \text{é orientado!}$$

$$v \in T_p M$$

$$\psi_{ij} = \psi_i \circ \psi_j^{-1} \quad (\text{d}\psi_{ij})_x = \begin{pmatrix} & | \\ \text{---} & \end{pmatrix}$$

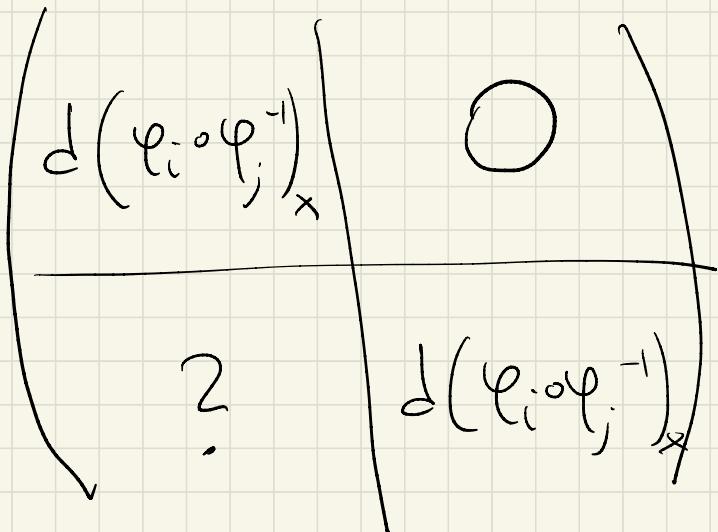
$$\psi_{ij}(x, v) = \left( \varphi_i \circ \varphi_j^{-1}(x), \text{d}(\varphi_i) \circ \text{d}(\varphi_j^{-1})_x(v) \right)$$

$$= \left( \varphi_i \circ \varphi_j^{-1}(x), \quad d(\varphi_i \circ \varphi_j^{-1})_x(x) \right)$$

$$(d\varphi_{ij})_{(x,w)} : \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$$

Jacobia

$\det$



$$= (\det d(\varphi_i \circ \varphi_j^{-1})_x)^2 > 0$$

Ex 1.6

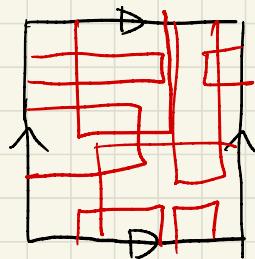
$M^m \times N^n$  non è ori

$\star \quad \star'$

$\star \times \star'$

↑  
non è orientabile

$$T = S^1 \times S^1$$



Supponiamo p.a. che  $M \times N$  orientabile

non è ori

Fissiamo  $p \in M$

$$\{p\} \times N \subseteq M \times N$$

112  
N

Fisso  $v_1, \dots, v_m \in T_p M$

Usa l'orientazione di  $M \times N$  per definirne una su  $N$  (assurdo)

Def.:  $\forall q \in N \quad w_1, \dots, w_n$  base di  $T_q N$

è positiva se

$v_1, \dots, v_m, w_1, \dots, w_n$  è base positiva

$$\text{di } T_p M \times T_q N = T_{(p,q)} M \times N$$

Ex:  $U \times V = W$  Date due orientazioni su  $U \cup V$

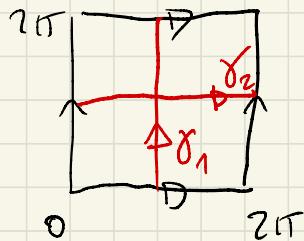
$\exists$  modo canonico di definire una su  $V$

$$\underline{1.7}: \quad T = S^1 \times S^1 \quad (\vartheta^1, \vartheta^2) \quad \omega = d\vartheta^1$$

$$\gamma_1 = \{1\} \times S^1 \quad \gamma_2 = S^1 \times \{-1\}$$

$$\int_{\gamma_1} \omega = 0$$

$$\int_{\gamma_2} \omega = 2\pi$$



$$\omega = dx$$

$$\underline{1.8}: \quad f: M \rightarrow N \quad \omega \in \Omega^k(N), \gamma \in \Omega^h(N)$$

$$f^*(\omega \wedge \gamma) = (f^*\omega) \wedge (f^*\gamma)$$

$$f^*(\alpha dx^{i_1} \wedge \dots \wedge dx^{i_k}) \\ = \alpha \circ f df^{i_1} \wedge \dots \wedge df^{i_k}$$

$$V \xrightarrow{f} W$$

$$f^*: T_o^k(W) \rightarrow T_o^k(V)$$

$$\begin{matrix} & & U \\ & & U \\ \Lambda^k(W) & \xrightarrow{\psi} & \Lambda^k(V) \\ & & \alpha \end{matrix}$$

$$f^*(\alpha)(v_1, \dots, v_k) =$$

$$\alpha(f(v_1), \dots, f(v_k))$$

$$\omega \in \Lambda^k(W) \quad \eta \in \Lambda^h(W)$$

$$n = k + h$$

TESI

$$\underbrace{f^*(\omega \wedge \eta) = f^*(\omega)}_{\wedge f^*(\eta)}$$

$$\begin{aligned} (\omega \wedge \eta) (v_1, \dots, v_n) &= \\ &= \frac{1}{k! h!} \sum_{\sigma \in S_n} \text{sgn}(\sigma) \tilde{\omega}(v_{\sigma(1)}, \dots, v_{\sigma(k)}) \cdot \eta(v_{\sigma(k+1)}, \dots, v_{\sigma(n)}) \end{aligned}$$

## CONNESSIONI

CONNESSIONE = DERIVATA COVARIANTE

Def:  $M$  varietà.

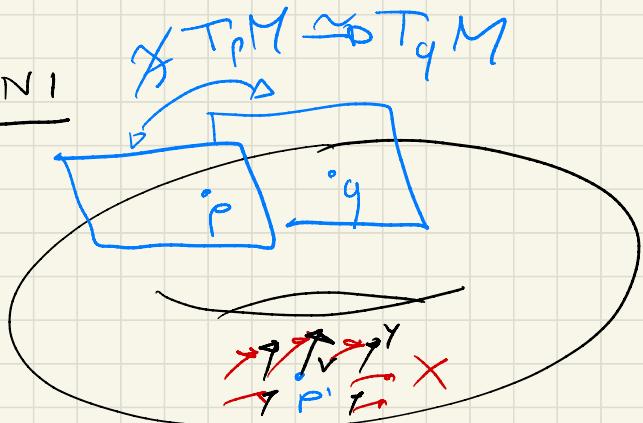
Una DERIVATA COVARIANTE

è un oggetto  $\nabla$  cle

$\forall p \in M, \forall X \in \mathcal{X}(U(p))$

$\forall v \in T_p M$

t.c.:



$$d_y X = [Y, X]$$

$$\mathcal{L}_y^s$$

definisce

$$\nabla_v X \in T_p M$$



LOCALE

1) Se  $X \in \mathcal{X}$  coincide su  $\cup(p)$

allora  $\nabla_v X = \nabla_v Y$

LINEARE

2) Lineare in  $v \in \mathcal{X}$ :

$$\begin{aligned} & \nabla_v (\lambda X + \mu Y) \\ &= \lambda \nabla_v X + \mu \nabla_v Y \end{aligned}$$

$$\lambda, \mu \in \mathbb{R}$$

$$X, Y \in \mathcal{X}(\cup(p))$$

$$\nabla_{\lambda v + \mu w} X = \lambda \nabla_v X + \mu \nabla_w X$$

LEIBNITZ

3)  $\nabla_v (f X) =$

$$\left[ \begin{array}{l} \text{i} \\ \text{ii} \end{array} \right] \nabla_v (f) \cdot X(p) + f(p) \cdot \nabla_v (X)$$

$$f \in C^\infty(\cup(p))$$

$$X \in \mathcal{X}(\cup(p))$$

$$v(f)$$

LISCA

4)  $\nabla_v X$  "dipende in modo lineare von  $v$  und  $X$ "

formalmente: dati  $X, Y \in \mathcal{X}(U)$

$$\nabla_Y X \in \mathcal{X}(U)$$

$$(\nabla_Y X)(p) = \nabla_{Y(p)} X$$

In carte:

$$X = x^i e_i = x^i \frac{\partial}{\partial x^i} = x^i \partial_i$$

$$v \in \mathbb{R}^n$$

$$v = v^i e_i$$

$$\nabla_v X \in \mathbb{R}^n$$

$$= \nabla_{v^i e_i} (x^j e_j) \underset{\text{LIN}}{=} v^i \nabla_{e_i} (x^j e_j) \underset{\text{LEIB}}{=}$$

$$= v^i \left( (\nabla_{e_i} x^j) e_j + x^j \nabla_{e_i} e_j \right)$$

$$= v^i \left( \frac{\partial x^j}{\partial x^i} e_j + x^j \Gamma_{ij}^k e_k \right)$$

simbolo di Christoffel

$\nabla$  è determinato da  $\Gamma_{ij}^k$

$\Gamma_{ij}^k(p)$   $n^3$  funzioni

definite solo  
in carte

$$\nabla_v x = v^i \frac{\partial x^j}{\partial x^i} e_j + v^i x^j \Gamma_{ij}^k e_k \quad \text{NON SONO TENSORI}$$



$$v^i \frac{\partial x}{\partial x^i} = \frac{\partial x}{\partial v}$$

D'altra parte, se  $U \subseteq \mathbb{R}^n$  e  $\Gamma_{ij}^k \in C^\infty(U)$

definiscono una connessione  $\nabla$  con  $\boxed{*}$

Ex: Effettivamente  $\nabla$  soddisfa (1) (2) (3) (4)

$$(\mathbb{R}^n, \nabla^E)$$

$\nabla^E$  connessione euclidea

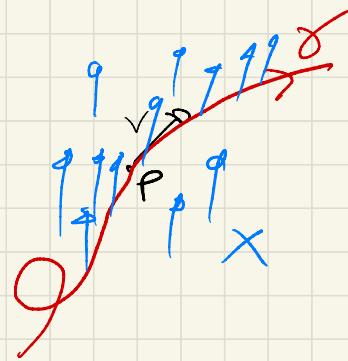
$$\Gamma_{ij}^k = 0$$

Prop:  $(M, \nabla)$

Sia  $\gamma: I \rightarrow M$  curva

t.c.  $\gamma'(t_0) = v$

$\gamma(t_0) = p$



$\forall X \in \mathcal{X}(U(p))$ ,  $\nabla_v X$  dipende solo dai valori di  $X$  su  $\gamma$

dim:

$$\nabla_v X = v^i \frac{\partial X^j}{\partial x^i} e_j + v^i X^j \Gamma_{ij}^k e_k$$

$$\frac{\partial X}{\partial v} = \frac{\partial X}{\partial v}$$

dip. solo  
di  $X(p)$

## CAMPI SU CURVE

$(M, \nabla)$

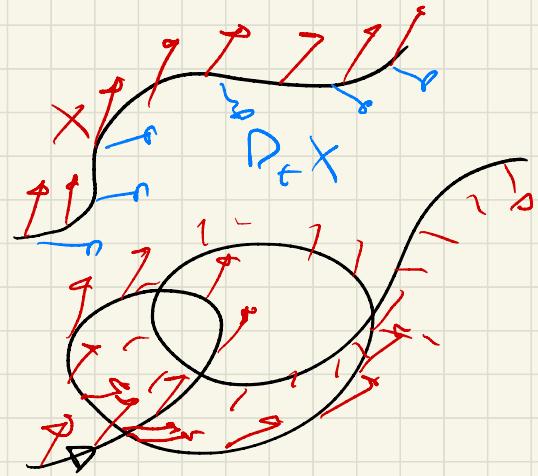
$\gamma: I \rightarrow M$

REGOLARE, cioè  $\dot{\gamma}(t) \neq 0 \forall t$

Def: Un CAMPO su  $\gamma$  è

$X: I \rightarrow TM$  t.c.

$X(t) \in T_{\gamma(t)} M$

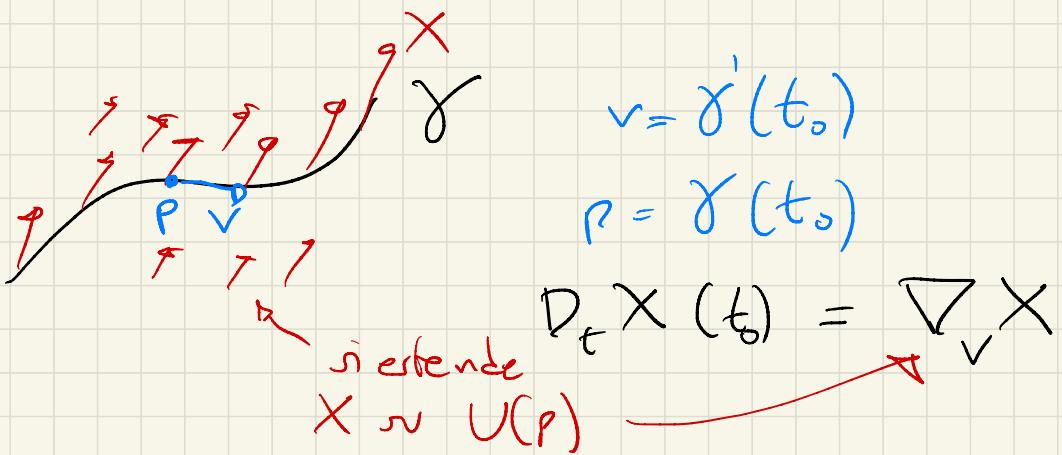


Def: Se  $X$  è un campo su  $\gamma$  regolare

$D_t X$  CAMPO DERIVATO LUNGO  $\gamma$

è la "derivata di  $X$  lungo  $\gamma$ "

Ogni  $\gamma$  reg. è loc. iniettiva e il suo supporto è  
sottovarietà dim 1



In carte:  $\gamma(t) \in \mathbb{R}^n$   $X = X^i e_i$

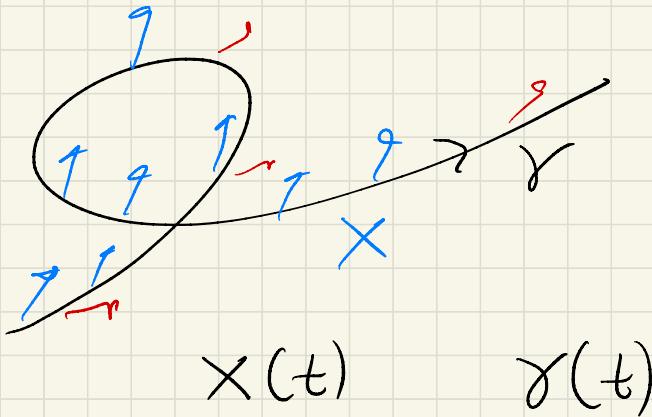
$$\nabla_v X = v^i \frac{\partial X^j}{\partial x^i} e_j + v^i X^j \Gamma_{ij}^k e_k$$

$\underbrace{v^i \frac{\partial X}{\partial x^i}}_{= \frac{\partial X}{\partial v}}$

$$v = \gamma'(t_0)$$

$$v^i \frac{\partial X}{\partial x^i} = \frac{\partial X}{\partial v}$$

$$D_t X(t_0) = \frac{dX}{dt}(t_0) + (\gamma'(t_0))^i X^j_{(t_0)} \Gamma^k_{ij}(\gamma(t_0)) e_k$$



$$D_t X = \frac{dX}{dt} + \dot{x}^i X^j \Gamma^k_{ij} e_k$$

TRASPORTO PARALLELO

Def:  $\gamma: I \rightarrow M$   $(\sqcap, \sqcup)$

$X: I \rightarrow TM$  campo su  $\gamma$

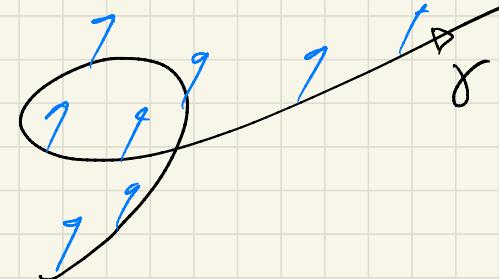
$X$  è PARALLELO se  $D_t X = 0$

$$\nabla^E \Gamma_{ij}^k = 0$$

$$X(t) \in \mathbb{R}^n$$

$$\gamma(t) \in \mathbb{R}^n$$

$X$  parallelo  $\Leftrightarrow D_t X = 0$



$\Leftrightarrow X$  curv

$$\frac{dX}{dt}$$

+

$$\Gamma_{ij}^k = 0$$

"

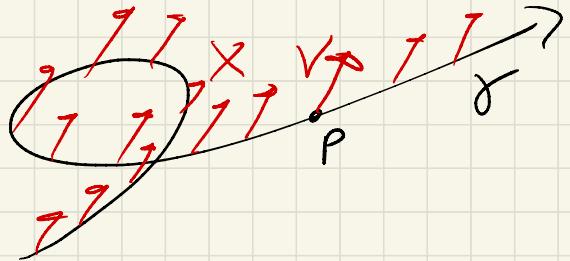
Prop: Data  $(M, \nabla)$   $\gamma$  reg.  $p = \gamma(t_0)$

$\exists! X$  su  $\gamma$  parallell. t.c.  $X(t_0) = v$

$v \in T_p M$

dim:

Basta dimostrarlo localmente



In corte:  $X$  è parallelo  $\Leftrightarrow$

$$\frac{dX^K}{dt}(t) + (\gamma'(t))^i X^j_{(t)} \Gamma^k_{ij}(\gamma(t)) \equiv 0$$

sistema di eq. diff. lineari  $k=1, \dots, n$

a coeff. variabili

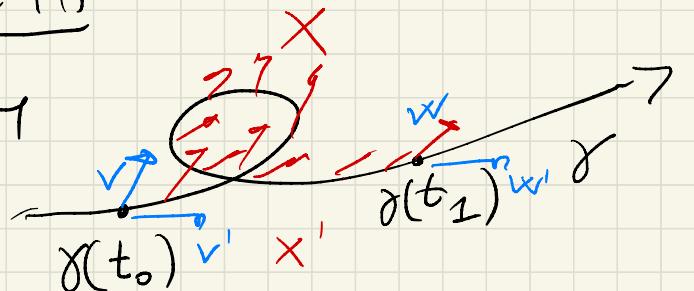
$$X^K : I \rightarrow \mathbb{R}$$

$\exists!$  Probl. Cauchy  $\Rightarrow \exists!$  soluz. loc. t.c.  $X^K(t_0) = v$   
 su tutto I

PROPRIETA'

$$\Gamma(\gamma)_{t_0}^{t_1} : T_{\gamma(t_0)} M \rightarrow T_{\gamma(t_1)} M$$

$$\begin{matrix} v & \longmapsto & w \\ \vdots & & \parallel \\ x & \dashrightarrow & X(t_1) \end{matrix}$$



$$\lambda v + \lambda' v' \longrightarrow \lambda w + \lambda' w'$$

$$\lambda x + \lambda' x'$$

Prop:  $\Gamma(\gamma)_{t_0}^{t_1}$  è un isomorfismo.

Dm:

- è lineare
- $\Gamma(\gamma)_{t_0}^{t_2} \circ \Gamma(\gamma)_{t_0}^{t_1} = \Gamma(\gamma)_{t_0}^{t_2}$

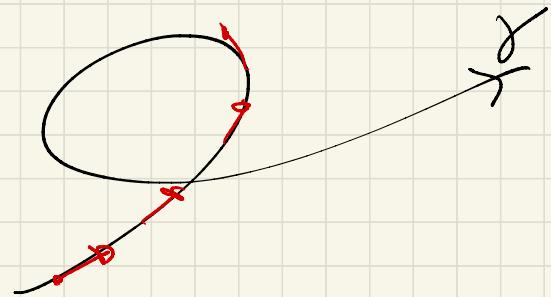
$$\Gamma(\gamma)_{t_0}^{t_2} \circ \Gamma(\gamma)_{t_0}^{t_1} = \Gamma(\gamma)_{t_0}^{t_2}$$

## GEODETICHE

$$\gamma: I \rightarrow M \quad (M, D)$$

Esempio di campo lungo  $\gamma$

$$X(t) = \gamma'(t)$$



Def:  $\gamma$  è **GEODETICA** se  $\gamma'(t)$  è parallelo.