## On the singularities of convex functions*

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Abstract. Given a (semi)-convex function $u: \Omega \subset \mathbb{R}^{n} \rightarrow \mathbb{R}$ and an integer $k \in[0, n]$, we show that the set $\Sigma^{k}$ defined by

$$
\Sigma^{k}:=\{x \in \Omega: \operatorname{dim}(\partial u(x)) \geq k\}
$$

is countably $H^{n-k}$-rectifiable, i.e., it is contained (up to a $H^{n-k_{-}}$ negligible set) in a countable union of $C^{1}$ hypersurfaces of dimension $(n-k)$. Moreover, if $u$ is convex in $\Omega$, we show that

$$
\int_{\Omega^{\prime} \cap \Sigma^{k}} \mathscr{H}^{k}(\partial u(x)) d \mathscr{H}^{n-k}(x)<+\infty
$$

for any open set $\Omega^{\prime} \subset \subset \Omega$.
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## 1. Introduction

This paper originated from our interest in the following question about the singularities of a convex functions:
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Problem: given a convex function $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$, and an integer $k \in[0, n]$, how to estimate the size of the $k$-th singular set of $u$, i.e., of the set

$$
\Sigma^{k}(u):=\left\{x \in \mathbb{R}^{n}: \operatorname{dim}(\partial u(x)) \geq k\right\} ?
$$

Of course, the problem has a trivial answer if $k=0$ or $k=n$, as $\Sigma^{0}(u)=\mathbb{R}^{n}$, whereas $\Sigma^{n}(u)$ is at most countable.

Moreover, if $k=1$, a solution to our problem could be given noting that $\nabla u$ has locally bounded first variation in $\mathbb{R}^{n}$ (see e.g. [13] and [18]). Indeed, the jump set of such a function is known to be countably $\mathscr{H}^{n-1}$-rectifiable (see [9] and [20]), where $\mathscr{H}^{m}$ denotes the $m$-dimensional Hausdorff measure in $\mathbb{R}^{n}$. Equivalently, $\mathscr{H}^{n-1}$-almost all of $\Sigma^{1}(u)$ can be covered with a sequence of $C^{1}$ hypersurfaces.

In this paper we show that, for any $k \in\{0,1, \ldots, n\}, \Sigma^{k}(u)$ is countably $\mathscr{H}^{n-k}$-rectifiable (Theorem 4.1). Consequently, $\Sigma^{k}(u)$ is $\sigma$-finite with respect to $\mathscr{H}^{n-k}$ and, in particular, its Hausdorff dimension does not exceed $(n-k)$. Very simple examples show that $\Sigma^{k}(u)$ may well be a $(n-k)$-dimensional set, for instance, a plane.

Another result contained in Theorem 4.1 of this paper is the estimate

$$
\int_{\Sigma^{k}(u) \cap \Omega} \mathscr{H}^{k}(\partial u(x)) d \mathscr{H}^{n-k}(x) \leq C(n)\left([u]_{\operatorname{Lip}(\Omega)}+\operatorname{diam}(\Omega)\right)^{n}
$$

that holds true for any integer $k \in[0, n]$. Such bound provides a quantitative information on the "measure" of the set $\Sigma^{k}(u)$.

At this point, a brief description of our techniques is in order. The main idea of our approach is to connect the $\mathscr{H}^{m}$-rectifiability of a set $S$ with an upper bound on the dimension of the contingent cone $\mathrm{T}(S, x)$ to $S$ at any point $x \in S$ (Theorem 3.1). Then, the rectifiability of $\Sigma^{k}(u)$ follows by splitting $\Sigma^{k}(u)$ as a countable union of sets $\Sigma_{\alpha}^{k}(u)$ for which we are able to prove an upper bound on the dimension of the contingent cone. Such a bound is obtained showing $\mathrm{T}\left(\Sigma_{\alpha}^{k}(u), x\right)$ is orthogonal to $\partial u(x)$ (Proposition 2.2), and recalling that $\operatorname{dim}(\partial u(x)) \geq k$.

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Although we have stated the problem for a convex function, the method we propose in this work also applies to semi-convex functions (see $\S 2$ for notation). Therefore our results are stated in this more general setup.

Semi-convexity - or, better, semi-concavity - properties are well known for solutions of nonlinear partial differential equations such as Hamilton-Jacobi-Bellmann equations of first or second order, see e.g. [16], [15].

Hence, the results of this paper provide upper bounds on the singular sets of solutions to these equations, and somehow complement the singularity propagation results of [6].

Finally, an interesting problem in this research is to provide lower bounds on the singular set of a solution in the neighborhood of a fixed singular point. Bounds of this kind are false for a general semi concave (or even concave) function, see Remark 2.4. However, they will be obtained in a forthcoming paper [3], using additional information derived from the equation.

## 2. Properties of semi-convex functions

We fix a bounded, convex, open set $\Omega \subset \mathbb{R}^{n}$, and we denote by $B_{\rho}(x)$ the open ball in $\mathbb{R}^{n}$ centered at $x$ with radius $\rho$.

For any $S \subset \mathbb{R}^{n}$ we denote by $S^{\perp}$ the plane

$$
\left\{p \in \mathbb{R}^{n}: q \mapsto\langle q, p\rangle \text { is constant on } S\right\}
$$

For any integer $m=0, \ldots, n$ we denote by $\mathscr{H}^{m}$ the Hausdorff $m$-dimensional measure in $\mathbb{R}^{n}$, defined by

$$
\begin{align*}
\mathscr{H}^{m}(B):=\frac{\omega_{m}}{2^{m}} \sup _{\delta>0} \inf \left\{\sum_{i} \operatorname{diam}^{m}\left(B_{i}\right)\right. & : B \subset \bigcup_{i} B_{i}  \tag{2.1}\\
& \left.\operatorname{diam}\left(B_{i}\right)<\delta\right\}
\end{align*}
$$

where $\omega_{m}$ is the Lebesgue measure of the unit ball in $\mathbb{R}^{m}$ if $m \geq 1$ and $\omega_{m}=1$ if $m=0$. In particular, $\mathscr{H}^{0}$ is the so-called counting measure.

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If $u$ is a Lipschitz function in $\Omega$, we set

$$
[u]_{\operatorname{Lip}(\Omega)}:=\sup \left\{\frac{|u(x)-u(y)|}{|y-x|}: x, y \in \Omega, x \neq y\right\}
$$

Definition. We say that $u$ is semi-convex in $\Omega$, and we write $u \in S C(\Omega)$, if we can find a non decreasing upper semicontinuous function $\omega:[0,+\infty[\rightarrow[0,+\infty[$ such that $\omega(0)=0$ and

$$
\begin{gather*}
t u\left(x_{1}\right)+(1-t) u\left(x_{0}\right)-u\left(x_{t}\right) \geq-t(1-t)\left|x_{1}-x_{0}\right| \omega\left(\left|x_{1}-x_{0}\right|\right)  \tag{2.2}\\
\text { for all } x_{0}, x_{1} \in \Omega, t \in[0,1] \text { and } x_{t}:=t x_{1}+(1-t) x_{0}
\end{gather*}
$$

If $u \in S C(\Omega)$, we denote by $\omega_{u, \Omega}$ the least function $\omega$ satisfying (2.2).

For any $x \in \Omega$ and any $u: \Omega \rightarrow \mathbb{R}$, the subdifferential $\partial u(x)$ of $u$ at $x$ is defined by

$$
\partial u(x):=\left\{p \in \mathbb{R}^{n}: \liminf _{y \rightarrow x} \frac{u(y)-u(x)-\langle p, y-x\rangle}{|y-x|} \geq 0\right\} .
$$

The subdifferential is a closed convex set, possibly empty.
If $u$ is a convex function, the above set coincides with the wellknown subdifferential of convex analysis, which captures all the relevant differential properties of convex functions. In particular, the subdifferential of a convex function is non-empty at every point (see for instance [8]). In the following proposition we list analogous properties of subdifferentials of semi-convex functions (see also [4] and [6]). We give a fairly detailed proof for the reader's convenience.
Proposition 2.1. Let $u \in S C(\Omega)$. Then, $u$ is locally Lipschitz continuous in $\Omega$, the sets $\partial u(x)$ are non-empty, compact, and $p \in$ $\partial u(x)$, if and only if
(2.3) $u(y)-u(x)-\langle p, y-x\rangle \geq-|y-x| \omega_{u, \Omega}(|y-x|) \quad \forall y \in \Omega$.

Finally, the map $x \rightarrow \partial u(x)$ is upper semi-continuous, i.e.,

$$
\begin{equation*}
x_{h} \rightarrow x, p_{h} \rightarrow p, p_{h} \in \partial u\left(x_{h}\right) \quad \Longrightarrow \quad p \in \partial u(x) . \tag{2.4}
\end{equation*}
$$

Proof. Let $x_{0}, x_{1}, x_{2}, x_{3}$ be an ordered set of points lying on the same line contained in $\Omega$. By using (2.2), it is not difficult to see that

$$
\begin{equation*}
\frac{u\left(x_{3}\right)-u\left(x_{1}\right)}{\left|x_{3}-x_{1}\right|}-\frac{u\left(x_{2}\right)-u\left(x_{1}\right)}{\left|x_{2}-x_{1}\right|} \geq-\omega_{u, \Omega}\left(\left|x_{3}-x_{1}\right|\right) \tag{2.5}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\frac{u\left(x_{2}\right)-u\left(x_{1}\right)}{\left|x_{2}-x_{1}\right|}-\frac{u\left(x_{1}\right)-u\left(x_{0}\right)}{\left|x_{1}-x_{0}\right|} \geq-\omega_{u, \Omega}\left(\left|x_{2}-x_{0}\right|\right) \tag{2.6}
\end{equation*}
$$

Hence

$$
\begin{aligned}
-\omega_{u, \Omega}\left(\left|x_{2}-x_{0}\right|\right)+ & \frac{u\left(x_{1}\right)-u\left(x_{0}\right)}{\left|x_{1}-x_{0}\right|} \leq \frac{u\left(x_{2}\right)-u\left(x_{1}\right)}{\left|x_{2}-x_{1}\right|} \leq \\
& \leq \frac{u\left(x_{3}\right)-u\left(x_{1}\right)}{\left|x_{3}-x_{1}\right|}+\omega_{u, \Omega}\left(\left|x_{3}-x_{1}\right|\right)
\end{aligned}
$$

This shows that $u$ is locally Lipschitz continuous on lines. Moreover, if $x_{1}$ and $x_{2}$ belong to $\Omega^{\prime} \subset \subset \Omega$, the above provides a uniform estimate of the Lipschitz constant, and therefore shows that $u$ is a Lipschitz function in $\Omega^{\prime}$.

Since $u$ is locally Lipschitz continuous, $\partial u(x)$ is compact.
Any vector $p \in \mathbb{R}^{n}$ satisfying (2.3) trivially belongs to $\partial u(x)$. Conversely, let $p \in \partial u(x)$, and let $x_{1}=x, x_{3}=y, x_{2}=x_{1}+t(y-x)$ in (2.5) with $0<t \leq 1$ :

$$
\frac{u(y)-u(x)}{|y-x|} \geq \frac{u(x+t(y-x))-u(x)}{t|y-x|}-\omega_{u, \Omega}(|y-x|)
$$

By letting $t \rightarrow 0^{+}$we obtain that $p$ fulfils (2.3).
By using (2.2), (2.5) and (2.6) it can be seen that the function

$$
v(y)=\lim _{t \rightarrow 0^{+}} \frac{u(x+t y)-u(x)}{t}
$$

is well defined, and convex. Therefore $\partial u(x)$ is not empty because it coincides, by (2.3), with $\partial v(0)$.

Finally, the upper semicontinuity of $x \rightarrow \partial u(x)$ is a straightforward consequence of (2.3).

In this paper we are interested in the properties of the singular sets of semi-convex functions.

Definition. For any integer $k \in[0, n]$ we define

$$
\Sigma^{k}(u):=\{x \in \Omega: \operatorname{dim}(\partial u(x)) \geq k\}
$$

and for any $\alpha>0$ we denote by $\Sigma_{\alpha}^{k}(u)$ the set of points $x \in \Sigma^{k}(u)$ such that $\partial u(x)$ contains some $k$-dimensional ball $B_{\alpha}^{k}$ of diameter $2 \alpha$, i.e.,
(2.7) $\Sigma_{\alpha}^{k}(u):=\left\{x \in \Sigma^{k}(u): \exists B_{\alpha}^{k} \subset \partial u(x)\right.$ with $\left.\operatorname{diam}\left(B_{\alpha}^{k}\right)=2 \alpha\right\}$.

We define now the contingent cone $\mathrm{T}(S, x)$ to a set $S \subset \mathbb{R}^{n}$ at a point $x$ (see [4], [8], and [11], 3.1.21).

Definition. Let $x \in S$. We define

$$
\begin{aligned}
& \mathrm{T}(S, x):=\left\{r \theta: r \geq 0, \theta=\lim _{h \rightarrow+\infty} \frac{x_{h}-x}{\left|x_{h}-x\right|}\right. \\
&\text { with } \left.x_{h} \in S \backslash\{x\}, x_{h} \rightarrow x\right\} .
\end{aligned}
$$

We denote by $\operatorname{Tan}(S, x)$ the vector space generated by $\mathrm{T}(S, x)$.
In the following lemma we investigate the properties of $\Sigma_{\alpha}^{k}(u)$.
Proposition 2.2. For any $u \in S C(\Omega)$, the set $\Sigma_{\alpha}^{k}(u)$ is closed in $\Omega$ and

$$
\begin{equation*}
\operatorname{Tan}\left(\Sigma_{\alpha}^{k}(u), x\right) \subset[\partial u(x)]^{\perp} \tag{2.8}
\end{equation*}
$$

for any $x \in \Sigma_{\alpha}^{k}(u) \backslash \Sigma^{k+1}(u)$. In particular, the dimension of $\operatorname{Tan}\left(\Sigma_{\alpha}^{k}(u), x\right)$ is not greater than $(n-k)$ for any $x \in \Sigma_{\alpha}^{k}(u) \backslash$ $\Sigma^{k+1}(u)$.

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Proof. Let us prove that $\Sigma_{\alpha}^{k}(u)$ is closed. Let $\left\{x_{i}\right\} \subset \Sigma_{\alpha}^{k}(u)$ be converging to $x \in \Omega$, and let $B_{\alpha}^{k}\left(p_{i}\right) \subset \partial u\left(x_{i}\right)$ be $k$-dimensional balls centered at $p_{i}$ with radius $\alpha$. Possibly passing to subsequences, we can assume with no loss of generality that there is a $k$-dimensional ball $B_{\alpha}^{k}$ with radius $\alpha$ such that each point $p \in B_{\alpha}^{k}$ can be approximated by points in $B_{\alpha}^{k}\left(p_{i}\right)$. By the upper semicontinuity of the differential (see (2.4)) we get $B_{\alpha}^{k} \subset \partial u(x)$, hence $x \in \Sigma_{\alpha}^{k}(u)$.

In order to show (2.8), we only need to prove that the map $p \rightarrow\langle\eta, p\rangle$ is constant on $\partial u(x)$ for any $\eta \in \mathrm{T}\left(\Sigma_{\alpha}^{k}(u), x\right)$ with $|\eta|=1$. Let $\left\{x_{h}\right\} \subset \Sigma_{\alpha}^{k}(u) \backslash\{x\}$ be a sequence converging to $x$ such that

$$
\lim _{h \rightarrow+\infty} \frac{x_{h}-x}{\left|x_{h}-x\right|}=\eta
$$

Possibly extracting a subsequence, we can assume with no loss of generality that there is a $k$-dimensional ball $B_{\alpha}^{k}$ with radius $\alpha$ such that each $p \in B_{\alpha}^{k}$ can be approximated by vectors in $\partial u\left(x_{h}\right)$. By (2.4), $B_{\alpha}^{k} \subset \partial u(x)$. Since $\partial u(x)$ is a $k$-dimensional set, we only need to know that $p \mapsto\langle\eta, p\rangle$ is constant on $B_{\alpha}^{k}$. Let $p, p^{\prime} \in B_{\alpha}^{k}$, and let $p_{h} \in \partial u\left(x_{h}\right)$ be converging to $p^{\prime}$; by adding the inequalities

$$
\begin{aligned}
\frac{u\left(x_{h}\right)-u(x)-\left\langle p, x_{h}-x\right\rangle}{\left|x_{h}-x\right|} & \geq-\omega_{u, \Omega}\left(\left|x_{h}-x\right|\right) \\
\frac{u(x)-u\left(x_{h}\right)-\left\langle p_{h}, x-x_{h}\right\rangle}{\left|x_{h}-x\right|} & \geq-\omega_{u, \Omega}\left(\left|x_{h}-x\right|\right)
\end{aligned}
$$

and passing to the limit as $h \rightarrow+\infty$, we get

$$
\left\langle\eta, p^{\prime}\right\rangle \leq\langle\eta, p\rangle
$$

Since $p$ and $p^{\prime}$ are arbitrary, (2.8) follows.
Remark 2.3. Proposition 2.2 yields $\operatorname{Tan}\left(\Sigma_{\alpha}^{n}(u), x\right)=\{0\}$ for any $x \in \Sigma_{\alpha}^{n}(u)$. Hence, $\Sigma_{\alpha}^{n}(u)$ is a discrete set in $\Omega$ and $\Sigma^{n}(u)$ is at most countable.

Remark 2.4. One may wonder whether the inclusion in (2.8) is indeed an equality. This fact could be regarded as a "singularity

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propagation" phenomenon. Now, Theorem 3.1 below shows that the set of points $S \subset \Sigma_{\alpha}^{k}(u)$ at which the inclusion is strict is countably $\mathscr{H}^{n-k-1}$-rectifiable, hence $\sigma$-finite with respect to $\mathscr{H}^{n-k-1}$. Indeed, since $\operatorname{Tan}(S, x) \subset \operatorname{Tan}\left(\Sigma_{\alpha}^{k}(u), x\right)$, by the definition of $S$ it follows that

$$
\operatorname{dim}(\operatorname{Tan}(S, x)) \leq n-k-1
$$

for any $x \in S$. However, the following example shows that equality (2.8) may fail at some point. Let $n=2, k=1$, and let $u(x, y):=$ $\sqrt{x^{2}+y^{4}}$. It is easy to check that $u$ is continuously differentiable in $\mathbb{R}^{2} \backslash\{0\}$, and convex in $\mathbb{R}^{2}$. Moreover, $\partial u(0)=[-1,1] \times\{0\}$, so that $\operatorname{dim}[\partial u(0)]^{\perp}=1$. On the other hand, $\mathrm{T}\left(\Sigma^{1}(u)\right)=\emptyset$. Based on the above, it is not hard to construct an example of function $u: \mathbb{R}^{2} \rightarrow[0,+\infty[$ such that the exceptional set $S$ is countable.

## 3. A rectifiability criterion

Let us first give a definition.
Definition. We say that $S \subset \mathbb{R}^{p}$ is countably $\mathscr{H}^{m}$-rectifiable if there is a countable family of $C^{1}$ hypersurfaces $\Gamma_{h} \subset \mathbb{R}^{p}$ of dimension $m$ such that

$$
\begin{equation*}
\mathscr{H}^{m}\left(S \backslash \bigcup_{h=1}^{\infty} \Gamma_{h}\right)=0 \tag{3.1}
\end{equation*}
$$

If $D \subset \mathbb{R}^{m}$ and $f: D \rightarrow \mathbb{R}^{p}$ is a Lipschitz function, then a Lusin-type argument shows that $f(D)$ is countably $\mathscr{H}^{m}$-rectifiable (see [19], Lemma 11.1).

We can now state a sufficient condition for rectifiability.
Theorem 3.1. Let $S \subset \mathbb{R}^{n}$, and let us assume that $\operatorname{Tan}(S, x)$ has dimension not greater than $m$ for any $x \in S$. Then, $S$ is countably $\mathscr{H}^{m}$-rectifiable.
Proof. Let us denote by $\varphi(x)$ the function $x /|x|$, defined for all $x \in$ $\mathbb{R}^{n} \backslash\{0\}$. Then, the following two properties are satisfied for any $x \in S$ and any $\epsilon>0$ :

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(i) there exists $r>0$ such that

$$
\begin{equation*}
\forall y \in S \cap B_{r}(x) \backslash\{x\}, \exists v \in \mathrm{~T}(S, x) \text { s.t. }|\varphi(y-x)-v|<\epsilon ; \tag{3.2}
\end{equation*}
$$

(ii) for any $r>0$ there exists $\rho<r / 2$ such that
$\forall v \in \mathrm{~T}(S, x), \exists y \in S \cap B_{r / 2}(x) \backslash B_{\rho}(x)$ s.t. $|\varphi(y-x)-v|<\epsilon$.
Both these properties can be proved arguing by contradiction.
Let us fix $\epsilon<1 / 7$, and for $0<\rho<r / 2$ define

$$
S_{r, \rho}:=\{x \in S:(3.2) \text { and (3.3) hold }\}
$$

We claim that $S_{r, \rho}$ is locally contained in the graph of a Lipschitz function. More precisely, let $x \in S_{r, \rho}$, let $M$ be the set $\operatorname{Tan}(S, x)$ and let us denote by $\pi: \mathbb{R}^{n} \rightarrow M$ the orthogonal projection on $M$. We will show that there is a set $D \subset M$ such that $\pi: S_{r, \rho} \cap B_{\epsilon \rho}(x) \rightarrow D$ is one to one and $f=\pi^{-1}$ is Lipschitz continuous.

Possibly replacing $S_{r, \rho}$ by $S_{r, \rho}-x$, it is not restrictive to assume that $x=0$. Let $y, z \in S_{r, \rho} \cap B_{\epsilon \rho}(0)$ with $y \neq z$. Since $|y-z|<$ $2 \epsilon \rho<r / 2$, by (3.2) we get

$$
\begin{equation*}
\exists v \in \mathrm{~T}(S, y) \text { such that }|\varphi(y-z)-v|<\epsilon . \tag{3.4}
\end{equation*}
$$

Similarly, (3.3) yields

$$
\begin{equation*}
\exists \bar{z} \in S \cap B_{r / 2}(y) \backslash B_{\rho}(y) \text { such that }|\varphi(y-\bar{z})-v|<\epsilon . \tag{3.5}
\end{equation*}
$$

By using the inequality $|\nabla \varphi(x)(y)| \leq 2|y| /|x|$, and

$$
|\bar{z}-t y| \geq|\bar{z}-y|-(1-t)|y| \geq \rho-\epsilon \rho \geq \rho / 2 \quad \forall t \in[0,1],
$$

we have

$$
\begin{equation*}
|\varphi(\bar{z}-y)-\varphi(\bar{z})| \leq \int_{0}^{1}|\nabla \varphi(\bar{z}-t y)||y| d t \leq \frac{2|y|}{\rho / 2} \leq 4 \epsilon \tag{3.6}
\end{equation*}
$$

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Moreover, since $\bar{z} \in B_{r / 2}(y)$, we get by (3.2) $w \in \mathrm{~T}(S, 0)$ such that

$$
\begin{equation*}
|\varphi(\bar{z})-w|<\epsilon . \tag{3.7}
\end{equation*}
$$

Putting together (3.3), (3.4), (3.5) and (3.6) we obtain

$$
\begin{align*}
|\varphi(z-y)-w| \leq \mid \varphi & (z-y)-v|+|v-\varphi(\bar{z}-y)|+  \tag{3.8}\\
& +|\varphi(\bar{z}-y)-\varphi(\bar{z})|+|\varphi(\bar{z})-w| \leq 7 \epsilon
\end{align*}
$$

By (3.8) we infer

$$
|\varphi(z-y)-\pi(\varphi(z-y))| \leq|\varphi(z-y)-w| \leq 7 \epsilon<1
$$

This shows that $\pi(z-y) \neq 0$ if $z \neq y$, hence $\pi$ is one to one in $S_{r, \rho} \cap B_{\epsilon \rho}(0)$. Moreover,

$$
|\pi(\varphi(z-y))| \geq \sqrt{1-(7 \epsilon)^{2}}
$$

and

$$
\begin{equation*}
|\pi(z)-\pi(y)| \geq \sqrt{1-(7 \epsilon)^{2}}|y-z| \tag{3.9}
\end{equation*}
$$

Let $D=\pi\left(S_{r, \rho} \cap B_{\epsilon \rho}(0)\right)$, and let $f: D \rightarrow \mathbb{R}^{n}$ be the inverse function of $\pi$. By (3.9), $f$ is a Lipschitz function, and $f(D)=S_{r, \rho} \cap B_{\epsilon \rho}(0)$.

This shows that $S_{r, \rho}$ is countably $\mathscr{H}^{m}$-rectifiable. Since any point $x \in S$ belongs to $S_{1 / n, 1 / p}$ for sufficiently large natural numbers $n, p$ with $p>2 n$, also $S$ is countably $\mathscr{H}^{m}$-rectifiable.

## 4. Estimates on singularities and rectifiability

Let $u$ be a semi-convex function, and let us denote by $\Gamma(u)$ the graph of the subdifferential, i.e.

$$
\Gamma(u)=\left\{(x, p) \in \mathbb{R}^{n} \times \mathbb{R}^{n}: p \in \partial u(x)\right\}
$$

In the following we apply the rectifiability criterion of $\S 3$ to the problem described in the introduction.

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Theorem 4.1. Let $u: \Omega \rightarrow \mathbb{R}$ be semi-convex and Lipschitz continuous. Then, for any integer $k \in[0, n]$, the set

$$
\Sigma^{k}(u):=\{x \in \Omega: \operatorname{dim}(\partial u(x)) \geq k\}
$$

is countably $\mathscr{H}^{n-k}$-rectifiable. Moreover, if $\omega_{u, \Omega}(t) \leq C t$ for some $C \geq 0$, then $\Gamma(u)$ is countably $\mathscr{H}^{n}$-rectifiable in $\mathbb{R}^{n} \times \mathbb{R}^{n}$ and

$$
\begin{equation*}
\mathscr{H}^{n}(\Gamma(u)) \leq C(n)\left(1+(C+1)^{2}\right)^{n / 2}[u]_{\operatorname{Lip}(\Omega)}^{n} \tag{4.1}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\int_{\Sigma^{k}(u)} \mathscr{H}^{k}(\partial u(x)) d \mathscr{H}^{n-k}(x) \leq \mathscr{H}^{n}(\Gamma(u)) \tag{4.2}
\end{equation*}
$$

Proof. By Theorem 3.1 and Proposition 2.2, the sets $\Sigma_{\alpha}^{k}(u)$ are countably $\mathscr{H}^{n-k}$-rectifiable. Since

$$
\Sigma^{k}(u)=\bigcup_{p \in \mathbb{N}} \Sigma_{1 / p}^{k}(u)
$$

also $\Sigma^{k}(u)$ is countably $\mathscr{H}^{n-k}$-rectifiable.
Let us assume now that $\omega_{u, \Omega}(t) \leq C t$ for some $C \geq 0$. Given any $x_{0} \in \Omega$ we define

$$
v(x)=u(x)+\frac{C}{2}\left|x-x_{0}\right|^{2}
$$

It is not hard to see that $v$ is convex and

$$
\begin{equation*}
\langle p-q, x-y\rangle \geq|x-y|^{2} \quad \forall x, y \in \Omega, p \in \partial u(x), q \in \partial u(y) \tag{4.3}
\end{equation*}
$$

In addition, we have

$$
\Gamma(u)=\Phi_{C}(\Gamma(v))
$$

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where $\Phi_{C}: \mathbb{R}^{2 n} \rightarrow \mathbb{R}^{2 n}$ is defined by

$$
\Phi_{C}(x, p):=\left(x, p-(C+1)\left(x-x_{0}\right)\right)
$$

Since the Lipschitz constant of $\Phi_{C}$ equals $\sqrt{1+(C+1)^{2}}$, by wellknown properties of Hausdorff measures (see for instance [11], paragraph 2.10.11) we infer the inequality

$$
\begin{equation*}
\mathscr{H}^{n}(\Gamma(u)) \leq\left(1+(C+1)^{2}\right)^{n / 2} \mathscr{H}^{n}(\Gamma(v)) \tag{4.4}
\end{equation*}
$$

Let $D \subset \mathbb{R}^{n}$ be the projection of $\Gamma(v)$ on the second factor, (a similar idea is also used in [13]) and let $\varphi: D \rightarrow \mathbb{R}^{n}$ be the function which assigns to each $p \in D$ the unique (by (4.3)) $x \in \Omega$ such that $p \in$ $\partial v(x)$. By (4.3) we get

$$
|\varphi(p)-\varphi(q)|^{2} l e q\langle p-q, \varphi(p)-\varphi(q)\rangle \leq|p-q||\varphi(p)-\varphi(q)|
$$

so that $\varphi$ is a contraction. Since $\Gamma(v)$ coincides with the graph of $\varphi$, by the area formula for Lipschitz functions (see [11], 3.2.1) we obtain

$$
\mathscr{H}^{n}(\Gamma(v))=\int_{D} \psi(\nabla \varphi(p)) d p
$$

where

$$
\psi(A)=\sqrt{1+\sum_{B \subset A} \operatorname{det}^{2}(B)}
$$

for any $n \times n$ matrix $A$. In particular,

$$
\begin{equation*}
\mathscr{H}^{n}(\Gamma(v)) \leq C(n) \mathscr{H}^{n}(D) \leq \omega_{n} C(n)[v]_{\operatorname{Lip}(\Omega)}^{n} \tag{4.5}
\end{equation*}
$$

Hence, (4.1) follows by (4.4) and (4.5). Finally, (4.2) follows by general properties of products of Hausdorff measures ([11], 2.10,.27) and of Lipschitz mappings between rectifiable sets. In fact, denoting

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by $\pi: \mathbb{R}^{2 n} \rightarrow \mathbb{R}^{n}$ the projection on the first factor, by [11], 3.2.22 we infer

$$
\mathscr{H}^{n}(\Gamma(v)) \geq \int_{\Omega} \mathscr{H}^{k}\left(\pi^{-1}(x) \cap \Gamma(u)\right) d \mathscr{H}^{n-k}(x)
$$

Since $\pi^{-1}(x) \cap \Gamma(u)=\{(x, p): p \in \partial u(x)\},(4.6)$ is equivalent to (4.2).

Remark 4.2. Let $M \subset \mathbb{R}^{p}$ be a countably $\mathscr{H}^{m}$-rectifiable set, and let $\pi: M \rightarrow \mathbb{R}^{n}$ be a Lipschitz function. In [11], 3.2.31 Federer shows that the set

$$
\left\{z \in \mathbb{R}^{n}: \mathscr{H}^{k}\left(\pi^{-1}(z)\right)>0\right\}
$$

is countably $\mathscr{H}^{m-k}$-rectifiable. Hence, the rectifiability of $\Sigma^{k}(u)$ follows by the rectifiability of $\Gamma(u)$ by applying Federer's proposition with $M=\Gamma(u), p=2 n, m=n$ and $\pi$ equal to the projection on the first variable.

A similar approach is followed by Baldo and Ossanna in [5]. However, this method does not apply to a general semi-convex function, like a function with Hölder continuous gradient. Therefore, using Theorem 3.1 to derive the rectifiability of $\Sigma^{k}(u)$ is more powerful. Moreover, we believe it is more direct as well, because it minimizes the application of sophisticated techniques from Geometric Measure Theory.

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